

# **Tension Controller**

LE7-40GU INSTRUCTION MANUAL (Communication)

### **SAFETY PRECAUTIONS**

(Read these precautions before use.)

Before using this product, please read this manual and the relevant manuals introduced in this manual carefully and pay full attention to safety in order to handle the product correctly.

This manual classifies the safety precautions into two categories: [ WARNING] and [ CAUTION].

# **MARNING**

Indicates that incorrect handling may cause hazardous conditions, resulting in death or severe injury.

# **A** CAUTION

Indicates that incorrect handling may cause hazardous conditions, resulting in minor or moderate injury or property damage.

Depending on the circumstances, procedures indicated by [ CAUTION] may also cause severe injury. It is important to follow all precautions for personal safety.

Store this manual in a safe place so that it can be read whenever necessary. Always forward it to the end user.

### [DESIGN PRECAUTIONS]

# **MARNING**

- Make sure to set up the following safety circuits outside the tension controller to ensure safe system operation even during external power supply problems or tension controller failure. Otherwise, malfunctions may cause serious accidents.
  - Note that when an error occurs in a relay or transistor of an output circuit, the output might stay on or off. For output signals that may lead to serious accidents, external circuits and mechanisms should be designed to ensure safe machinery operation in such a case.
- Most importantly, set up the following: an emergency stop circuit, a protection circuit, an interlock circuit for opposite movements (such as normal vs. reverse rotation), and an interlock circuit (to prevent damage to the equipment at the upper and lower torque limits and upper and lower tension limits).
- In an output circuit, when a load current exceeding the current rating or an overcurrent caused by a load short-circuit flows for a long time, it may cause smoke and fire. To prevent this, configure an external safety circuit, such as a fuse.
- For the operating status of each station after a communication failure of the network, refer to relevant manuals for the network. Incorrect output or malfunction may result in an accident.

### [DESIGN PRECAUTIONS]

## **CAUTION**

 If a power failure or an abnormal voltage drop occurs, the tension controller stops, and output is turned off.

### [INSTALLATION PRECAUTIONS]

# **WARNING**

- Make sure to cut off all phases of the power supply externally before attempting installation or wiring work. Failure to do so may cause electric shock or damage to the product.
- Use the product within the generic environment specifications described in LE7-40GU APPLICATION MANUAL (SH-081822ENG). Never use the product in areas with excessive dust, oily smoke, conductive dusts, corrosive gas (salt air, Cl<sub>2</sub>, H<sub>2</sub>S, SO<sub>2</sub> or NO<sub>2</sub>), flammable gas, vibration or impacts, or expose it to high temperature, condensation, or rain and wind. If the product is used in such conditions, electric shock, fire, malfunctions, deterioration or damage may occur.

### [INSTALLATION PRECAUTIONS]

# **ACAUTION**

- Do not touch the conductive parts of the product directly. Doing so may cause device failures or malfunctions.
- Always wear an anti-static wristband and discharge static electricity from the body before handling the
  extension option. Failure to do so may cause the extension option to fail or malfunction.
- When drilling screw holes or wiring, make sure that cutting and wiring debris do not enter the ventilation slits of the tension controller. Failure to do so may cause fire, equipment failures or malfunctions.
- Install the product on a flat surface. If the mounting surface is rough, undue force will be applied to the PC board, thereby causing nonconformities.
- Install the product securely using mounting screws or fixtures.
- Connect the extension options securely to their designated connectors. Loose connections may cause malfunctions.
- Make sure to affix the extension option with tapping screws. Tightening torque should follow the specifications in the manual. If the screws are tightened outside of the specified torque range, poor connections may cause malfunctions.
- Work carefully when using a screwdriver such as installation of the product. Failure to do so may cause damage to the product or accidents.
- Connect the input/output cables and power cable securely to their designated connectors. Loose connections may cause malfunctions.
- Turn off the power to the tension controller before attaching or detaching the optional devices. Failure to do so may cause equipment failures or malfunctions.

### [WIRING PRECAUTIONS]

# **WARNING**

- Make sure to cut off all phases of the power supply externally before attempting installation or wiring work. Failure to do so may cause electric shock or damage to the product.
- Make sure to properly wire to the terminal block (Spring clamp type) in accordance with the following precautions. Failure to do so may cause electric shock, equipment failures, a short-circuit, wire breakage, malfunctions, or damage to the product.
  - The disposal size of the cable end should follow the dimensions described in the manual.
  - Twist the ends of stranded wires and make sure that there are no loose wires.
  - Do not solder-plate the electric wire ends.
  - Do not connect more than the specified number of wires or electric wires of unspecified size.
  - Affix the electric wires so that neither the terminal block nor the connected parts are directly stressed.

### [WIRING PRECAUTIONS]

# **ACAUTION**

- Perform class D grounding (grounding resistance: 100  $\Omega$  or less) of the grounding terminal on the tension controller with a wire 0.2 to 1.5 mm<sup>2</sup>. Do not use common grounding with heavy electrical systems.
- Connect the power supply wiring to the dedicated terminals described in this manual. If an AC power supply is connected to a DC input/output terminal or DC power supply terminal, the tension controller will burn out.
- Do not wire vacant terminals externally. Doing so may damage the product.
- Install module so that excessive force will not be applied to terminal blocks, power wire, or communication cables. Failure to do so may result in wire damage/breakage or tension controller failure.
- Make sure to observe the following precautions in order to prevent any damage to the machinery or accidents due to malfunction of the tension controller due to the effects of noise.
  - Do not bundle the power line and communication cables together with or lay them close to the main circuit, high-voltage line, load line or power line. As a guideline, lay the power line, control line and communication cables at least 100 mm away from the main circuit, high-voltage line, load line or power line.
  - Ground the shield of the shielded wire or shielded cable at one point on the tension controller. However, do not use common grounding with heavy electrical systems.
  - Ground the shield of the analog input/output cable at one point on the signal receiving side. However, do not use common grounding with heavy electrical systems.

## [STARTUP AND MAINTENANCE PRECAUTIONS]

# **MARNING**

- Do not touch any terminal while the tension controller's power is on. Doing so may cause electric shock or malfunctions.
- Before cleaning, cut off all phases of the power supply externally. Failure to do so in the power ON status may cause electric shock.

### [STARTUP AND MAINTENANCE PRECAUTIONS]

### **!** CAUTION

- Do not disassemble or modify the product. Doing so may cause fire, equipment failures, or malfunctions.
  - \*For repair, contact your local Mitsubishi Electric representative.
- Turn off the power to the tension controller before connecting or disconnecting any extension cable.
   Failure to do so may cause equipment failures or malfunctions.
- Turn off the power to the tension controller before attaching or detaching the optional devices. Failure to do so may cause equipment failures, or malfunctions.

### [DISPOSAL PRECAUTIONS]

# **ACAUTION**

 Please contact a certified electronic waste disposal company for the environmentally safe recycling and disposal of your device.

### [TRANSPORTATION PRECAUTIONS]

### **!** CAUTION

- The tension controller is a precision instrument. During transportation, avoid impacts larger than those specified in the general specifications described in LE7-40GU APPLICATION MANUAL (SH-081822ENG) by using dedicated packaging boxes and shock-absorbing palettes. Failure to do so may cause failures in the tension controller. After transportation, verify operation of the tension controller and check for damage of the mounting part, etc.
- When fumigants that contain halogen materials such as fluorine, chlorine, bromine, and iodine are used for disinfecting and protecting wooden packaging from insects, they cause malfunction when entering our products. Please take necessary precautions to ensure that remaining materials from fumigant do not enter our products, or treat packaging with methods other than fumigation (heat method). Additionally, disinfect and protect wood from insects before packing products.

# INTRODUCTION

Thank you very much for purchasing the tension controller.

Before using, read this document, and thoroughly understand the functions and performance of the tension controller to use it correctly.

### Regarding use of this product

- This product has been manufactured as a general-purpose part for general industries, and has not been designed or manufactured to be incorporated in a device or system used in purposes related to human life.
- Before using the product for special purposes such as nuclear power, electric power, aerospace, medicine or passenger movement vehicles, consult Mitsubishi Electric.
- This product has been manufactured under strict quality control. However when installing the product where major accidents or losses could occur if the product fails, install appropriate backup or failsafe functions in the system.

### Note

- If in doubt at any stage during the installation of the product, always consult a professional electrical engineer who is qualified and trained in the local and national standards. If in doubt about the operation or use, please consult the nearest Mitsubishi Electric representative.
- Since the examples indicated by this manual, technical bulletin, catalog, etc. are used as a reference, please use it after confirming the function and safety of the equipment and system. Mitsubishi Electric will accept no responsibility for actual use of the product based on these illustrative examples.
- · This manual content, specification etc. may be changed, without a notice, for improvement.
- The information in this manual has been carefully checked and is believed to be accurate; however, if you notice a doubtful point, an error, etc., please contact the nearest Mitsubishi Electric representative. When doing so, please provide the manual number given at the end of this manual.

# **CONTENTS**

SAF	ETY PRECAUTIONS	
INTF	RODUCTION	5
	EVANT MANUALS	
TER	MS	
СН	APTER 1 OUTLINE OF COMMUNICATION FUNCTION	11
1.1	Communication with a Personal Computer (GT Designer 3 and Data Transfer Tool)	
•••	USB connection.	
	Ethernet connection.	
1.2	Ethernet Communication	
	CC-Link IE Field Network Basic communication	12
	SLMP communication	12
	MODBUS/TCP (slave)	12
1.3	RS-485 Communication	13
	N:N Network	13
	MODBUS/RTU, ASCII (slave)	13
1.4	CC-Link Communication	13
СН	APTER 2 COMMUNICATION WITH A PERSONAL COMPUTER (GT D	ESIGNER3
O11/	DATA TRANSFER TOOL)	14
2.1	USB Connection	14
	System configuration	14
	Communication specifications	14
	How to install the USB driver	15
	Precautions for using a USB cable	15
2.2	Ethernet Connection	
	System configuration	
	Communication specifications	16
СН	APTER 3 CC-LINK IE FIELD NETWORK BASIC COMMUNICATION	17
3.1	System Configuration	17
	When connecting to one master station	17
	When connecting one master station and multiple LE7-40GU (slave stations)	17
3.2	Communication Setting	18
	Communication parameter settings	18
	Link data configuration	
	Remote input/output	
	Remote register	
	Continuous setting/continuous monitoring	
	Access by request command	
	Request code	
3.3	Reference Program	
CH	APTER 4 SLMP COMMUNICATION	40
4.1	System Configuration	
4.2	Communication Setting	
	Communication parameter settings	
	Link data configuration	43

	Station Number command	
	Continuous setting/continuous monitoring	
	Access by request command	
	Request code	
4.3	Reference Program	54
СНА	APTER 5 MODBUS/TCP (SLAVE)	61
5.1	System Configuration	
5.2	Communication Setting	
	Communication parameter settings	
	Bit device	
	Word device	
	Function code	67
	Continuous setting/continuous monitoring	
	Access by request command	68
	Request code	
5.3	Reference Program	78
CHA	APTER 6 N:N NETWORK	87
6.1	System Configuration	87
6.2	Wiring	
	Selection of cable	
	Terminating resistor settings	
	Connection diagram	
	Grounding	
6.3	Communication Setting	90
	Communication specifications	
	Communication parameter settings	
	Link data configuration	
	Station Number command	95
	Continuous setting/continuous monitoring	95
	Access by request command	
	Request code	
6.4	Reference Program	
CHA	APTER 7 MODBUS/RTU, ASCII (SLAVE)	112
7.1	System Configuration	
7.2	Wiring	
	Selection of cable	
	Terminating resistor settings	
	Connection diagram	
	Grounding	
7.3	Communication Setting	
	Communication specifications	
	Frame specifications	
	Communication parameter settings	
	Data exchange between the master station and the slave station	
7.4	Reference Program	
	vo. 2012	
KEV	'ISIONS	

TRADEMARKS
------------

# **RELEVANT MANUALS**

Manual name <manual number=""></manual>	Description
LE7-40GU INSTRUCTION MANUAL <ib-0800569eng></ib-0800569eng>	How to handle and install the tension controller LE7-40GU
LE7-40GU APPLICATION MANUAL <sh-081822eng></sh-081822eng>	How to handle, install and set the tension controller LE7-40GU
LE7-40GU INSTRUCTION MANUAL (Communication) <sh-081834eng> (this manual)</sh-081834eng>	How to wire and set the communication for the tension controller LE7-40GU
LE7-DCA INSTRUCTION MANUAL <ib-0800570></ib-0800570>	How to handle and install the reel diameter calculation option LE7-DCA
LE7-DCA APPLICATION MANUAL <sh-081825eng></sh-081825eng>	How to handle, install and set the reel diameter calculation option LE7-DCA
LE7-CCL INSTRUCTION MANUAL <ib-0800571></ib-0800571>	How to handle and install the network option LE7-CCL
LE7-CCL APPLICATION MANUAL <sh-081828eng></sh-081828eng>	How to handle, install and set the network option LE7-CCL

# **TERMS**

Unless otherwise specified, this manual uses the following terms.

Terms	Description
Option	Generic term for extension options, memory cassette
Extension options	Generic term for reel diameter calculation option, network option
Reel diameter calculation option	Generic term for the reel diameter calculation option LE7-DCA
Network option	Generic term for the network option LE7-CCL
LE7-40GU	Abbreviation for the tension controller LE7-40GU
LE7-DCA	Abbreviation for the reel diameter calculation option LE7-DCA
LE7-CCL	Abbreviation for the network option LE7-CCL
LD-8EEPROM	Abbreviation for LD-8EEPROM type EEPROM cassette

# 1 OUTLINE OF COMMUNICATION FUNCTION

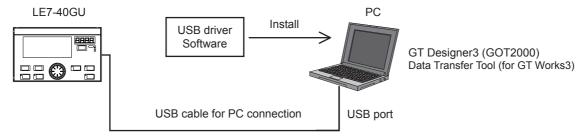
This chapter provides an outline of the communication function.

# 1.1 Communication with a Personal Computer (GT Designer 3 and Data Transfer Tool)

### **USB** connection

LE7-40GU can be connected to a PC via USB.

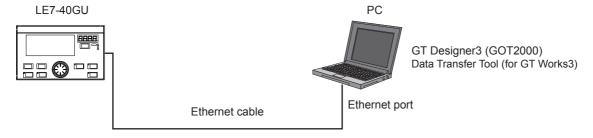
Screen data can be written to LE7-40GU from GT Designer 3 (GOT2000) and Data Transfer Tool (for GT Works 3).



### **Ethernet connection**

LE7-40GU can be connected to a PC via Ethernet (100BASE-TX, 10BASE-T).

Screen data can be written to LE7-40GU from GT Designer 3 (GOT2000) and Data Transfer Tool (for GT Works 3).



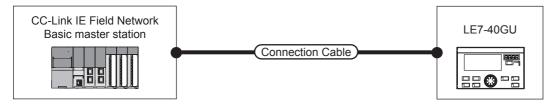
### 1.2 Ethernet Communication

### CC-Link IE Field Network Basic communication

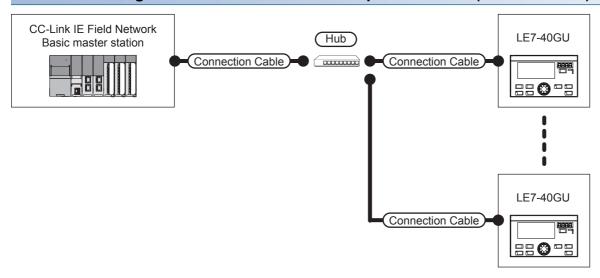
LE7-40GU supports slave functionality for CC-Link IE field network basic communication.

LE7-40GU can communicate with all kinds of CC-Link IE field network basic communication master stations.

### When connecting to one master station



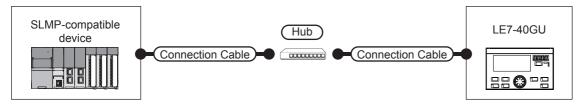
### When connecting one master station and multiple LE7-40GU (slave stations)



### **SLMP** communication

LE7-40GU supports client functionality for SLMP communication.

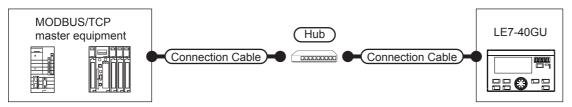
LE7-40GU can communicate with various SLMP-compatible devices, and up to seven LE7-40GU units can be connected to one SLMP-compatible device to carry out data monitoring and parameter writing.



## MODBUS/TCP (slave)

LE7-40GU can be operated as a slave station for MODBUS/TCP communication.

LE7-40GU (as a slave station) can perform data monitoring and parameter writing from up to four master stations.

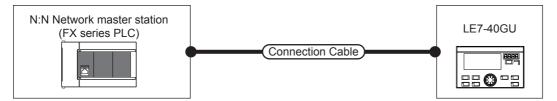


### 1.3 RS-485 Communication

### **N:N Network**

LE7-40GU can be operated as a local station for FX PLC N:N network communication.

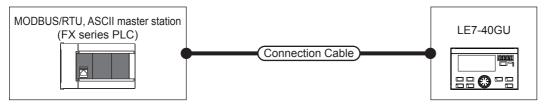
Data monitoring and parameter writing from a master station FX PLC for up to seven local stations (LE7-40GU units) can be carried out.



# MODBUS/RTU, ASCII (slave)

LE7-40GU can be operated as a slave station for MODBUS/RTU and ASCII communication.

Data monitoring and parameter writing from a master station for up to 247 slave stations (LE7-40GU units) can be carried out.



### **Precautions**

RS-485 communication and CC-Link communication cannot be used simultaneously.

# 1.4 CC-Link Communication

LE7-40GU can be operated as a remote device station for CC-Link by connecting the optional LE7-CCL network option.

CCLink Ver. 1.10 and Ver. 2.00 are supported, so extended cyclic transmission can be performed.

For details on CC-Link Communication, refer to the following.

**LILE7-CCL APPLICATION MANUAL** 

### **Precautions**

RS-485 communication and CC-Link communication cannot be used simultaneously.

# 2 COMMUNICATION WITH A PERSONAL COMPUTER (GT DESIGNER3, DATA TRANSFER TOOL)

Data is transferred between the personal computer (GT Designer3, Data Transfer Tool) and LE7-40GU.

For details on data transfer, refer to the following.

<GT Designer3 (GOT2000)>

GT Designer3 (GOT2000) Screen Design Manual

<Data Transfer Tool (for GT Works3)>

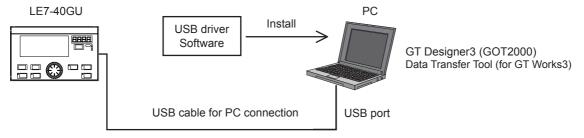
Data Transfer Tool [GOT2000 Series] help

### 2.1 USB Connection

## System configuration

Ensure that one of the following software packages is installed, and that the PC is equipped with a USB port.

- GT Designer3 (GOT2000)
- Data Transfer Tool (for GT Works3)\*1



<sup>\*1</sup> Obtain Data Transfer Tool (for GT Works3) from your local Mitsubishi Electric representative.

### **Communication specifications**

Communication specifications of the USB communication are as follows.

Item	Specifications
Transmission standard	Compliant with USB 2.0 (full speed compatible)
Isolation method	Photocoupler isolation (between communication line and CPU)
Maximum transmission distance	Up to 5 m
Transmission speed	9600/19200/38400/57600/115200 bps
Connector type	USB (Mini-B plug female)
USB cable	MR-J3USBCBL3M [3 m]     GT09-C30USB-5P [3 m] (manufactured by Mitsubishi Electric System & Service Co., Ltd.)

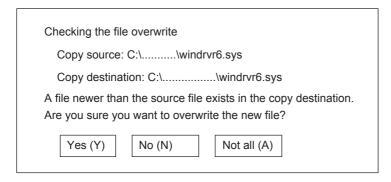
### How to install the USB driver

Follow the procedure below.

- 1. Connect the A type connector of the USB cable to the USB port on the PC side.
- 2. Connect the Mini-B side of the USB cable to the USB interface of the LE7-40GU.
- Switch on the LE7-40GU power supply.
- **4.** The USB driver is installed automatically to the PC only when it is connected for the first time.



When the USB driver of other products is installed, the confirmation message for overwriting the USB driver file (windrvr6.sys) may appear. If a new file already exists, click the [No] button and do not overwrite the file. When the file is overwritten, the USB communication of GT Designer3 and the LE7-40GU may not be properly executed.



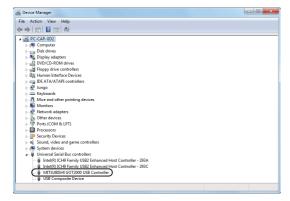
### Precautions for using a USB cable

To transfer the data by connecting the personal computer and the LE7-40GU using a USB cable, do not set the resume function, the suspending function, the power saving function, or the standby mode of the personal computer. For the details of the resume function, the suspending function, the power saving function or the standby mode, refer to the manual of the personal computer or the Help of Windows.

If the USB cable is removed or the LE7-40GU is reset or powered off/on, the communication may not be recovered from an error. In this case, perform either of the following operations.

Checking if the personal computer recognizes the USB.

Check that [MITSUBISHI GOT2000 USB Controller] is displayed in [USB (Universal Serial Bus) Controller] in the device manager.



· Restart the LE7-40GU.

Remove the USB cable from the LE7-40GU and power off the LE7-40GU. After the LE7-40GU is powered off, restart the LE7-40GU and connect a cable to communicate again.

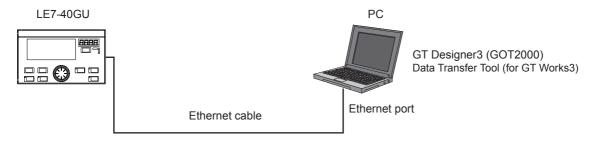
### 2.2 Ethernet Connection

# System configuration

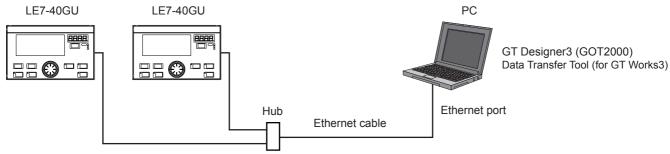
Ensure that one of the following software packages is installed, and that the PC is equipped with an Ethernet port.

- GT Designer3 (GOT2000)
- Data Transfer Tool (for GT Works3)<sup>\*1</sup>

### **Direct connection**



### Connection via hub



<sup>\*1</sup> Obtain Data Transfer Tool (for GT Works3) from your local Mitsubishi Electric representative.

# **Communication specifications**

The communication specifications of the Ethernet communication are as follows.

Item			Specification contents			
Transmission	Data transmission speed		100/10 Mbps			
specifications	Communication mode		Full duplex/half duplex*1			
	Interface		RJ45 connector			
	Transmission method		Baseband			
Maximum segment length (length between hub and node)		ı (length between hub and	100 m			
	Number of cascade	100BASE-TX	Up to 2 stages <sup>*3</sup>			
	connection stages	10BASE-T	Maximum 4 stages <sup>*3</sup>			
Supported protocol			MELSOFT connection			
Number of connections			MELSOFT connection (Up to 8 external devices can access one LE7-40GU simultaneously.)			
Hub <sup>*1</sup>			Hubs with a 100BASE-TX or 10BASE-T*4 port can be used.			
IP address			Initial value: 192.168.3.250			
Cable used*2 In the case of 100BASE-TX connection		ΓX connection	Ethernet standard compatible item cable category 5 or more (STP cable)			
	In the case of 10BASE-T	connection	Ethernet standard compatible item cable category 3 or more (STP cable)			

<sup>\*1</sup> IEEE802.3x flow control is not supported.

<sup>\*2</sup> Straight cable can be used.

<sup>\*3</sup> This is the number of connectable stages when using a repeater hub. Check the manufacturer of the switching hub to be used for the number of connectable stages when using a switching hub.

<sup>\*4</sup> The port must comply with the IEEE802.3 100BASE-TX or IEEE802.3 10BASE-T standard.

# 3 CC-LINK IE FIELD NETWORK BASIC COMMUNICATION

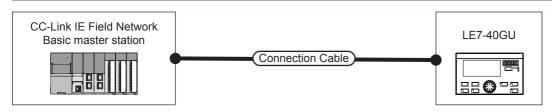
Since LE7-40GU supports the slave function of CC-Link IE Field Network Basic communication which is an open FA network, it can communicate with various CC-Link IE field network Basic master stations.

### **Precautions**

- Since CC-Link IE Field Network Basic uses port No. [61451] as a device detection port, when port No. [61451] is used for another communication function, CC-Link IE Field Network Basic connection cannot be used.
- Since LE7-40GU handles a number of object functions besides the CC-Link IE Field Network Basic connection function, the response performance with respect to access from the master station may deteriorate. In such a case, it is necessary to adjust the link scan time or the timeout time on the master station side. The recommended setting value is 50 ms or more.

# 3.1 System Configuration

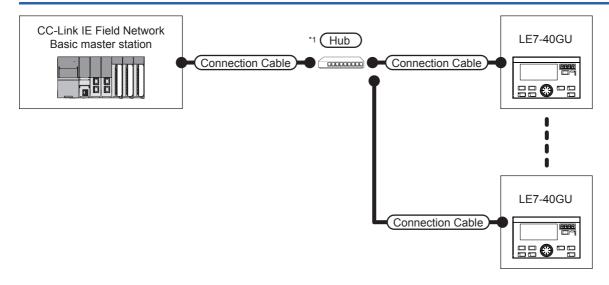
### When connecting to one master station



Connection equipment	Communication form	Connection cable		Tension controller (s station)	Number of connectable	
		Cable type name <sup>*1</sup>	Maximum segment length	Optional equipment	Main unit	devices
CC-Link IE Field Network Basic master station	Ethernet	100BASE-TX Category 5 or more shield twisted pair cable (STP)	100 m	— (Built-in to main unit)	LE7-40GU	One LE7-40GU for one master station

<sup>\*1</sup> For twisted pair cable, please use a cross cable.

# When connecting one master station and multiple LE7-40GU (slave stations)



- \*1 Please use a hub that meets the following conditions.
  - · Complies with IEEE802.3 (100BASE-TX) standard
  - · Automatic MDI/MDI-X function installed
  - · Equipped with auto negotiation function
  - · Switching hub (Layer 2 switch) (Repeater hub cannot be used.)

Connection	Communic	Connection ca	able	External				Number of	
equipment	ation form	Cable type name*4	Maximum segment length*3	device	Cable type Name <sup>*4</sup>	Maximum segment length*3	Optional equipment	Main unit	connectable devices
CC-Link IE Field Network Basic master station	Ethernet*5	100BASE-TX Category 5 or more shield twisted pair cable (STP)	100 m	Hub <sup>*2</sup>	100BASE-TX Category 5 or more shield twisted pair cable (STP)	100 m	— (Built-in to main unit)	LE7-40GU	Maximum 64 units of LE7- 40GU (slave station) for one master station

\*2 Connect CC-Link IE Field Network Basic master station via a hub.

Use cables, connectors and hubs that satisfy the IEEE802.3 100BASE-TX standard.

\*3 This is the length between the hub and the node.

The maximum distance depends on the Ethernet device used.

When using a repeater hub, the number of units that can be connected is as follows.

• 100 BASE-TX: Cascade connection maximum 2 (205 m)

When using a switching hub, the cascade connection between switching hubs has no theoretical limit on the number that can be cascaded.

- \*4 For the twisted pair cable, please use a straight cable.
- \*5 CC-Link IE Field Network Basic communication does not support connection beyond the router.

# 3.2 Communication Setting

### **Communication parameter settings**

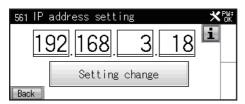
When using CC-Link IE Field Network Basic communication, set the communication parameters with the following procedure.

### **Setting with Data Transfer Tool**

- 1. Obtain the "Screen package data for CC-Link IEF Basic" from your local Mitsubishi Electric representative.
- **2.** Transfer the "Screen package data for CC-Link IEF Basic" to LE7-40GU with Data Transfer Tool (for GT Works3). For more information on data transfer, refer to the following.
- F Page 14 COMMUNICATION WITH A PERSONAL COMPUTER (GT DESIGNER3, DATA TRANSFER TOOL)
- 3. Select "CC-Link IEF Basic" on the "Ethernet communication selection" screen of the LE7-40GU screen.



**4.** If you want to change the IP address of LE7-40GU (default: 192.168.3.18), change it on the "IP address setting" screen of LE7-40GU.



5. Restart LE7-40GU.

### Setting with GT Designer3 (GOT2000)

- 1. Obtain the "Screen package data for CC-Link IEF Basic" from your local Mitsubishi Electric representative.
- **2.** Open the "Screen package data for CC-Link IEF Basic" in GT Designer3 (GOT2000) and change the settings of [Common] [Controller Settings] [CH2] as follows.

For details on the communication settings in GT Designer3 (GOT2000), refer to the following.

GOT2000 Series Connection Manual (Microcomputers, MODBUS/Fieldbus Products, Peripherals)

<Controller Setting>

Setting name	Setting detail
Manufacturer	CLPA
Controller Type	CC-Link IE Field Network Basic
I/F	Ethernet:Multi
Driver	Ethernet(CC-Link IE Field Network Basic)

### <Detail setting>

Property	Value
GOT Net No.	0 (Not used)
GOT Station	0 (Not used)
GOT Communication Port No.	61450 (Fixed)

**3.** Change the settings of [Common] - [GOT Ethernet Setting] - [GOT IP Address Setting] as follows.

For details on the communication settings in GT Designer3 (GOT2000), refer to the following.

GOT2000 Series Connection Manual (Microcomputers, MODBUS/Fieldbus Products, Peripherals)

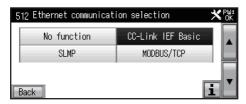
<GOT IP Address Setting>

Setting name	Setting value
GOT IP Address	192.168.3.18 (optional)

**4.** Transfer the "Screen package data for CC-Link IEF Basic" to LE7-40GU with GT Designer3 (GOT2000) For more information on data transfer, refer to the following.

Page 14 COMMUNICATION WITH A PERSONAL COMPUTER (GT DESIGNER3, DATA TRANSFER TOOL)

5. Select "CC-Link IEF Basic" on the "Ethernet communication selection" screen of the LE7-40GU screen.



6. Restart LE7-40GU.

# Link data configuration

LE7-40GU uses "1" for the number of occupied stations because the contents of the allocated link data does not change even if the number of occupied stations of the CC-Link IE Field Network Basic slave station is changed.

\*1 When using other than "1" for the number of occupied stations, all functions except remote input/output and remote register become non-functioning.

### Remote input/output

Each remote input/output has 48 points.

The remaining area becomes non-functioning and cannot be used.

Remote output (Master Station → Slave Station)

Device No.	Signal name	Signal name ON (data value=1)	OFF (data value=0)	
RY00	Run/Stop	Run	Stop	
RY01	Reel change B axis/A axis	B axis control	A axis control	
RY02	Control output OFF/ON	Control output OFF	Control output ON	
RY03	Auto/Manual	Automatic control	Manual control	
RY04	Stall memory ON/OFF	Stall memory ON	Stall memory OFF	
RY05	Gain 1 ON/OFF	Gain 1 ON	Gain 1 OFF	
RY06	Gain 2 ON/OFF	Gain 2 ON	Gain 2 OFF	
RY07	Inching ON/OFF	Inching ON	Inching OFF	
RY08	Cutting torque ON/OFF	Cutting torque ON	Cutting torque OFF	
RY09	Constant tension ON/OFF	Constant tension ON	Constant tension OFF	
RY0A	Predrive ON/OFF	Predrive ON	Predrive OFF	
RY0B	Memory hold ON/OFF	Memory hold ON	Memory hold OFF	
RY0C	Reverse run/Forward run	Reverse run operation	Forward run operation	
RY0D	_	_	_	
RY0E	_	_	_	
RY0F	_	_	_	
RY10	Alarm reset ON/OFF	Alarm reset ON	Alarm reset OFF	
RY11	Reel diameter reset ON/OFF	Reel diameter reset ON	Reel diameter reset OFF	
RY12	Measurement length and remaining length reset ON/OFF	Measurement length and remaining length reset ON	Measurement length and remaining length reset OFF	
RY13	_	_	_	
RY14	_	_	_	
RY15	_	_	_	
RY16	_	_	_	
RY17	_	_	_	
RY18	Zero adjustment execution	Execution	Normal	
RY19	Span adjustment execution	Execution	Normal	
RY1A	Maximum diameter teaching execution	Start maximum diameter teaching execution	Normal	
RY1B	Minimum diameter teaching execution	Start minimum diameter teaching execution	Normal	
RY1C	Control gain tuning execution	Start control gain tuning execution	Normal	
RY1D	Speed teaching execution	Start speed teaching execution	Normal	
RY1E	_	_	_	
RY1F	_	_	_	
RY20	Data copy execution	Start data copy execution	Normal	
RY21	Data initial execution	Start data initial execution	Normal	
RY22	_	_	_	
RY23	_	_	_	
RY24	_	_	_	
RY25	_	_	_	
RY26	_	_	_	

Device No.	Signal name	Signal name ON (data value=1)	OFF (data value=0)
RY27	_	_	_
RY28	_	_	_
RY29	_	_	_
RY2A	_	_	_
RY2B	_	_	_
RY2C	Link tension monitor digit ×10/×1	Link tension monitor digit ×10	Link tension monitor digit ×1
RY2D	Continuous settings execution	Start continuous settings execution	Normal
RY2E	Continuous monitor execution	Start continuous monitor execution	Normal
RY2F	Request command execution	Start request command execution	Normal
RY30 to 3F	System use area		

### • Remote input (Slave Station → Master Station)

Device No.	Signal name	Signal name ON (data value=1)	OFF (data value=0)
RX00	Run/Stop Run		Stop
RX01	Output ON/OFF	Output ON	Output OFF
RX02	B-axis controlled/A-axis controlled	B-axis controlled	A-axis controlled
RX03	Constant tension ON/OFF	Constant tension ON	Constant tension OFF
RX04	Predrive being executed	Predrive being executed	Normal
RX05	Memory hold being executed	Memory hold being executed	Normal
RX06	Reverse running/Forward running	Reverse running	Forward running
RX07	_	_	_
RX08	Manual control	Manual control	_
RX09	Automatic control	Automatic control	_
RX0A	Auto lamp flicker in operation/ stopped	Auto lamp flicker in operation	Auto lamp flicker stopped
RX0B	Stall setting output being executed	Stall setting output being executed	Normal
RX0C	Stall memory output being executed	Stall memory output being executed	Normal
RX0D	Start timer operation being executed	Start timer operation being executed	Normal
RX0E	Stop timer operation being executed	Stop timer operation being executed	Normal
RX0F	Preset timer operation being executed	Preset timer operation being executed	Normal
RX10	Cut torque operation being executed	Cut torque operation being executed	Normal
RX11	Inching operation being executed	Inching operation being executed	Normal
RX12	_	_	_
RX13	Zero adjustment being executed	Zero adjustment being executed	Normal
RX14	Span adjustment being executed	Span adjustment being executed	Normal
RX15	Maximum diameter teaching being executed	Speed teaching being executed	Normal
RX16	Minimum diameter teaching being executed	Speed teaching being executed	Normal
RX17	Control gain tuning being executed	Control gain tuning being executed	Normal
RX18	Speed teaching being executed	Speed teaching being executed	Normal
RX19	Tension upper limit detection ON/ OFF	Tension upper limit detection ON	Tension upper limit detection OFF
RX1A	Tension lower limit detection ON/OFF	Tension lower limit detection ON	Tension lower limit detection OFF
RX1B	Detection outside tension range ON/ OFF	Detection outside tension range ON	Detection outside tension range OFF
RX1C	Reel diameter detection 1 ON/OFF	Reel diameter detection 1 ON	Reel diameter detection 1 OFF
RX1D	Reel diameter detection 2 ON/OFF	Reel diameter detection 2 ON	Reel diameter detection 2 OFF
RX1E	Reel diameter detection 3 ON/OFF	Reel diameter detection 3 ON	Reel diameter detection 3 OFF
RX1F	Measurement length/remaining length detection 1 ON/OFF	Measurement length/remaining length detection 1 ON  Measurement length length detection 1 C	
RX20	Measurement length/remaining length detection 2 ON/OFF	Measurement length/remaining length detection 2 ON Measurement length/remaining length length detection 2 OFF	
RX21	Measurement length/remaining length detection 3 ON/OFF	Measurement length/remaining length detection 3 ON	Measurement length/remaining length detection 3 OFF

Device No.	Signal name	Signal name ON (data value=1)	OFF (data value=0)	
RX22	Peripheral speed synchronization detection ON/OFF	Peripheral speed synchronization detection ON	Peripheral speed synchronization detection OFF	
RX23	Alarm occurrence detection	Alarm occurrence	Normal	
RX24	Parameter protection being executed	Parameter protection being executed	Normal	
RX25	Settings password matching being executed	Settings password matching being executed	Settings password does not match	
RX26	Monitor password matching being executed	Monitor password matching being executed	Monitor password does not match	
RX27	_	_	_	
RX28	Data copy being executed	Data copy being executed	Normal	
RX29	Data initial being executed	Data initial being executed	Normal	
RX2A	_	_	_	
RX2B	_	_	_	
RX2C	_	_	_	
RX2D	Continuous settings being executed	Continuous settings being executed	Normal	
RX2E	Continuous monitor being executed	Continuous monitor being executed	Normal	
RX2F	Request command completion	Request command completion	Normal	
RX30 to 3F	System use area			

# Remote register

Remote register uses 12 points for both RWw and RWr.

The remaining area becomes non-functioning and cannot be used.

CC-Link IE Field Network Basic master station→LE7-40GU				
Device No.	Signal name	Signal name		
RWw n	Continuous settings 1			
RWw n+1	Continuous settings 2			
RWw n+2	Request command 0	Request code 0		
RWw n+3	Setting data 0			
RWw n+4	Request command 1	Request code 1		
RWw n+5	Setting data 1			
RWw n+6	Continuous settings 3			
RWw n+7	Continuous settings 4			
RWw n+8	Request command 2	Request code 2		
RWw n+9	Setting data 2			
RWw n+10	Request command 3	Request code 3		
RWw n+11	Setting data 3			
RWw n+12 to 15	Unavailable			

LE7-40GU→CC-Link IE Field Ne	LE7-40GU→CC-Link IE Field Network Basic master station				
Device No.	Signal name				
RWr n	Continuous monitor 1				
RWr n+1	Continuous monitor 2				
RWr n+2	Continuous monitor 3				
RWr n+3	Continuous monitor 4				
RWr n+4	Request command execution result 0				
RWr n+5	Request command execution result 1				
RWr n+6	Continuous monitor 5				
RWr n+7	Continuous monitor 6				
RWr n+8	Continuous monitor 7				
RWr n+9	Continuous monitor 8				
RWr n+10	Request command execution result 2				
RWr n+11	Request command execution result 3				
RWw n+12 to 15	Unavailable				

### Continuous setting/continuous monitoring

Data specified in advance can be set and monitored continuously by setting the continuous setting execution (RY2E) and continuous monitor execution (RY2E) in the master station to ON.

For continuous setting data, the data set for RAM writing is not stored during a power failure.

The latest data existing in LE7-40GU when the master station gives the send request can be monitored continuously. However, regarding the update of parameters for which the monitor update cycle is specified by the setting in LE7-40GU, the data is updated in the specified update cycle if the specified update cycle is longer than the monitor update cycle in the send request given by the master station.

### Continuous settings

- 1. Data write to devices with continuous settings 1 to 16
- **2.** Turn on continuous settings execution

### **Continuous monitor**

- **1.** Turn on continuous monitor execution
- 2. Read the data of the devices of continuous monitors 1 to 16

### Access by request command

For any access to data in LE7-40GU from the master station, data can be read and written by handshake between the "request command execution (RY2F)" flag and the "request command completion (RX2F)" flag.

This access is performed using a 2-word word device of the master station.

This 2-word data is comprised of the request command, to which the upper 4 bits of the first word are assigned, and the request code, to which the lower 2 bits are assigned, and the setting data, to which the next word is assigned.

bit 15 to 12	bit 11 to 0
Request command	Request code
Setting data	·

There are three types of request command, Data Monitor, Writing to RAM, and Writing to RAM + ROM, according to the selection of data reading and writing method.

Monitor	Writing to RAM	Writing to RAM + ROM
Writing data is reflected in the settings based on a	Writing data is reflected in the settings based on a	Perform the above RAM write + data power failure
data read request from the master station but is	data write request from the master station but is	write.
not stored in the case of a power failure.	not stored in the case of a power failure.	

In the ROM for storage against power interruption, the allowable number of times of writing is limited. Accordingly, data cyclically written and updated by the PLC must be written only to the RAM.

Request command	Contents of execution	Execution result
Н0	Monitor	Monitored value
H1	Writing to RAM	Writing result
H2	Writing to RAM + ROM	Writing result

The request code is the data number (address) of the data that executes the request command. The subsequent data setting is the data to be written to the data number, and if the request command is the monitor, the data setting data is ignored. When double word data is written to send data in the master station, and the handshake is executed by turning ON/OFF the request command execution flag and request command completion flag as follows, LE-70GU sends back the request command execution request.

- **1.** The master station is set to request command execution ON.
- 2. LE7-40GU executes processing when receiving turning ON of the request command execution by the master station.
- **3.** LE7-40GU turns ON the request command completion.
- **4.** The master station receives the request command completion ON.
- 5. The master station is set to request command execution OFF.

- **6.** LE7-40GU receives turning OFF of the request command execution by the master station.
- **7.** LE7-40GU turns OFF the request command completion.
- **8.** The master station receives the request command completion OFF.

Please perform reading of the execution results of the request command between step 4 and 5 of the handshake procedure. If an error occurs, in the execution result with respect to the request command from the master station, turn on the network alarm occurrence flag and output the device number where the alarm occurred to the network alarm device number monitor. For the request command execution result, refer to the following.

**LALE7-CCL APPLICATION MANUAL** 

### Request code

The numerical value of each parameter corresponding to the request code is treated as real number data without a decimal point.

In addition, the minimum and maximum values are determined for LE7-40GU, and when a value exceeding this data is written, it is automatically rewritten to the minimum or maximum value.

In this case, an "Out of data range" alarm is generated.

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H000(0)	_	_	_	_	_	_
H001(1)	Total tension	Monitor	_	0 or less	2000 or more	N/×10 N
H002(2)	Left tension	Monitor	_	0 or less	2000 or more	N/×10 N
H003(3)	Right tension	Monitor	_	0 or less	2000 or more	N/×10 N
H004(4)	Left input voltage	Monitor	_	-1500 or less	1500 or more	mV
H005(5)	Right input voltage	Monitor	_	-1500 or less	1500 or more	mV
H006(6)	_	_	_	_	_	-
H007(7)	_	_	_	_	_	-
H008(8)	_	_	_	_	_	_
H009(9)	_	_	_	_	_	_
H00A(10)	_	_	_	_	_	_
H00B(11)	_	_	_	_	_	_
H00C(12)	_	_	_	_	_	_
H00D(13)	_	_	_	_	_	_
H00E(14)	_	_	_	_	_	_
H00F(15)	_	_	_	_	_	_
H010(16)	Tension upper limit detection	Setting	_	0	Tension full scale	N/×10 N
H011(17)	Tension lower limit detection	Setting	_	0	Tension full scale	N/×10 N
H012(18)	Detection outside target tension range	Setting	_	0	50	%
H013(19)	Tension display filter	Setting	_	5	80	sec
H014(20)	Tension detection filter	Setting	_	0	80	sec
H015(21)	Tension output filter	Setting	_	0	80	sec
H016(22)	_	_	_	_	_	-
H017(23)	_	_	_	_	_	_
H018(24)	_	_	_	_	_	_
H019(25)	_	_	_	_	_	_
H01A(26)	_	_	_	_	_	_
H01B(27)	_	_	_	_	_	_
H01C(28)	_	_	_	_	_	_
H01D(29)	_	_	_	_	_	_
H01E(30)	_	_	_	_	_	_
H01F(31)	_	_	_	_	_	_
H020(32)	Sensor input type selection	Setting	_	0 (LX type), 1 (strain	gauge)	_
H021(33)	Tension full scale	Setting	_	1	2000	N/×10 N
H022(34)	Tension display decimal point selection	Setting	_	0 (1), 1 (0.1), 2 (0.01	)	_
H023(35)	Tension display unit selection	Setting	_	0 (N), 1 (×10 N)		_

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H024(36)	Span target tension	Setting	_	1	Tension full scale	N/×10 N
H025(37)	Left manual zero calibration	Setting	_	-999	999	N/×10 N
H026(38)	Right manual zero calibration	Setting	_	-999	999	N/×10 N
H027(39)	Left manual span calibration	Setting	_	50	300	%
H028(40)	Right manual span calibration	Setting	_	50	300	%
H029(41)	_	_	_	_	_	_
H02A(42)	_	_	_	_	_	_
H02B(43)	_	_	_	_	_	_
H02C(44)	_	_	_	_	_	_
H02D(45)	_	_	_	_	_	_
H02E(46)	_	_	_	_	_	_
H02F(47)	_	_	_	_	_	_
H030(48)	Reel diameter	Monitor	_	1	2000	mmφ
H031(49)	Target line velocity	Monitor	LE7-DCA	0	10000	m/min
H032(50)	Line acceleration	Monitor	LE7-DCA	0	50	m/min/sec
H033(51)	Measurement length/remaining length	Monitor	LE7-DCA	_	_	m
H034(52)	Reel rotational speed	Monitor	LE7-DCA	65000	1	r/min
H035(53)	New reel rotational speed	Monitor	LE7-DCA	3600	1	r/min
	·	Monitor	LE7-DCA	1000	0.1	%
H036(54)	Constant slip ROTO speed command output			+	+	%
H037(55)	Predrive rotation speed command output	Monitor	LE7-DCA	1000	0.1	
H038(56)	Predrive target rotation speed	Monitor	LE7-DCA	3600	1	r/min
H039(57)	Reel diameter CALC adapter ROM version	Monitor	LE7-DCA	999	0.01	_
H03A(58)		_	_	_	_	_
H03B(59)	_	_	_	_	_	_
H03C(60)	_	_	_	_	_	_
H03D(61)	_	_	_	_	_	_
H03E(62)	_	_	_	_	_	_
H03F(63)	_	_	_	_	_	_
H040(64)	Initial diameter	Setting	LE7-DCA	1	2000	mmφ
H041(65)	Material thickness	Setting	LE7-DCA	0	10000	μm
H042(66)	Reel diameter detection 1	Setting	LE7-DCA	0	2000	mmφ
H043(67)	Reel diameter detection 2	Setting	LE7-DCA	0	2000	mmφ
H044(68)	Reel diameter detection 3	Setting	LE7-DCA	0	2000	mmφ
H045(69)	Measurement/remaining length detection 1	Setting	LE7-DCA	0	65000	m
H046(70)	Measurement/remaining length detection 2	Setting	LE7-DCA	0	65000	m
H047(71)	Measurement/remaining length detection 3	Setting	LE7-DCA	0	65000	m
H048(72)	Accelerating judgment acceleration	Setting	LE7-DCA	0	10	m/min/sec
H049(73)	Reel rotational speed gain	Setting	LE7-DCA	0	150	%
H04A(74)	Reel rotational speed bias	Setting	LE7-DCA	0	100	%
H04B(75)	Reel rotational speed startup gain	Setting	LE7-DCA	1	5	Time (s)
H04C(76)	Reel rotational speed startup timer	Setting	LE7-DCA	0	10	sec
H04D(77)	Predrive time	Setting	LE7-DCA	0	200	sec
H04E(78)	Predrive bias	Setting	LE7-DCA	-10	10	%
H04F(79)	_	_	_	_	_	_
H050(80)	Maximum diameter	Setting	_	Minimum diameter	2000	mmφ
H051(81)	Minimum diameter	Setting	_	1	Maximum diameter	mmφ
H052(82)	Teaching speed	Setting	LE7-DCA	1	10000	m/min
H053(83)	Velocity electronic gear ratio	Setting	LE7-DCA	9000	18000	%
H054(84)	Reel selection	Setting	LE7-DCA	0(unwinding), 1(wind		_
H055(85)	Number of reel pulse	Setting	LE7-DCA	1 0,1	es), 2 (4 pulses), 3 (8	_
H056(86)	Reel diameter calculation cycle	Setting	LE7-DCA	1 1 1	es), 2 (4 pulses), 3 (8	_

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H057(87)	MEAS/RMN length calculation switch	Setting	LE7-DCA	0 (measurement length), 1 (remaining length)		_
H058(88)	Material thickness unit	Setting	LE7-DCA	0 (×1), 1 (×0.1)		_
H059(89)	Maximum line acceleration	Setting	LE7-DCA	1	50	m/min/sec
H05A(90)	Maximum reel rotational speed	Setting	LE7-DCA	1	3600	r/min
H05B(91)	Detection output selection	Setting	LE7-DCA	0 (Reel diameter), (m remaining length)	neasurement length/	_
H05C(92)	Detection output holding selection	Setting	LE7-DCA	0 (non-holding), 1 (ho	olding)	_
H05D(93)	Run/Stop judgment selection	Setting	LE7-DCA	0 (contact + internal) (internal)	1 (contact), 2	_
H05E(94)	Run judgment speed	Setting	LE7-DCA	Stop judgment speed	30	m/min
H05F(95)	Stop judgment speed	Setting	LE7-DCA	1	Run judgment speed	m/min
H060(96)	_	_	_	_	_	_
H061(97)	_	_	_	_	_	_
H062(98)	_	_	_	_	_	_
H063(99)	_	_	_	_	_	_
H064(100)	_	_	_	_	_	_
H065(101)	_	_	_	_	_	_
H066(102)	_	_	_	_	_	_
H067(103)	_	_	_	_	_	_
H068(104)	_	_	_	_	_	_
H069(105)		_	_	_	_	_
H06A(106)		_	_	_	_	_
H06B(107)	_	_	_	_		_
H06C(108)	_	_	_	_	_	_
H06D(109)		_	_	_		_
H06E(110)	_	_	_	_	_	_
H06F(111)		_	_			_
H070(112)	Target tension	Monitor	_	0	2000	N/×10 N
H071(113)	Control output	Monitor	_	-1000 or less	1000 or more	%
H072(114)	Torque output	Monitor	_	-1000 or less	1000 or more	%
H073(115)	Torque output	WOTHO		-1000 of less	1000 of filore	70
H074(116)	_					
. ,		Manitar		260 or more	0.1	V
H075(117)	Control output voltage for powder	Monitor	_	260 or more	0.1	
H076(118)	Control output current for powder  —	Monitor	_	400 or more	0.01	A
, ,				_	_	_
H078(120)	_		_	_	_	_
H079(121)	_		_	_	_	_
H07A(122)	<del> -</del>		_	_	_	_
H07B(123)	_	_	_	_	_	_
H07C(124)	_	_	_	_	_	_
H07D(125)	_	_	_	_	_	_
H07E(126)	_		_	_	_	_
H07F(127)	_	_	_	_	_	_
H080(128)	Tension setting	Setting	_	1	Tension full scale	N/×10 N
H081(129)	Manual setting	Setting	_	-1000	1000	%
H082(130)	Stall setting	Setting	_	0	1000	%
H083(131)	Start timer	Setting	_	0	300	sec
H084(132)	Stop timer	Setting	_	0	1000	sec
H085(133)	Stop gain	Setting	_	5	400	%
H086(134)	Stop bias	Setting	_	0	100	%

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H087(135)	Acceleration/deceleration torque setting	Setting	LE7-DCA	0	1000	%
H088(136)	Gain 1	Setting	_	5	400	%
H089(137)	Gain 2	Setting	_	5	400	%
H08A(138)	Internal taper ratio	Setting	_	0	80	%
H08B(139)	External linear line taper ratio	Setting	_	0	100	%
H08C(140)	New reel preset	Setting	_	0	1000	%
H08D(141)	New reel preset timer	Setting	_	0	300	sec
H08E(142)	Cutting torque	Setting	_	0	1000	%
H08F(143)	_	_	_	_	_	_
H090(144)	Broken line taper corner 1	Setting	_	1	2000	mmφ
H091(145)	Broken line taper ratio 1	Setting	_	0	100	%
H092(146)	Broken line taper corner 2	Setting	_	1	2000	mmφ
H093(147)	Broken line taper ratio 2	Setting	_	0	100	%
H094(148)	Broken line taper corner 3	Setting	_	1	2000	mmφ
H095(149)	Broken line taper ratio 3	Setting	_	0	100	%
* *	·	_	_	1	2000	
H096(150)	Broken line taper corner 4	Setting		0		mmφ
H097(151)	Broken line taper ratio 4	Setting			100	%
H098(152)	Broken line taper corner 5	Setting	_	1	2000	mmφ
H099(153)	Broken line taper ratio 5	Setting	_	0	100	%
H09A(154)	Broken line taper corner 6	Setting	_	1	2000	mmφ
H09B(155)	Broken line taper ratio 6	Setting	_	0	100	%
H09C(156)	Broken line taper corner 7	Setting	_	1	2000	mmφ
H09D(157)	Broken line taper ratio 7	Setting	_	0	100	%
H09E(158)	Broken line taper corner 8	Setting	_	1	2000	mmφ
H09F(159)	Broken line taper ratio 8	Setting	_	0	100	%
H0A0(160)	Proportional gain	Setting	_	0	100	%
H0A1(161)	Integral time	Setting	_	0	100	%
H0A2(162)	Dead band gain	Setting	_	0	100 - Proportional gain	%
H0A3(163)	Dead band width	Setting	_	0	100	%
H0A4(164)	Tension control filter	Setting	_	0	40	sec
H0A5(165)	Static mechanical loss A	Setting	_	-1000	1000	%
H0A6(166)	Static mechanical loss B	Setting	_	-1000	1000	%
H0A7(167)	Kinetic mechanical loss A	Setting	LE7-DCA	-1000	1000	%
H0A8(168)	Kinetic mechanical loss B	Setting	LE7-DCA	-1000	1000	%
H0A9(169)	Mass correction gain A	Setting	LE7-DCA	0	100	%
H0AA(170)	Mass correction gain B	Setting	LE7-DCA	0	100	%
H0AB(171)	Mass correction bias A	Setting	LE7-DCA	0	100	%
H0AC(172)	Mass correction bias B	Setting	LE7-DCA	0	100	%
H0AD(173)	_	_	_	_	_	_
H0AE(174)	_	_	_	-	_	_
H0AF(175)	_	_	_	_	_	_
H0B0(176)	Control mode selection	Setting	LE7-DCA	0 (feedback control),	1 (open loop control)	-
H0B1(177)	Integral feedback limit	Setting	_	0	101	%
H0B2(178)	Feedback selection during the stop timer	Setting	_	0 (invalid), 1 (valid)	1	-
H0B3(179)	Automatic control output polarity selection	Setting	_	0 (forward), 1 (revers	e)	-
H0B4(180)	Open-loop control ratio	Setting	LE7-DCA	0	100	%
H0B5(181)	Taper function selection	Setting	_	0 (no function), 1 (intelline taper (external)),	3 (broken line taper	_
	1	I		(external)), 4 (direct to	ap <del>e</del> i)	
LIODG(400)	Colorion of two really switching 51010	Cottine.		0 (invested) 4 ( -11.15		
H0B6(182) H0B7(183)	Selection of two reel's switching FUNC Internal taper standard selection	Setting Setting	_ 	0 (invalid), 1 (valid) 0 (zero standard), 1 (	atall atau da (1)	<u> </u>

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H0B9(185)	Mechanical loss function selection	Setting	LE7-DCA	0 (fixed mechanical loss), 1 (high function mechanical loss)		-
H0BA(186)	Stall automatic calculation gain	Setting	LE7-DCA	0	100	%
H0BB(187)	New reel preset AUTO calculation gain	Setting	LE7-DCA	0	100	%
H0BC(188)	Control output upper limit	Setting	_	Control output lower limit	101	%
H0BD(189)	Control output lower limit	Setting	_	-101	Control output upper limit	%
H0BE(190)	_	_	_	_	_	_
H0BF(191)	_	_	_	_	_	_
H0C0(192)	Load model	Setting	_	0	200	_
H0C1(193)	Rated current	Setting	_	0	400	Α
H0C2(194)	Maximum torque correction	Setting	_	50	250	%
H0C3(195)	Nonlinear correction 0	Setting	_	0	1000	%
H0C4(196)	Nonlinear correction 10	Setting	_	0	1000	%
H0C5(197)	Nonlinear correction 20	Setting	_	0	1000	%
H0C6(198)	Nonlinear correction 30	Setting	_	0	1000	%
H0C7(199)	Nonlinear correction 40	Setting	_	0	1000	%
H0C8(200)	Nonlinear correction 50	Setting	_	0	1000	%
H0C9(201)	Nonlinear correction 60	Setting	_	0	1000	%
H0CA(202)	Nonlinear correction 70	Setting	_	0	1000	%
H0CB(203)	Nonlinear correction 80	Setting	_	0	1000	%
H0CC(204)	Nonlinear correction 90	Setting	_	0	1000	%
H0CD(205)	—	—	_	_	_	70
H0CE(206)					_	
H0CF(207)			_	-  -	_	_
H0D0(208)			_			0/
H0D1(209)	Weak excitation	Setting	_	0	1000	%
H0D2(210)	Over current detection filter	Setting	_	0	20	sec
H0D3(211)	_	_	_	-	_	_
H0D4(212)	_	_	_	_	_	_
H0D5(213)	_		_	_	_	_
H0D6(214)	_	_	_	_	_	_
H0D7(215)	_		_	_	_	_
H0D8(216)	_	_	_	_	_	_
H0D9(217)	_	_	_	_	_	_
H0DA(218)	_	_	_	_	_	_
H0DB(219)	_	_	_	_	_	_
H0DC(220)	_	_	_	_	_	_
H0DD(221)	<u> -</u>		_	-	_	_
H0DE(222)	_	_	_	_	_	_
H0DF(223)	_	_	_	_	_	_
H0E0(224)	Contact input monitor	Monitor	_	0	0xFFFF	_
H0E1(225)	Contact output monitor	Monitor	_	0	0xFFFF	_
H0E2(226)	General-purpose analog input 1 monitor	Monitor	_	0	100	%
H0E3(227)	General-purpose analog input 2 monitor	Monitor	_	0	100	%
H0E4(228)	General-purpose analog input 3 monitor	Monitor	_	0	100	%
H0E5(229)	General-purpose analog output 1 monitor	Monitor	_	0	100	%
H0E6(230)	General-purpose analog output 2 monitor	Monitor	_	0	100	%
H0E7(231)	Analog output monitor for TENS control	Monitor	_	0	100	%
H0E8(232)	Analog output monitor for new reel preset	Monitor	_	0	100	%
H0E9(233)	Contact input monitor for reel DIA CALC	Monitor	LE7-DCA	0	0xFFFF	_
	Contact output monitor for reel DIA CALC		LE7-DCA	0	0xFFFF	+

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H0EB(235)	Alarm display	Monitor	_	0	63	_
H0EC(236)	Network alarm device No.	Monitor	_	0	999	_
H0ED(237)	Main unit ROM version	Monitor	_	0	999	_
			LE7-CCL	0	999	
H0EE(238)	Network adapter ROM version	Monitor		-		_
H0EF(239)	Communication signal monitor	Monitor	_	0	0xFFFF	_
H0F0(240)	Contact input 1 function selection	Setting	_	0 (no function), 1 (rur output OFF/ON), 3 (s		_
H0F1(241)	Contact input 2 function selection	Setting	_		(constant tension ON/	
H0F2(242)	Contact input 3 function selection	Setting	_	OFF), 6 (gain 1 ON/C		_
H0F3(243)	Contact input 4 function selection	Setting	_	OFF), 8 (automatic/m ON/OFF), 10 (cut toro	anual), 9 (reel change	_
H0F4(244)	Contact input 5 function selection	Setting	_	(alarm reset ON/OFF	•	_
H0F5(245)	Contact input 6 function selection	Setting	_	,	,	_
H0F6(246)	-	_	_	_	_	_
H0F7(247)	-	<u> </u>	_	_	_	_
H0F8(248)	Contact output 1 function selection	Setting	_	0 (no function), 1 (ten	sion lower limit	_
H0F9(249)	Contact output 2 function selection	Setting	_	detection), 2 (tension 3 (detection outside to (alarm occurrence de	= :	_
H0FA(250)	_	_	_	_	_	_
H0FB(251)	1-	_	_	_	_	_
H0FC(252)	_	_	_	_	_	_
H0FD(253)	_	_	_	_	_	_
H0FE(254)	_	_	_	_	_	_
H0FF(255)	<del> </del> _		_	_	_	_
H100(256)	Analog input mode selection	Setting	_	0 (0 to 5 V mode), 1 (	0 to 10 V mode)	_
H101(257)	Analog input 1 function selection	Setting	_	0 (no function), 1 (ten	•	_
	<u> </u>		_	setting), 3 (straight lin	•, ,	_
H102(258)	Analog input 2 function selection	Setting		4 (new axis preset se	tting), 5 (manual	
H103(259)	Analog input 3 function selection	Setting	_	setting), 6 (tension input), 7 (Reel diameter input)		_
H104(260)	<u> </u> -		_	_	_	_
H105(261)	-	_	_	_	_	_
H106(262)	_	_	_	_	_	_
H107(263)	_	_	_	_	_	_
H108(264)	Analog output mode selection	Setting	_	0 (0 to 5 V mode), 1 (	0 to 10 V mode)	_
H109(265)	Analog output 1 function selection	Setting	_	0 (no function), 1 (ten	sion monitor), 2 (Reel	_
H10A(266)	Analog output 2 function selection	Setting	_	diameter monitor), 3 (tension setting monitor), 4 (A-axis Reel shaft rotational speed output), 5 (B-axis Reel shaft		_
				rotational speed outp		
H10B(267)	Analog output 1 gain	Setting	_	500	3000	%
H10C(268)	Analog output 1 gain  Analog output 2 gain	-	_	500	3000	%
, ,		Setting				
H10D(269)	Analog output 1 bias	Setting	_	-500	500	%
H10E(270)	Analog output 2 bias	Setting	_	-500	500	%
H10F(271)		-	_			_
H110(272)	Two reel's switching FUNC output mode	Setting	_	0 (no internal switchir switching)		_
H111(273)	Control output mode selection	Setting	_	0 (0 to 5 V mode), 1 (-5 to 5 V mode), 2 (0 to 10 V mode), 3 (-10 to 10 V mode), 4 (0 to 8 V mode), 5 (-8 to 8 V mode), 6 (0 to 2.7 V mode), 7 (-2.7 to 2.7 V mode), 8 (1 to 5 V		_
11440/074)	Control autout pain	0-411		mode)	2000	0/
H112(274)	Control output gain	Setting	_	500	3000	%
H113(275)	New reel preset output gain	Setting	_	500	3000	%
H114(276)	Control output bias	Setting	_	-500	500	%
H115(277)	New reel preset output bias	Setting	_	-500	500	%
H116(278)	_	I —	-	-	-	<b> </b> —

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H117(279)	_	_	_	_	_	_
H118(280)	_	_	_	_	_	_
H119(281)	_	_	_	_	_	_
H11A(282)	_	_	_	_	_	_
H11B(283)		_	_	_	_	_
H11C(284)	_	_	_	_	_	_
H11D(285)		_	_	_	_	_
H11E(286)	_	_	_	_	_	_
H11F(287)	_	_	_	_	_	_
H120(288)	Set setting password	Setting	_	0	32000	_
H121(289)	Input setting password	Setting	_	0	32000	_
H122(290)	Set monitor password	Setting	_	0	32000	_
H123(291)	Input monitor password	Setting	_	0	32000	_
H124(292)	_	_	_	_	_	_
H125(293)	_	_	_	_	_	_
H126(294)	_	_	_	_	_	_
H127(295)	_	_	_	_	_	_
H128(296)	_	_	_	_	_	_
H129(297)	_	_	_	_	_	_
H12A(298)	_	_	_	_	_	_
H12B(299)	_	_	_	_	_	_
H12C(300)	_	_	_	_	_	_
H12D(301)	_	_	_	_	_	_
H12E(302)	_	_	_	_	_	_
H12F(303)	_	_	_	_	_	_
H130(304)	Alarm history 1	Monitor	_	0	63	_
H131(305)	Alarm history 2	Monitor	_	0	63	_
H132(306)	Alarm history 3	Monitor	_	0	63	_
H133(307)	Alarm history 4	Monitor	_	0	63	_
H134(308)	Alarm history 5	Monitor	_	0	63	_
H135(309)	Alarm history 6	Monitor	_	0	63	_
H136(310)	Alarm history 7	Monitor	_	0	63	_
H137(311)	Alarm history 8	Monitor	_	0	63	_
H138(312)	Alarm history holding selection	Setting	_	0 (no holding), 1 (hole		_
H139(313)	Alarm display time	Setting	_	0	301	sec
H13A(314)	Alarm operation selection 1	Setting	_	0	0xFFFF	
H13B(315)	Alarm operation selection 2		_	0	0xFFFF	_
H13C(316)	Alarm operation selection 2  Alarm operation selection 3	Setting Setting	-	0	0xFFFF	
	<u>'</u>		+	0	0xFFFF	
H13D(317)	Alarm operation selection 4  —	Setting —	_	_	— UXFFFF	_
H13E(318)	_	<del> -</del>	_	_	<del>-</del>	_
H13F(319)						
H140(320)	<u> </u>		_	_	_	_
H141(321)	<u> </u>	<u> </u>	_	_	_	_
H142(322)	_	<u> </u>	_	_	_	_
H143(323)	_		_	_	_	_
H144(324)	_		_	_	_	_
H145(325)	_		_	_	_	_
H146(326)	_		_	_	_	_
H147(327)	_	_	_	_	_	_
H148(328)	_	_	_	_	_	_
H149(329)	_	_	_	_	_	_
H14A(330)	_	_	_	_	_	_

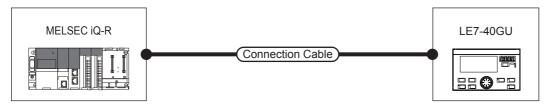
Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H14B(331)	_	_	_	_	_	_
H14C(332)	_	_	_	_	_	_
H14D(333)	_	_	_	_	_	_
H14E(334)	_	_	_	_	_	_
H14F(335)	_	_	_	_	_	_
H150(336)	_	_	_	_	_	_
H151(337)	_	_	_	_	_	_
H152(338)	_	_	_	_	_	_
H153(339)	_	_	_	_	_	_
H154(340)	_	_	_	_	_	_
H155(341)	_	_	_	_	_	_
H156(342)	_	_	_	_	_	_
H157(343)	_	_	_	_	_	_
H158(344)	_	_	_	_	_	_
	_	_				_
H159(345)			_	_	_	
H15A(346)	_	_	_	_	_	_
H15B(347)	_	_	_	_	_	_
H15C(348)	_	_	_	_	_	_
H15D(349)	_	_	_	_	_	_
H15E(350)	_	_	_	_	_	_
H15F(351)	_	_	_	_	_	_
H160(352)	_	_	_	_	_	_
H161(353)	_	_	_	_	_	_
H162(354)	_	_	_	_	_	_
H163(355)	_	_	_	_	_	_
H164(356)	_	_	_	_	_	_
H165(357)	_	_	_	_	_	_
H166(358)	_	_	_	_	_	_
H167(359)	_	_	_	_	_	_
H168(360)	_	_	_	_	_	_
H169(361)	_	_	_	_	_	_
H16A(362)	_	_	_	_	_	_
H16B(363)	_	_	_	_	_	_
H16C(364)	_	_	_	_	_	_
H16D(365)	_	_	_	_	_	_
H16E(366)	_	_	_	_	_	_
H16F(367)	_	_	_	_	_	_
H170(368)	_	_	_	_	_	_
H171(369)	_	_	_	_	_	_
H172 (370)	_	_	_	_	_	_
H173(371)	_	_	_	_	_	_
H174(372)	_	_	_	_	_	_
H175(373)	_	_	_	_	_	_
H176(374)	_	_	_	_	_	_
H177(375)	_	_	_	_	_	_
H177(375)	_	_	_	_	_	_
	_	_				<del>-</del>   <u>-</u>
H179(377)			_	_	_	
H17A(378)	_	_	_	_	_	_
H17B(379)	_	_	_	_	_	_
H17C(380)	_	_	_	_	_	_
H17D(381)	_	_	_	_	_	_
H17E(382)	_	_	_	_	_	_

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H17F(383)	_	_	_	_	_	_
H180(384)	Open-loop control base torque	Setting	LE7-DCA	0	1000	%
H181(385)	Direct taper ratio	Setting	_	0	1000	%
H182(386)	Link tension monitor filter	Setting	_	0	80	sec
H183(387)	Tension input	Setting	_	0	2000	N/×10 N
H184(388)	Reel diameter input	Setting	_	0	2000	mmφ
H185(389)	_	_	_	_	_	_
H186(390)	_	_	_	_	_	_
H187(391)	_	_	_	_	_	_
H188(392)	_	_	_	_	_	_
H189(393)	_	_	_	_	_	_
H18A(394)	_	_	_	_	_	_
H18B(395)	_	_	_	_	_	_
H18C(396)	_	_	_	_	_	_
H18D(397)	_	_	_	_	_	_
H18E(398)	_	_	_	_	_	_
H18F(399)	_	_	_	_	_	_

# 3.3 Reference Program

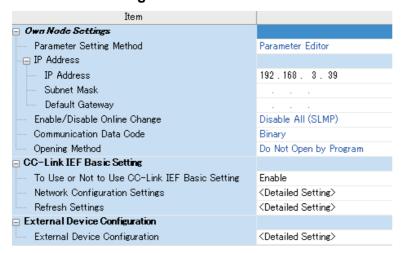
A basic example program (GX Works3) for CC-Link IE Field Network Basic communication is described.

### System configuration



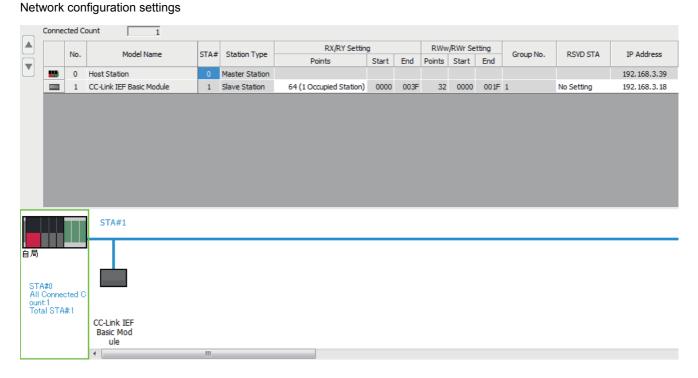
### Settings

### **■**Own node settings

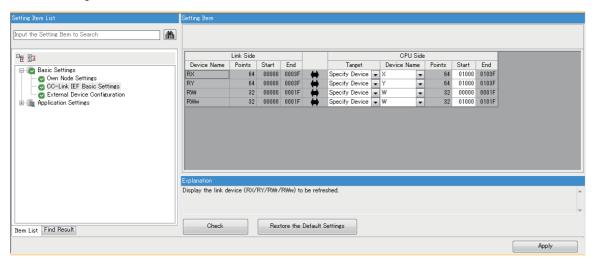


### **■CC-Link IEF Basic setting**

To use or not use CC-Link IEF Basic setting: Enable



### Refresh settings



### **■**External device configuration

Setting is unnecessary.

#### **Program example** 10 12 Write 1 \*Request command access processing X20 X102F D100 W1002 1/1 RWwn+2 Request 2 (0) MOV command 0 + request Request Request command command access start completion code 0 D101 W1003 RWwn+3 3 MOV data 0 D102 W1004 Request command 1 RWwn+4 + request code 1 D103 W1005 RWwn+5 Setting 5 MOV data 1 D100 W1008 Request 6 MOV command 0 + request code 0 D104 W1009 MOV Request RWwn+9 command 2 + request code 2

Writ	te	- 1	2	3	4	5	6	7	8	9	10	11	12
												D105	W100A
8											MOV	Setting data 2	RWwn+10
9											MOV	D106  Request command 3 + request code 3	W100B RWwn+11
													Y102F
10												SET	Request command execution
			X102F										5446
11			Request command completion								MOV	W4 RWrn+4	D110 Request command execution result 1
												W5	D111
12											MOV	RWrn+5	Request command execution result 2
												WOA	D112
13											MOV	RWrn+10	Request command execution request 3
												WOB	D113
14											MOV	RWrn+11	Request command execution result 4
		X20											LIN 2 0=
													Y102F
15	(3	Request command access start										RST	Request command execution

Write	· 1	2	3	4	5	6	7	8	9	10	11	12
16 *Cc	ntinuous monito	processing										
17	(33) Continus monito start	ıou									SET	Y102E Continuous monitor execution
18										MOV	W0 RWrn+0	D120 Continuous monitor 1 (Total tension)
19										MOV	W1 RWrn+1	D121 Continuous monitor 2 (Target tension)
20										MOV	W2 RWrn+2	D122 Continuous monitor 3 (Control output)
21										MOV	W3 RWrn+3	D123  Continuous monitor 4 (Alarm display)
22	(44) Continu s monito start	Iou									RST	Y102E Continuous monitor execution

Writ			2	3	4	5	6	7	8	9	10	11	12
23	*Continuous	settings pro	cessing										
24	(46)	Continuou s setting start									MOV	D130 Continuous settings 1 (Tension setting)	W1000 RWwn
25											моч	D131 Continuous settings 2	W1001 RWwn+1
												(Manual setting)	W1006
26											MOV	Continuous settings 3 (Stall setting)	
												D133	W1007
27											MOV	Continuous settings 4 (Alarm display)	RWwn+7
												_	Y102D
28												SET	Continuous settings execution
		X22											Y102D
29	(57)	Continuou s setting start										RST	Continuous settings execution
30	*Feedback o	ontrol seque	nce process	ing									
50		X23	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,										Y1003
		$\vdash$										-	
31	(59)	Stall start										SET	Auto/Manual
			X24										Y1000
32			Start the controller.									SET	Run/Stop
			X24										114000
			$\sqcup_{l}$									_	Y1000
33			Start the controller.									RST	Run/Stop
		X23											
		$\vdash$										_	Y1000
34	(68)	Stall start										RST	Run/Stop
													Y1003
35												RST	Auto/Manual

Write	*	1	2	3	4	5	6	7	8	9	10	11	12
36 *Sta	atus mon	itoring proce	essing										
		X1000											Y30
37	(71)	Run/Stop											Running lamp
38	(74)	X1008											Y31
		Manual control X1009											Manual control lamp Y32
39	(76)	<u></u>											
		Automatic control X100A											Automatic control lamp Y33
40	(78)	Auto lamp											
		flicker in operation/ stopped X102F											Auto lamp flicker in operation lamp Y34
41	(80)	Request											Request command
		command completion X102E											completion lamp
42	(82)	Continuou s monitor											Continuous monitor being
		being executed X102D											executed lamp
43	(84)	Continuou s settings											Continuous settings being
		being executed											executed lamp
44	(86)												(END }

## Using method of ladder

Required data is stored to D100 to D133, and each function is executed in X20 to X24. List of used devices (The allocation is an example.)

Device name	Classification*1	Allocation function	Use
D100 to D106	Setting	Request command + request code/data setting 1 to 4	Device set to use the request command
D110 to D113	Setting	Request command execution result 1 to 4	Request command execution result is stored.
D120 to D123	Setting	Continuous monitor 1 to 4	Continuous monitor execution result is stored.
D130 to D133	Setting	Continuous setting 1 to 4	Setting value of continuous setting is stored.
X20	Setting	Start request command access execution	Execute request command.
X21	Setting	Start continuous monitor execution	Start to execute continuous monitor.
X22	Setting	Start continuous setting execution	Start to execute continuous setting.
X23	Setting	Start stall execution	Start to execute stall.
X24	Monitoring	Start operation	Start to operate.
Y30	Monitoring	Run	Run: ON/Stop: OFF
Y31	Monitoring	Manual control	Manual control ON
Y32	Monitoring	Automatic control	Automatic control ON
Y33	Monitoring	Auto lamp flicker in operation	Auto lamp flicker in operation ON
Y34	Monitoring	Request command completion	ON when request command is completed
Y35	Monitoring	Continuous monitor being executed	ON when continuous monitor is being executed.
Y36	Monitoring	Continuous settings being executed	ON when continuous setting is being executed.

<sup>\*1</sup> Classification

Setting: items to be set/input when using functions Monitoring: items to monitor output when using functions

# 4 SLMP COMMUNICATION

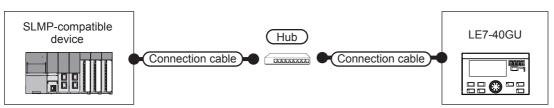
Since the LE7-40GU supports the SLMP communication function which is an open FA network, it can communicate with various SLMP-compatible devices. Also, up to seven LE7-40GU units can be connected to one SLMP-compatible device to carry out data monitoring and parameter writing.

#### **Precautions**

If you replace an external device or an SLMP equipment due to a malfunction, the MAC address of the connected device changes, so communication may not be possible. (When exchanged with the same IP address equipment)

If you replace a device in the Ethernet, restart all the devices in the network.

# 4.1 System Configuration



Connection	Communic	Connection ca	able	External	Connection ca	able	Tension controller*2		Number of
equipment	ation form	Cable type name*4	Maximum segment length*3	device	Cable type name*4	Maximum segment length*3	Optional equipment	Main unit	connectable devices
SLMP equipment	Ethernet	1000BASE-T 100BASE-TX Category 5 or more of shield twisted pair cable (STP) or unshielded twisted pair cable (UTP)     10BASE-T Category 3 or more of shield twisted pair cable (STP) or unshielded twisted pair cable (STP) or unshielded twisted pair cable (STP) or unshielded twisted pair cable (UTP)	100 m	Hub*1	1000BASE-T 100BASE-TX Category 5 or more of shield twisted pair cable (STP) or unshielded twisted pair cable (UTP)     10BASE-T Category 3 or more of shield twisted pair cable (STP) or unshielded twisted pair cable (STP) or unshielded twisted pair cable (UTP)	100 m	— (Built-in to main unit)	LE7-40GU	Up to seven units can be connected to one SLMP compatible device The maximum number of connected units may be seven or less depending on the SLMP equipment used 15

<sup>\*1</sup> Please connect with SLMP equipment via a hub.

Use cables, connectors, and hubs that satisfy the IEEE 802.3 10BASE-T/100BASE-TX/1000BASE-T standard.

The maximum distance depends on the Ethernet device used.

When using a repeater hub, the number of units that can be connected is as follows.

- · 10BASE-T: Cascade connection up to 4 units (500 m)
- · 100BASE-TX: Cascade connection up to 2 units (205 m)

When using a switching hub, the cascade connection between switching hubs has no theoretical limit on the number that can be cascaded.

Please check with the manufacturer of the switching hub used for any restrictions.

- \*4 For the twisted pair cable, please use a straight cable.
- \*5 For details, refer to the manual of the SLMP equipment used.

<sup>\*2</sup> When connecting LE7-40GU to 10 BASE (- T/2/5) compliant equipment, use it in a network environment where 10 Mbps/100 Mbps can be mixed using a switching hub.

<sup>\*3</sup> This is the length between the hub and the node.

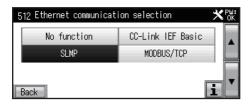
# 4.2 Communication Setting

# **Communication parameter settings**

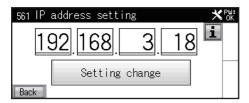
When using SLMP communication, set the communication parameters with the following procedure.

#### **Setting with Data Transfer Tool**

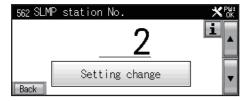
- 1. Obtain the "Screen package data for SLMP communication" from your local Mitsubishi Electric representative.
- **2.** Transfer the "Screen package data for SLMP communication" to LE7-40GU with Data Transfer Tool (for GT Works3). For more information on data transfer, refer to the following.
- Page 14 COMMUNICATION WITH A PERSONAL COMPUTER (GT DESIGNER3, DATA TRANSFER TOOL)
- 3. Select "SLMP" on the "Ethernet communication selection" screen of the LE7-40GU screen.



**4.** If you want to change the IP address of LE7-40GU (default: 192.168.3.18), change it on the "IP address setting" screen of the LE7-40GU screen.



**5.** If you want to change the SLMP station No. (default: 2), change it on the "SLMP station number" screen on the LE7-40GU screen.



6. Restart LE7-40GU.

#### Precautions

For SLMP communication, only the LE7-40GU station No. and IP address can be changed on the LE7-40GU screen. To change the port number or SLMP equipment communication settings, they must be set with GT Designer3 (GOT2000).

#### Setting with GT Designer3 (GOT2000)

- 1. Obtain the "Screen package data for SLMP communication" from your local Mitsubishi Electric representative.
- **2.** Open the "Screen package data for SLMP communication" in GT Designer3 (GOT2000) and change the settings of [Common] [Controller Setting] [CH2] as follows.

For details on the communication settings in GT Designer3 (GOT2000), refer to the following.

GOT2000 Series Connection Manual (Microcomputers, MODBUS/Fieldbus Products, Peripherals)

<Controller Setting>

Setting name	Setting detail
Manufacturer	CLPA
Controller Type	SLMP
I/F	Ethernet:Multi
Driver	Ethernet(SLMP), Gateway

#### <Detail setting>

Property	Value
GOT Net No.	1
GOT Station	2 to 7
GOT Communication Port No.	5031
Retry(Times)	3
Startup Time(Sec)	3
Timeout Time(Sec)	3
Delay Time(ms)	0
Message Format	4E frame
Communication deta code	Binary code
Device read points(Points)	960
Device write points(Points)	960
Device read random points(Points)	0
Device write random point(Points)	0

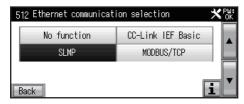
#### <Ethernet Controller Setting>

Setting name	Setting value
Net No.	1
Station	1
Unit tType	SLMP
IP Address	192.168.3.250
Port No.	49152
Communication	UDP

**3.** Transfer the "Screen package data for SLMP communication" to LE7-40GU with GT Designer3 (GOT2000). For more information on data transfer, refer to the following.

F Page 14 COMMUNICATION WITH A PERSONAL COMPUTER (GT DESIGNER3, DATA TRANSFER TOOL)

4. Select "SLMP" on the "Ethernet communication selection" screen of the LE7-40GU screen.



5. Restart LE7-40GU.

## Link data configuration

Link data of SLMP server equipment and LE7-40GU uses D100 to D179 of SLMP equipment D device.

SLMP server equipment—>LE7-40GU					
Device No. (server equipment)	Signal name				
D100	Station No. command				
D101	Input signal 0 to 15				
D102	Input signal 16 to 31				
D103	Input signal 32 to 47				
D104	Continuous settings 1				
D105	Continuous settings 2				
D106	Request command 0	Request code 0			
D107	Setting data 0				
D108	Request command 1	Request code 1			
D109	Setting data 1				

LE7-40GU→SLMP server equipment	LE7-40GU→SLMP server equipment					
Device No. (server equipment)	Signal name					
Dn	_					
Dn+1	Output signal 0 to 15					
Dn+2	Output signal 16 to 31					
Dn+3	Output signal 32 to 47					
Dn+4	Continuous monitor 1					
Dn+5	Continuous monitor 2					
Dn+6	Continuous monitor 3					
Dn+7	Setting monitor 4					
Dn+8	Request command 0 execution result					
Dn+9	Settings command 1 execution result					

<sup>\*1</sup> Dn switches according to the LE7-40GU SLMP station No. setting. (Station No. 1: D 110, Station No. 2: D 120 ··· Station No. 7: D 170)

### **Station Number command**

Determine the station No. of the LE7-40GU to be accessed by the station No. command of the SLMP equipment D device (D 106).

By setting the station No. command to 0, simultaneous settings can be done for all LE7-40GU units.

Station No. command	Function
1 to 7	Individual access to designated LE7-40GU
0	Simultaneous access to all LE7-40GU units

## Continuous setting/continuous monitoring

By simply turning on continuous settings execution (D103, b13) and continuous monitor execution (D103, b14) of SLMP equipment, preset data can be set and monitored continuously.

For continuous setting data, the data set for RAM writing is not stored during a power failure.

The latest data existing in LE7-40GU when the master station gives the send request can be monitored continuously. However, regarding the update of parameters for which the monitor update cycle is specified by the setting in LE7-40GU, the data is updated in the specified update cycle if the specified update cycle is longer than the monitor update cycle in the send request given by the master station.

## Access by request command

For any access to data in LE7-40GU from the SLMP equipment, data can be read and written by handshake between the "request command execution" flag and the "request command completion" flag.

Double word data from the SLMP equipment is used for this access.

This 2-word data is comprised of the request command, to which the upper 4 bits of the first word are assigned, and the request code, to which the lower 2 bits are assigned, and the setting data, to which the next word is assigned.

bit 15 to 12	bit 11 to 0
Request command	Request code
Setting data	

There are three types of request command, Data Monitor, Writing to RAM, and Writing to RAM + ROM, according to the selection of data reading and writing method.

Monitor	Writing to RAM	Writing to RAM + ROM
Writing data is reflected in the settings based on a	Writing data is reflected in the settings based on a	Execute data writing to the RAM + ROM (for
data read request from the SLMP equipment but is	data write request from the SLMP equipment but is	storage against power interruption).
not stored against power interruption.	not stored against power interruption.	

Since there is a limit on the number of writable times in the ROM for power failure storage, it is necessary to write the data where write updates are performed periodically from the PLC only to RAM.

Request command	Contents of execution	Execution result
Н0	Monitor	Monitored value
H1	Writing to RAM	Writing result
H2	Writing to RAM + ROM	Writing result

The request code indicates the data No. (address) of data for which the request command is executed. Also, the subsequent data setting is the data to be written to that data number.

If the request command is a monitor, the data setting data is ignored.

When double word data is written to send data in the SLMP equipment, and the handshake is executed by turning ON/OFF the request command execution flag and request command completion flag as follows, LE7-40GU sends back the request command execution result.

If an error occurs, triggered by the request command from the SLMP equipment, the local station turns ON the network alarm occurrence flag and outputs the device No. that has the error to the monitor of the device number of the network alarm.

- 1. SLMP compatible device executes request command (D103, b15) ON.
- 2. The LE7-40GU processes in accordance with the SLMP equipment request command execution ON.
- 3. LE7-40GU turns ON the request command completion.
- 4. The SLMP equipment receives request command completion (Dn+3, b15) ON.
- The SLMP equipment sets request command completion OFF.
- 6. The LE7-40GU receives request command execution OFF from the SLMP equipment.
- 7. LE7-40GU turns OFF the request command completion.
- **8.** The SLMP equipment receives turning OFF of the request command completion.

Please perform reading of the execution results of the request command between step 4 and 5 of the handshake procedure. For the request command execution result, refer to the following.

**LILE7-CCL APPLICATION MANUAL** 

# Request code

The numerical value of each parameter corresponding to the request code is treated as real number data without a decimal point.

In addition, the minimum and maximum values are determined for LE7-40GU, and when a value exceeding this data is written, it is automatically rewritten to the minimum or maximum value.

In this case, an "Out of data range" alarm is generated.

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H000(0)	_	_	_	_	_	_
H001(1)	Total tension	Monitor	_	0 or less	2000 or more	N/×10 N
H002(2)	Left tension	Monitor	_	0 or less	2000 or more	N/×10 N
H003(3)	Right tension	Monitor	_	0 or less	2000 or more	N/×10 N
H004(4)	Left input voltage	Monitor	_	-1500 or less	1500 or more	mV
H005(5)	Right input voltage	Monitor	_	-1500 or less	1500 or more	mV
H006(6)	_	_	_	_	_	_
H007(7)	_	_	_	_	_	_
H008(8)	_	_	_	_	_	_
H009(9)	_	_	_	_	_	_
H00A(10)	_	_	_	_	_	_
H00B(11)	_	_	_	_	_	_
H00C(12)	_	_	_	_	_	_
H00D(13)	_	_	_	_	_	_
H00E(14)	_	_	_	_	_	_
H00F(15)	_	_	_	_	_	_
H010(16)	Tension upper limit detection	Setting	_	0	Tension full scale	N/×10 N
H011(17)	Tension lower limit detection	Setting	_	0	Tension full scale	N/×10 N
H012(18)	Detection outside target tension range	Setting	_	0	50	%
H013(19)	Tension display filter	Setting	_	5	80	sec
H014(20)	Tension detection filter	Setting	_	0	80	sec
H015(21)	Tension output filter	Setting	_	0	80	sec
H016(22)	_	_	_	_	_	_
H017(23)	_	_	_	_	_	_
H018(24)	_	_	_	_	_	_
H019(25)	_	_	_	_	_	_
H01A(26)	_	_	_	_	_	_
H01B(27)	_	_	_	_	_	_
H01C(28)	_	_	_	_	_	_
H01D(29)	_	_	_	_	_	_
H01E(30)	_	_	_	_	_	_
H01F(31)	_	_	_	_	_	_
H020(32)	Sensor input type selection	Setting	_	0 (LX type), 1 (strain	gauge)	_
H021(33)	Tension full scale	Setting	_	1	2000	N/×10 N
H022(34)	Tension display decimal point selection	Setting	_	0 (1), 1 (0.1), 2 (0.01)	)	_
H023(35)	Tension display unit selection	Setting	_	0 (N), 1 (×10 N)		_
H024(36)	Span target tension	Setting	_	1	Tension full scale	N/×10 N
H025(37)	Left manual zero calibration	Setting	_	-999	999	N/×10 N
H026(38)	Right manual zero calibration	Setting	_	-999	999	N/×10 N
H027(39)	Left manual span calibration	Setting	_	50	300	%
H028(40)	Right manual span calibration	Setting	_	50	300	%
H029(41)	_	_	_	_	_	_
H02A(42)	_	_	_	_	_	_
H02B(43)	_	_	_	_	_	_

Request	Name	Monitor/	Extension	Minimum value	Maximum value	Unit
code		settings	option			
H02C(44)	_	_	_	_	_	_
H02D(45)	_	_	_	_	_	_
H02E(46)	_	_	_	_	_	_
H02F(47)	_	_	_	_	_	_
H030(48)	Reel diameter	Monitor	_	1	2000	mmφ
H031(49)	Target line velocity	Monitor	LE7-DCA	0	10000	m/min
H032(50)	Line acceleration	Monitor	LE7-DCA	0	50	m/min/sec
H033(51)	Measurement length/remaining length	Monitor	LE7-DCA	_	_	m
H034(52)	Reel rotational speed	Monitor	LE7-DCA	65000	1	r/min
H035(53)	New reel rotational speed	Monitor	LE7-DCA	3600	1	r/min
H036(54)	Constant slip ROTO speed command output	Monitor	LE7-DCA	1000	0.1	%
H037(55)	Predrive rotation speed command output	Monitor	LE7-DCA	1000	0.1	%
H038(56)	Predrive target rotation speed	Monitor	LE7-DCA	3600	1	r/min
H039(57)	Reel diameter CALC adapter ROM version	Monitor	LE7-DCA	999	0.01	_
H03A(58)	_	_	_	_	_	_
H03B(59)			_	_	_	_
H03C(60)	_	+-	_	_	_	_
H03D(61)			_		_	
H03E(62)	_			_	_	
H03F(63)	_	_	_	_	_	_
H040(64)	Initial diameter	Setting	LE7-DCA	1	2000	mmd
H041(65)	Material thickness	Setting	LE7-DCA	0	10000	mmφ
	Reel diameter detection 1		LE7-DCA	0	2000	μm
H042(66)		Setting	LE7-DCA	0	+	mm¢
H043(67)	Reel diameter detection 2	Setting		0	2000	mm¢
H044(68)	Reel diameter detection 3	Setting	LE7-DCA		2000	mmφ
H045(69)	Measurement/remaining length detection 1	Setting	LE7-DCA	0	65000	m
H046(70)	Measurement/remaining length detection 2	Setting	LE7-DCA	0	65000	m
H047(71)	Measurement/remaining length detection 3	Setting	LE7-DCA	0	65000	m
H048(72)	Accelerating judgment acceleration	Setting	LE7-DCA	0	10	m/min/sec
H049(73)	Reel rotational speed gain	Setting	LE7-DCA	0	150	%
H04A(74)	Reel rotational speed bias	Setting	LE7-DCA	0	100	%
H04B(75)	Reel rotational speed startup gain	Setting	LE7-DCA	1	5	Time (s)
H04C(76)	Reel rotational speed startup timer	Setting	LE7-DCA	0	10	sec
H04D(77)	Predrive time	Setting	LE7-DCA	0	200	sec
H04E(78)	Predrive bias	Setting	LE7-DCA	-10	10	%
H04F(79)		_	_		_	_
H050(80)	Maximum diameter	Setting	_	Minimum diameter	2000	mmφ
H051(81)	Minimum diameter	Setting		1	Maximum diameter	mmφ
H052(82)	Teaching speed	Setting	LE7-DCA	1	10000	m/min
H053(83)	Velocity electronic gear ratio	Setting	LE7-DCA	9000	18000	%
H054(84)	Reel selection	Setting	LE7-DCA	0(unwinding), 1(wind		_
H055(85)	Number of reel pulse	Setting	LE7-DCA	0 (1 pulse), 1 (2 puls pulses), 4 (16 pulses	es), 2 (4 pulses), 3 (8	_
H056(86)	Reel diameter calculation cycle	Setting	LE7-DCA	0 (1 pulse), 1 (2 puls pulses), 4 (16 pulses	es), 2 (4 pulses), 3 (8	_
H057(87)	MEAS/RMN length calculation switch	Setting	LE7-DCA	0 (measurement leng length)	gth), 1 (remaining	_
H058(88)	Material thickness unit	Setting	LE7-DCA	0 (×1), 1 (×0.1)		_
H059(89)	Maximum line acceleration	Setting	LE7-DCA	1	50	m/min/sec
H05A(90)	Maximum reel rotational speed	Setting	LE7-DCA	1	3600	r/min
H05B(91)	Detection output selection	Setting	LE7-DCA	0 (Reel diameter), (n	neasurement length/	_
H05C(92)	Detection output holding selection	Setting	LE7-DCA	0 (non-holding), 1 (he	olding)	_
- (/	1 3	1 3	1	,	J,	1

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H05D(93)	Run/Stop judgment selection	Setting	LE7-DCA	0 (contact + internal), (internal)	1 (contact), 2	_
H05E(94)	Run judgment speed	Setting	LE7-DCA	Stop judgment speed	30	m/min
H05F(95)	Stop judgment speed	Setting	LE7-DCA	1	Run judgment speed	m/min
H060(96)	_	_	_	_	_	_
H061(97)	_	_	_	_	_	_
H062(98)	_	_	_	_	_	_
H063(99)	_	_	_	_	_	_
H064(100)	_	_	_	_	_	_
H065(101)	_	_	_	_	_	_
H066(102)	_	_	_	_	_	_
H067(103)	_	_	_	_	_	_
H068(104)	_	_	_	_	_	_
H069(105)	_	_	_	_	_	_
H06A(106)	_	_	_	_	_	_
H06B(107)	_	_	_	_	_	_
H06C(108)	_	_	_	_	_	_
H06D(109)	_	_	_	_	_	_
H06E(110)	_	_	_	_	_	_
H06F(111)		_	_	_	_	_
H070(112)	Target tension	Monitor	_	0	2000	N/×10 N
H071(113)	Control output	Monitor	_	-1000 or less	1000 or more	%
H072(114)	Torque output	Monitor	_	-1000 or less	1000 or more	%
H073(115)		- Worldon	_	-1000 of less	—	70
H074(116)	_		_			
H075(117)	Control output voltage for powder	Monitor	_	260 or more	0.1	V
	Control output voltage for powder  Control output current for powder	Monitor		400 or more	0.01	A
H076(118) H077(119)	—	—		—	_	A
			-  -	_		
H078(120)	_	<u> </u>	_	-	_	_
H079(121)			_	-	_	_
H07A(122)	_	<u> </u>	<del>-</del>	_	_	_
H07B(123)				_	_	_
H07C(124)		<u> </u>	_	<u> </u>	_	_ 
H07D(125)			_		_	1
H07E(126)	_		_	_	_	_
H07F(127)			_	_	—	- N/V/40 N/
H080(128)	Tension setting	Setting	_	1	Tension full scale	N/×10 N
H081(129)	Manual setting	Setting	_	-1000	1000	%
H082(130)	Stall setting	Setting	-	0	1000	%
H083(131)	Start timer	Setting	_	0	300	sec
H084(132)	Stop timer	Setting	_	0	1000	sec
H085(133)	Stop gain	Setting	-	5	400	%
H086(134)	Stop bias	Setting	_	0	100	%
H087(135)	Acceleration/deceleration torque setting	Setting	LE7-DCA	0	1000	%
H088(136)	Gain 1	Setting	_	5	400	%
H089(137)	Gain 2	Setting	_	5	400	%
H08A(138)	Internal taper ratio	Setting	_	0	80	%
H08B(139)	External linear line taper ratio	Setting	_	0	100	%
H08C(140)	New reel preset	Setting	_	0	1000	%
H08D(141)	New reel preset timer	Setting	_	0	300	sec
H08E(142)	Cutting torque	Setting	_	0	1000	%

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H08F(143)	_			_	_	_
H090(144)	Broken line taper corner 1	Setting	_	1	2000	mmφ
H091(145)	Broken line taper ratio 1	Setting	_	0	100	%
H092(146)	Broken line taper corner 2	Setting	_	1	2000	mmφ
H093(147)	Broken line taper ratio 2	Setting	_	0	100	%
H094(148)	Broken line taper ratio 2  Broken line taper corner 3	Setting	_	1	2000	mmφ
H095(149)	Broken line taper ratio 3	Setting	_	0	100	%
H096(150)	Broken line taper ratio 3	Setting	_	1	2000	mmφ
H097(151)	Broken line taper ratio 4	Setting	_	0	100	%
H098(152)	Broken line taper corner 5	Setting	_	1	2000	mmφ
	<u>'</u>		_	0	100	%
H099(153)	Broken line taper ratio 5	Setting				
H09A(154)	Broken line taper corner 6	Setting	_	1	2000	mmφ
H09B(155)	Broken line taper ratio 6	Setting	_	0	100	%
H09C(156)	Broken line taper corner 7	Setting	_	1	2000	mmφ
H09D(157)	Broken line taper ratio 7	Setting	_	0	100	%
H09E(158)	Broken line taper corner 8	Setting	_	1	2000	mmφ
H09F(159)	Broken line taper ratio 8	Setting	_	0	100	%
H0A0(160)	Proportional gain	Setting	_	0	100	%
H0A1(161)	Integral time	Setting	_	0	100	%
H0A2(162)	Dead band gain	Setting	_	0	100 - Proportional gain	%
H0A3(163)	Dead band width	Setting	_	0	100	%
H0A4(164)	Tension control filter	Setting	_	0	40	sec
H0A5(165)	Static mechanical loss A	Setting	_	-1000	1000	%
H0A6(166)	Static mechanical loss B	Setting	_	-1000	1000	%
H0A7(167)	Kinetic mechanical loss A	Setting	LE7-DCA	-1000	1000	%
H0A8(168)	Kinetic mechanical loss B	Setting	LE7-DCA	-1000	1000	%
H0A9(169)	Mass correction gain A	Setting	LE7-DCA	0	100	%
H0AA(170)	Mass correction gain B	Setting	LE7-DCA	0	100	%
H0AB(171)	Mass correction bias A	Setting	LE7-DCA	0	100	%
H0AC(172)	Mass correction bias B	Setting	LE7-DCA	0	100	%
H0AD(173)	_	_	_	_	_	_
H0AE(174)	_	_	_	_	_	_
H0AF(175)	_	_	_	_	_	_
H0B0(176)	Control mode selection	Setting	LE7-DCA	0 (feedback control),	1 (open loop control)	_
H0B1(177)	Integral feedback limit	Setting	_	0	101	%
H0B2(178)	Feedback selection during the stop timer	Setting	_	0 (invalid), 1 (valid)		_
H0B3(179)	Automatic control output polarity selection	Setting	_	0 (forward), 1 (revers	e)	_
H0B4(180)	Open-loop control ratio	Setting	LE7-DCA	0	100	%
H0B5(181)	Taper function selection	Setting	_	0 (no function), 1 (intelline taper (external)), (external)), 4 (direct ta	3 (broken line taper	_
H0B6(182)	Selection of two reel's switching FUNC	Setting	_	0 (invalid), 1 (valid)		_
H0B7(183)	Internal taper standard selection	Setting	_	0 (zero standard), 1 (	stall standard)	_
H0B8(184)	_	_	_	_	_	_
H0B9(185)	Mechanical loss function selection	Setting	LE7-DCA	0 (fixed mechanical lo mechanical loss)	oss), 1 (high function	_
H0BA(186)	Stall automatic calculation gain	Setting	LE7-DCA	0	100	%
H0BB(187)	New reel preset AUTO calculation gain	Setting	LE7-DCA	0	100	%
H0BC(188)	Control output upper limit	Setting	-	Control output lower limit	101	%
H0BD(189)	Control output lower limit	Setting	-	-101	Control output upper limit	%
H0BE(190)	_	_	_	_	_	_
	1		1	1	I	1

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H0BF(191)	_	_	_	_	_	_
H0C0(192)	Load model	Setting	_	0	200	_
H0C1(193)	Rated current	Setting	_	0	400	A
H0C2(194)	Maximum torque correction	Setting	_	50	250	%
H0C3(195)	Nonlinear correction 0	Setting	_	0	1000	%
H0C4(196)	Nonlinear correction 10	Setting	_	0	1000	%
H0C5(197)	Nonlinear correction 20	Setting	_	0	1000	%
H0C6(198)	Nonlinear correction 30	Setting	_	0	1000	%
H0C7(199)	Nonlinear correction 40	Setting	_	0	1000	%
H0C8(200)	Nonlinear correction 50	Setting	_	0	1000	%
H0C9(201)	Nonlinear correction 60	Setting	_	0	1000	%
H0CA(202)	Nonlinear correction 70	Setting	_	0	1000	%
H0CB(203)	Nonlinear correction 80	Setting	_	0	1000	%
H0CC(204)	Nonlinear correction 90	Setting	_	0	1000	%
H0CD(205)	_	_	_	_	_	_
H0CE(206)	_	_	_		_	_
H0CF(207)	_	_	_	_	_	_
H0D0(208)	_	_	_	_	_	_
H0D1(209)	Weak excitation	Setting		0	1000	%
H0D2(210)	Over current detection filter	Setting	_	0	20	sec
H0D3(211)	—	_	_	_	_	_
H0D4(212)	_	_	_	_		
H0D5(213)	_	_	_	_		
H0D6(214)	_	_	_	_		
H0D7(215)	_	_	_		_	
H0D8(216)	_	_			_	
H0D9(217)	_	_			_	
H0DA(218)	_	_	_			
H0DB(219)	_	_	_			
H0DC(220)	_	_	_			
H0DD(221)	_	_	_			
H0DE(222)	_	_	_			
H0DF(223)	_	_	_		_	
H0E0(224)	Contact input monitor	Monitor	_	0	0xFFFF	
H0E1(225)	Contact input monitor	Monitor	_	0	0xFFFF	
H0E2(226)	General-purpose analog input 1 monitor	Monitor	_	0	100	%
H0E3(227)	General-purpose analog input 2 monitor	Monitor	_	0	100	%
H0E4(228)	General-purpose analog input 3 monitor	Monitor	_	0	100	%
H0E5(229)	General-purpose analog output 1 monitor	Monitor	_	0	100	%
H0E6(230)	General-purpose analog output 1 monitor	Monitor	_	0	100	%
H0E7(231)	Analog output monitor for TENS control	Monitor	_	0	100	%
			_	0	100	%
H0E8(232) H0E9(233)	Analog output monitor for new reel preset  Contact input monitor for reel DIA CALC	Monitor Monitor	LE7-DCA	0	0xFFFF	
H0E9(233)	Contact input monitor for reel DIA CALC  Contact output monitor for reel DIA CALC	Monitor	LE7-DCA	0	0xFFFF	_
H0EB(235)	Alarm display	Monitor	—	0	63	_
	Network alarm device No.	Monitor	<del>-</del>	0	999	<del> </del>
H0EC(236)	Main unit ROM version	Monitor	_ 	0	999	<del>  </del>
H0ED(237) H0EE(238)		Monitor	LE7-CCL	0	999	<del>  </del>
	Network adapter ROM version  Communication signal monitor			0	0xFFFF	_
H0EF(239)	Communication signal monitor	Monitor	L	١٠	VALLE	

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H0F0(240)	Contact input 1 function selection	Setting	_	0 (no function), 1 (rur		_
H0F1(241)	Contact input 2 function selection	Setting	_	output OFF/ON), 3 (s	_	
H0F2(242)	Contact input 3 function selection	Setting	_	<ul><li>(inching ON/OFF), 5</li><li>OFF), 6 (gain 1 ON/O</li></ul>	_	
H0F3(243)	Contact input 4 function selection	Setting	_	- · · · · · · · · · · · · · · · · · · ·	anual), 9 (reel change	_
H0F4(244)	Contact input 5 function selection	Setting	_	ON/OFF), 10 (cut toro		_
H0F5(245)	Contact input 6 function selection	Setting	_	(alarm reset ON/OFF	)	_
H0F6(246)	_	_	_	_	_	_
H0F7(247)	_	_	_	_	_	_
H0F8(248)	Contact output 1 function selection	Setting	_	0 (no function), 1 (ter	sion lower limit	_
H0F9(249)	Contact output 2 function selection	Setting	_	detection), 2 (tension 3 (detection outside t (alarm occurrence de	• ,.	_
H0FA(250)	_	_	_	_	_	_
H0FB(251)	_	_	_	_	_	_
H0FC(252)		_	_	_	_	_
H0FD(253)	_	_	_	_	_	_
H0FE(254)	_	_	_	_	_	_
H0FF(255)	_	_	_	_	_	_
H100(256)	Analog input mode selection	Setting	_	0 (0 to 5 V mode), 1 (	0 to 10 V mode)	_
H101(257)	Analog input 1 function selection	Setting	_	0 (no function), 1 (ten	•	_
H102(258)	Analog input 2 function selection	Setting	_	setting), 3 (straight lir	• , ,	
H103(259)	Analog input 3 function selection	Setting	_	4 (new axis preset setting), 5 (manual setting), 6 (tension input), 7 (Reel diameter input)		_
H104(260)	_	_	_	_	_	_
H105(261)	_		_	_	_	_
H106(262)	_		_	_	_	_
H107(263)	_		_	_	_	_
H108(264)	Analog output mode selection	Setting	_	0 (0 to 5 V mode), 1 (	(0 to 10 V mode)	_
H109(265)	Analog output 1 function selection	Setting	_		sion monitor), 2 (Reel	_
H10A(266)	Analog output 2 function selection	Setting	_	diameter monitor), 3 monitor), 4 (A-axis Ro speed output), 5 (B-a rotational speed outp	tension setting eel shaft rotational xis Reel shaft	_
H10B(267)	Analog output 1 gain	Setting	_	500	3000	%
H10C(268)	Analog output 2 gain	Setting	_	500	3000	%
H10D(269)	Analog output 1 bias	Setting	_	-500	500	%
H10E(270)	Analog output 2 bias	Setting	_	-500	500	%
H10F(271)	_	_	_	_	_	_
H110(272)	Two reel's switching FUNC output mode	Setting	_	0 (no internal switchin switching)	ng), 1 (with internal	_
H111(273)	Control output mode selection	Setting	_	0 (0 to 5 V mode), 1 (-5 to 5 V mode), 2 (0 to 10 V mode), 3 (-10 to 10 V mode), 4 (0 to 8 V mode), 5 (-8 to 8 V mode), 6 (0 to 2.7 V mode), 7 (-2.7 to 2.7 V mode), 8 (1 to 5 V mode)		_
H112(274)	Control output gain	Setting	_	500	3000	%
H113(275)	New reel preset output gain	Setting	_	500	3000	%
H114(276)	Control output bias	Setting	_	-500	500	%
H115(277)	New reel preset output bias	Setting	_	-500	500	%
H116(278)	_	_	_	_	_	_
H117(279)	_	_	_	_	_	_
H118(280)	_	_	_	_	_	_
(= )						
	_	_	_	_	_	_
H119(281) H11A(282)	_ _	<u> </u>	_	-  -	_	_

H11D(285) - H11E(286) - H11F(287) -	_					
H11E(286) -		_	_	_	_	_
H11F(287) -		_	_	_	_	_
	_	_	_	_	_	_
11400(000)	_	_	_	_	_	_
H120(288)	Set setting password	Setting	_	0	32000	_
H121(289)	Input setting password	Setting	_	0	32000	_
H122(290) S	Set monitor password	Setting	_	0	32000	_
H123(291)	Input monitor password	Setting	_	0	32000	_
	_	_	_	_	_	_
	_	_	_	_	_	_
H126(294) -	_	_	_	_	_	_
	_	_	_	_	_	_
	_	_	_	_	_	_
· ' '	_	_	_	_	_	_
· ' '	_	_	_	_	_	_
	_	_	_	_	_	_
	_	_	_	_	_	_
			_	_		
25(00.1)	_		_	_	_	
=(00=)	_	_		_	_	_
11121 (000)			_	_	_	_
	Alarm history 1	Monitor	_	0	63	_
	Alarm history 2	Monitor	_	0	63	_
	Alarm history 3	Monitor	_	0	63	_
	Alarm history 4	Monitor	_	0	63	_
	Alarm history 5	Monitor	_	0	63	_
H135(309)	Alarm history 6	Monitor	_	0	63	_
H136(310)	Alarm history 7	Monitor	_	0	63	_
H137(311)	Alarm history 8	Monitor	_	0	63	_
H138(312)	Alarm history holding selection	Setting	_	0 (no holding), 1 (hold	ling)	_
H139(313)	Alarm display time	Setting	_	0	301	sec
H13A(314)	Alarm operation selection 1	Setting	_	0	0xFFFF	_
H13B(315)	Alarm operation selection 2	Setting	_	0	0xFFFF	_
H13C(316)	Alarm operation selection 3	Setting	_	0	0xFFFF	_
H13D(317)	Alarm operation selection 4	Setting	_	0	0xFFFF	_
H13E(318) -	_	_	_	_	_	_
H13F(319) -	_	_	_	_	_	_
H140(320) -	_	_	_	_	_	_
H141(321) -	_	_	_	_	_	_
H142(322) -	_	_	_	_	_	_
H143(323) -	_	_	_	_	_	_
H144(324) -	_	_	_	_	_	_
	_	_	_	_	_	_
	_	_	_	_	_	_
	_	_	_	_	_	_
	_	_	_	_	_	_
	_	_	_	_	_	_
	_	_	_	_	_	_
	_	_	_	_		_
	_	_	_	_	_	_
	_	_	_	_	_	_
	_	_	_	_	_	_
	_		_	_	_	_

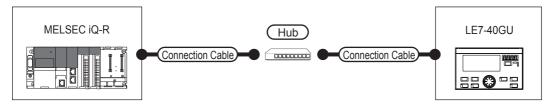
Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H150(336)	_	_	_	_	_	_
H151(337)	_	_	_	_	_	_
H152(338)	_	_	_	_	_	_
H153(339)	_	_	_	_	_	_
H154(340)	_	_	_	_	_	_
H155(341)	_	_	_	_	_	_
H156(342)	_	_	_	_	_	_
H157(343)	_	_	_	_	_	_
H158(344)	_	_	_	_	_	_
H159(345)	_	_	_	_	_	_
H15A(346)	_	_	_	_	_	_
H15B(347)	_	_	_	_	_	_
H15C(348)	_	_	_	_	_	_
H15D(349)	_	_	_	_	_	_
H15E(350)	_	_	_	_	_	_
H15F(351)	_	_	_	_	_	_
H160(352)	_	_	_	_	_	_
H161(353)	_	_	_	_	_	_
H162(354)	_	_	_	_	_	_
H163(355)	_	_	_	_	_	_
H164(356)	_	_	_	_	_	_
	_		_	_	_	_
H165(357)	_		_	-  -	-  -	
H166(358)						-  -
H167(359)	_	_	_	_	_	_
H168(360)	_	_	_	_	_	_
H169(361)	_		_	_	-	_
H16A(362)	_	_	_	_	_	_
H16B(363)	_	_	_	_	_	_
H16C(364)	_		_	_	_	_
H16D(365)	_	_	_	_	_	_
H16E(366)	_	_	_	_	_	_
H16F(367)	_	_	_	_	_	_
H170(368)	_	_	_	_	_	_
H171(369)	_	_	_	_	_	_
H172 (370)	_	_	_	_	_	_
H173(371)	_	_	_	_	_	_
H174(372)	_	_	_	_	_	_
H175(373)	_	_	_	_	_	_
H176(374)	_	_	_	_	_	_
H177(375)	_	_	_	_	_	_
H178(376)	_	_	_	_	_	_
H179(377)	_	_	_	_	_	_
H17A(378)	_	_	_	_	_	_
H17B(379)	_	_	_	_	_	_
H17C(380)	_	_	_	_	_	_
H17D(381)	_	_	_	_	_	_
H17E(382)	_	_	_	_	_	_
H17F(383)	_	_	_	_	_	_
H180(384)	Open-loop control base torque	Setting	LE7-DCA	0	1000	%
H181(385)	Direct taper ratio	Setting	_	0	1000	%
H182(386)	Link tension monitor filter	Setting	_	0	80	sec
H183(387)	Tension input	Setting	<del>-</del>	0	2000	N/×10 N

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H184(388)	Reel diameter input	Setting	_	0	2000	mmφ
H185(389)	_	_	_	_	_	_
H186(390)	_	_	_	_	_	_
H187(391)	_	_	_	_	_	_
H188(392)	_	_	_	_	_	_
H189(393)	_	_	_	_	_	_
H18A(394)	_	_	_	_	_	_
H18B(395)	_	_	_	_	_	_
H18C(396)	_	_	_	_	_	_
H18D(397)	_	_	_	_	_	_
H18E(398)	_	_	_	_	_	_
H18F(399)	_	_	_	_	_	_

# 4.3 Reference Program

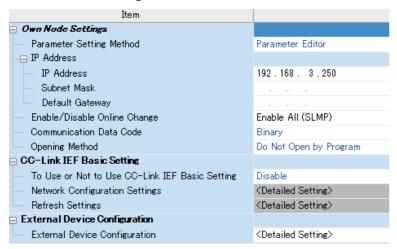
A basic example program (GX Works3) for SLMP communication is described.

#### System configuration



#### Parameter settings

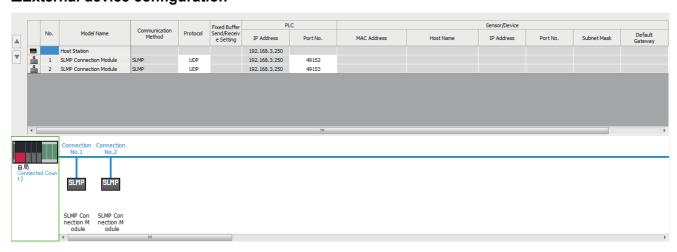
#### **■**Own node settings



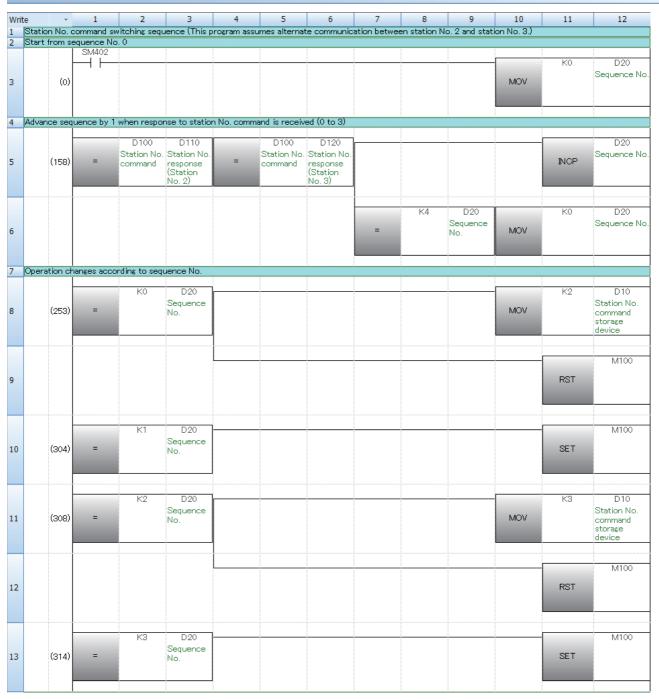
#### **■CC-Link IEF Basic setting**

To use or not use CC-Link IEF Basic setting: Disable

#### **■**External device configuration



#### **Program example**



15 (318)	1 12	11	10	9	8	7	6	5	4	3	2	1	*	Writ
15											ation		ation No. d	14
15												SM400		
16		D10										$\vdash\vdash\vdash$		
16		Station No.			1									
16		command		+									(318)	15
17	9	storage												
17		aevice			1									
17											ļ			
17	IO ZO	K10	D11											
17			Station No.		1									
18 Station No. offset  D11 H Station No. offset  19 Station No. command change  M100  MOV Static commister adevice				*	1									16
18 Station No. offset  D11 H Station No. offset  19 Station No. command change  M100  H   MOV   Station Storal device   MOV   MOV   Station Storal device   MOV   MOV   Station Storal device   MOV														
18 Station No. offset  D11 H Station No. offset  19 Station No. command change  M100  MOV Static commister adevice					L									
18 Station No. offset  D11 H Station No. offset  19 Station No. command change  M100  MOV Static commister adevice	<u>i</u>													
18  D11 H Station No. command change  M100  MOV Static communications of the storal device of	10 Z1	H10	D11											
19 Station No. command change  20 (363)    M100					1									
18 * Station No. offset  19 Station No. command change  20 (363)  MOV Static communication and evice storal device			offset	*										17
18 * Station No. offset  19 Station No. command change  20 (363)  MOV Static communication and evice storal device														
18 * Station No. offset  19 Station No. command change  20 (363)  MOV Static communication and evice storal device														
18 * Station No. offset  19 Station No. command change  20 (363)  MOV Static communication and evice storal device														
19 Station No. command change  20 (363)  MOV Static command change	A0 Z2	НОДО												
19 Station No. command change  20 (363)  M100  MOV Station of the command change of the					1									
20 (363) M100 Common stora device			offset	*	1									18
20 (363) M100 Common stora device														
20 (363) M100 Common stora device					1									
20 (363) MOV Static commissions adevice			<u> </u>				·			·	nange		ation No. o	19
20 (363) MOV Static communications and device states are device states and device states and device states are device states and device states and device states are device states and device states and device states are device states and device states and device states are device states and device states and device states are device states and device states and device states are device states are device states and device states are device states are device states and device states are device st	10 D100	D10										M100		
20 (363) MOV commistora device														
stora devic		Station No.											(363)	20
devic		storage	1010 0										(000)	20
	*	device												
L M100														
		124										M100		
		K1										$\vdash$ $\vdash$ $\vdash$		
21 (394) MOV	Station No.		MOV										(204)	21
E1 (094)	command		NO										(394)	21

22 *Request command access processing  M100	MOV	D200Z0 Request command 0 + request code 0	D106 Link data 6 (Partner station)
23 (397) Request command being		Request command 0 + request code 0	Link data 6 (Partner
Request command being		Request command 0 + request code 0	Link data 6 (Partner
command being		command 0 + request code 0	(Partner
command being		+ request code 0	
being	MOV	code 0	stationy
	MOV		
	MOV		
	MOV		
	MOV	D201Z0	D107
		Setting data	
24	IVIOV	0	(Partner station)
			station)
			i
	-	D202Z0	D108
25	MOV	Request	Link data 8
	IVIOV	command 1 + request	(Own station)
		code 1	
			D109
		D203Z0 Setting data	
26	MOV	Setting data	(Own station)
			Commiscations
		_	D103.F
			Request
27		SET	command
			execution
X20Z1			
		-	D103.F
			Request
28		RST	command
			execution
X20Z1 D113.FZ1			
		D118Z0	D204Z0
(100)	MOV	Link data 8	Request
29 (421) Request	MOV	(Partner station)	command 0 execution
command being		station)	result
executed			1
		D119Z0	D205Z0
30	MOV	Link data 9	Request
	IVIOV	(Partner station)	command 1 execution
			result

Write	-	1	2	3	4	5	6	7	8	9	10	11	12
31  *Co	ntinuous	monitor pr M100	X21Z1										
32	(433)	<del> </del> / <del> </del>										SET	D103.E Continuous monitor execution
33			X21Z1									RST	D103.E Continuous monitor execution
34	(443)	X21Z1 —    —									моч	D114Z0 Link data 4 (Partner station)	D300Z0 Continuous monitor 1 (Total tension)
35											МОУ	D115Z0 Link data 5 (Partner station)	D301Z0 Continuous monitor 2 (Target tension)
36											MOV	D116Z0 Link data 6 (Partner station)	D302Z0 Continuous monitor 3 (Control output)
37											MOV	D117Z0 Link data 7 (Partner station)	D303Z0 Continuous monitor 4 (Alarm display)
38 *Co	ntinuous	settings pr					<u> </u>		<u> </u>				
39	(461)	M100	X22Z1								MOV	D400Z0 Continuous settings 1 (Tension setting)	D104 Link data 4 (Own station)
40											моу	D401Z0 Continuous settings 2 (Manual setting)	D105 Link data 5 (Own station)
41												SET	D103.D Continuous settings execution
42			X22Z1									RST	D103.D Continuous settings execution

Writ		2	3	4	5	6	7	8	9	10	11	12
43	*Feedback control seque   M100 	X23Z1	sing									D101.3
44	(477)										SET	Auto/Manual
45			X24Z1 								SET	D101.0 Run/Stop
			X24Z1									D101.0 Run/Stop
46		X23Z1									RST	Tai / Stop
47		X23Z1									RST	D101.0 Run/Stop
48											RST	D101.3 Auto/Manual
49	*Status monitoring proce	essing										
50	D111.0Z2 —     —   (496)   Run/Stop											Y30Z1
51	D111.8Z2											Y31Z1
31	(501) Manual control											Y32Z1
52	(505) Automatic control											
53	D111.AZ2  (509) Auto lamp flicker in operation/											Y33Z1
54	stopped D113.FZ2											Y34Z1
	command being executed D113.EZ2											Y35Z1
55	(517) Continuou s monitor beins executed D113.DZ2											Y36Z1
56	(521) Continuou s settings being											
57	executed (525)											[END ]

#### **Ladder Operation**

Operation is changed depending on the sequence No. When the PLC is started, the sequence No. 1 is set, and the station No. command is changed as the following table (station No. 1). When the station No. response (station No. 2) and the station No. response (station No. 3) match with the station No. command, the sequence No. increases by one. When the process up to sequence No. 3 is complete, the number returns to 0.

Sequence No.	Station No.	Station No.	Station No.	Available		Description
(D20)	command (D100)	offset (D10)	command being changed (M100)	Setting	Monitoring	
0	1	2	OFF	0	0	Change the setting value of station No. 2.
1	2	2	ON	×	0	Change the station No. command to 2. Setting value is reflected.
2	1	3	OFF	0	0	Change the setting value of station No. 3.
3	3	3	ON	×	0	Change the station No. command to 3. Setting value is reflected.

## Using method of ladder

List of used devices (The allocation is an example.)

Device name		Classification*1	Allocation function	Use	
Station No. 2	Station No. 3				
D200 to D203	D210 to D213	Setting	Request command + request code/data setting 1 to 2	Device set to use the request command	
D204 to D205	D214 to D215	Setting	Request command execution result 1 to 2	Request command execution result is stored.	
D300 to D303	D310 to D313	Setting	Continuous monitor 1 to 4	Continuous monitor execution result is stored.	
D400 to D401	D410 to D413	Setting	Continuous setting 1 to 2	Setting value of continuous setting is stored.	
X20	X30	Setting	Start request command access execution	Execute request command.	
X21	X31	Setting	Start continuous monitor execution	Start to execute continuous monitor.	
X22	X32	Setting	Start continuous setting execution	Start to execute continuous setting.	
X23	X33	Setting	Start stall execution	Start to execute stall.	
X24	X34	Monitoring Start operation		Start to operate.	
Y30	Y40	Monitoring	Run	Run: ON/Stop: OFF	
Y31	Y41	Monitoring	Manual control	Manual control ON	
Y32	Y42	Monitoring	Automatic control	Automatic control ON	
Y33	Y43	Monitoring	Auto lamp flicker in operation	Auto lamp flicker in operation ON	
Y34	Y44	Monitoring	Request command completion	ON when request command is completed	
Y35	Y45	Monitoring	Continuous monitor being executed	ON when continuous monitor is being executed.	
Y36	Y46	Monitoring	Continuous settings being executed	ON when continuous setting is being executed.	
D100 to D109		System	Link data (Station No. 1)	Setting items such as input signal are stored.	
D110 to D119		System	Link data (Station No. 2)	Monitored item from station No. 2 is stored.	
D120 to D129		System	Link data (Station No. 3)	Monitored item from station No. 3 is stored.	
D20		System	Sequence No.	Processing is changed by the sequence No.	
M100		System	Station No. command being changed	Turn ON when the station No. command is being written.	
D10		System	Station No. command storage device	Offset the device according to the station No.	
D11		System	Station No. offset	Used to offset the device	

<sup>\*1</sup> Classification

Setting: items to be set/input when using functions

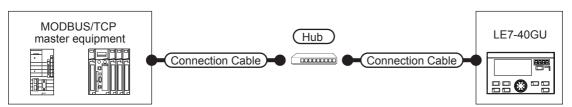
Monitoring: items to monitor output when using functions

System: Used for internal processing, setting is unnecessary

# 5 MODBUS/TCP (SLAVE)

Since LE7-40GU supports the slave function of MODBUS/TCP communication which is an open FA network, it can communicate with various MODBUS/TCP master equipment. Also, LE7-40GU (as a slave station) can perform data monitoring and parameter writing from up to four master stations.

# 5.1 System Configuration



Connection	Communic	Connection ca	able	External	Connection ca	able	Tension cor	troller*2	Number of
equipment	ation form	Cable type name*4	Maximum segment length*3	device	Cable type name*4	Maximum segment length*3	Optional equipment	Main unit	connectable devices
MODBUS/ TCP master device	Ethernet	100BASE-TX Category 5 or more of shield twisted pair cable (STP) or unshielded twisted pair cable (UTP)     10BASE-T Category 3 or more of shield twisted pair cable (STP) or unshielded twisted pair cable (UTP)  unshielded twisted pair cable (UTP)	100 m	Hub* <sup>1</sup>	100BASE-TX Category 5 or more of shield twisted pair cable (STP) or unshielded twisted pair cable (UTP)     10BASE-T Category 3 or more of shield twisted pair cable (STP) or unshielded twisted pair cable (WTP)  total (STP) or unshielded twisted pair cable (UTP)	100 m	— (Built-in to main unit)	LE7-40GU	Master equipment: When LE7- 40GU is N:1, four or less master equipment for one LE7- 40GU) Master equipment: When LE7- 40GU is 1:N, the following number of LE7- 40GU units for one master device. Depending on the MODBUS/ TCP master equipment used*5

- \*1 Connect with MODBUS/TCP master equipment via a hub.
  - Use cables, connectors, and hubs that satisfy the IEEE 802.3 10BASE-T/100BASE-TX/1000BASE-T standard.
- \*2 When connecting LE7-40GU to 10BASE (-T/2/5) compliant equipment, please use it in a network environment where 10 Mbps/100 Mbps can be mixed using a switching hub.
- \*3 This is the length between the hub and the node.

The maximum distance depends on the Ethernet device used.

When using a repeater hub, the number of units that can be connected is as follows.

- · 10BASE-T: Cascade connection up to 4 units (500 m)
- · 100BASE-TX: Cascade connection up to 2 units (205 m)

When using a switching hub, the cascade connection between switching hubs has no theoretical limit on the number that can be cascaded.

Please check with the manufacturer of the switching hub used for any restrictions.

- \*4 For the twisted pair cable, please use a straight cable.
- \*5 For details, refer to the manual of the MODBUS/TCP master equipment used.

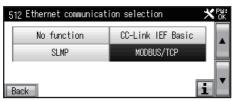
# **5.2** Communication Setting

# **Communication parameter settings**

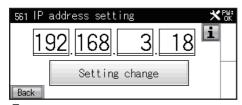
When using MODBUS/TCP communication (slave), set the communication parameters with the following procedure.

#### **Setting with Data Transfer Tool**

- 1. Obtain the "Screen package data for MODBUS/TCP" from your local Mitsubishi Electric representative.
- **2.** Transfer the "Screen package data for MODBUS/TCP" to LE7-40GU with Data Transfer Tool (for GT Works3). For more information on data transfer, refer to the following.
- Page 14 COMMUNICATION WITH A PERSONAL COMPUTER (GT DESIGNER3, DATA TRANSFER TOOL)
- 3. Select "MODBUS/TCP" on the "Ethernet communication selection" screen of the LE7-40GU screen.



**4.** If you want to change the IP address of LE7-40GU (default: 192.168.3.18), change it on the "IP address setting" screen of the LE7-40GU screen.



Restart LE7-40GU.

#### **Precautions**

For MODBUS/TCP communication, only the IP address can be changed on the LE7-40GU screen.

To change the port number, it must be set in GT Designer3 (GOT2000).

#### Setting with GT Designer3 (GOT2000)

- 1. Obtain the "Screen package data for MODBUS/TCP" from your local Mitsubishi Electric representative.
- **2.** Open the "Screen package data for MODBUS/TCP" in GT Designer3 (GOT2000) and change the settings of [Common] [Controller Settings] [CH2] as follows.

For details on the communication settings in GT Designer3 (GOT2000), refer to the following.

GOT2000 Series Connection Manual (Microcomputers, MODBUS/Fieldbus Products, Peripherals)

<Controller Setting>

Setting name	Setting detail
Manufacturer	MODBUS
Controller Type	MODBUS Slave
I/F	Ethernet:Multi
Driver	MODBUS/TCP Slave, Gateway

#### <Detail setting>

Property	Value
GOT Net No.	0 (Fixed)
GOT Station	255 (Fixed)
GOT Communication Port No.	502 (Optional)
Delay Time(ms)	0
32bit Storage	LH Order

3. Change the settings of [Common] - [GOT Ethernet Setting] - [GOT IP Address Setting] as follows.

For details on the communication settings in GT Designer3 (GOT2000), refer to the following.

 $\begin{tabular}{l} $\square$ GOT2000 Series Connection Manual (Microcomputers, MODBUS/Fieldbus Products, Peripherals) \end{tabular}$ 

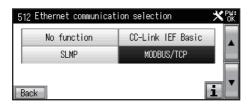
<GOT IP Address Setting>

Setting name	Setting value
GOT IP Address	192.168.3.18 (optional)

4. Transfer the "Screen package data for MODBUS/TCP" to LE7-40GU with GT Designer3 (GOT2000).

For more information on data transfer, refer to the following.

- Page 14 COMMUNICATION WITH A PERSONAL COMPUTER (GT DESIGNER3, DATA TRANSFER TOOL)
- 5. Select "MODBUS/TCP" on the "Ethernet communication selection" screen of the LE7-40GU screen.



6. Restart LE7-40GU.

# Bit device

The input relay (1) and the coil (0) each have 48 points. The remaining area becomes non-functioning and cannot be used.

• Input relay (1) (Master station→Slave station)

Device No.	Signal name	Signal name ON (data value=1)	OFF (data value=0)
100001	Run/Stop	Run	Stop
100002	Reel change B axis/A axis	B axis control	A axis control
100003	Control output OFF/ON	Control output OFF	Control output ON
100004	Auto/Manual	Automatic control	Manual control
100005	Stall memory ON/OFF	Stall memory ON	Stall memory OFF
100006	Gain 1 ON/OFF	Gain 1 ON	Gain 1 OFF
100007	Gain 2 ON/OFF	Gain 2 ON	Gain 2 OFF
100008	Inching ON/OFF	Inching ON	Inching OFF
100009	Cutting torque ON/OFF	Cutting torque ON	Cutting torque OFF
100010	Constant tension ON/OFF	Constant tension ON	Constant tension OFF
100011	Predrive ON/OFF	Predrive ON	Predrive OFF
100012	Memory hold ON/OFF	Memory hold ON	Memory hold OFF
100013	Reverse run/Forward run	Reverse run operation	Forward run operation
100014	_	_	_
100015	_	_	_
100016	_	_	_
100017	Alarm reset ON/OFF	Alarm reset ON	Alarm reset OFF
100018	Reel diameter reset ON/OFF	Reel diameter reset ON	Reel diameter reset OFF
100019	Measurement length and remaining length reset ON/OFF	Measurement length and remaining length reset ON	Measurement length and remaining length reset OFF
100020	_	_	_
100021	_	_	_
100022	_	_	_
100023	_	_	_
100024	_	_	_
100025	Zero adjustment execution	Execution	Normal
100026	Span adjustment execution	Execution	Normal
100027	Maximum diameter teaching execution	Start maximum diameter teaching execution	Normal
100028	Minimum diameter teaching execution	Start minimum diameter teaching execution	Normal
100029	Control gain tuning execution	Start control gain tuning execution	Normal
100030	Speed teaching execution	Start speed teaching execution	Normal
100031	_	_	_
100032	_	_	_
100033	Data copy execution	Start data copy execution	Normal
100034	Data initial execution	Start data initial execution	Normal
100035	_	_	_
100036	_	_	_
100037	_	_	_
100038	_	_	_
100039	_	-	_
100040	_	_	_
100041	_	_	_
100042			_
100043		_	_
100043		_	_
100045	Link tension monitor digit ×10/×1	Link tension monitor digit ×10	Link tension monitor digit ×1
100046	Continuous settings execution	Start continuous settings execution	Normal

Device No.	Signal name	Signal name ON (data value=1)	OFF (data value=0)
100047	Continuous monitor execution	Start continuous monitor execution	Normal
100048	Request command execution	Start request command execution	Normal
After 100049	System use area		

#### • Coil (0) (Slave station→Master station)

Device No.	Signal name	Signal name ON (data value=1)	OFF (data value=0)
000001	Run/Stop	Run	Stop
000002	Output ON/OFF	Output ON	Output OFF
000003	B-axis controlled/A-axis controlled	B-axis controlled	A-axis controlled
000004	Constant tension ON/OFF	Constant tension ON	Constant tension OFF
000005	Predrive being executed	Predrive being executed	Normal
000006	Memory hold being executed	Memory hold being executed	Normal
000007	Reverse running/Forward running	Reverse running	Forward running
000008	_	_	_
000009	Manual control	Manual control	_
000010	Automatic control	Automatic control	_
000011	Auto lamp flicker in operation/ stopped	Auto lamp flicker in operation	Auto lamp flicker stopped
000012	Stall setting output being executed	Stall setting output being executed	Normal
000013	Stall memory output being executed	Stall memory output being executed	Normal
000014	Start timer operation being executed	Start timer operation being executed	Normal
000015	Stop timer operation being executed	Stop timer operation being executed	Normal
000016	Preset timer operation being executed	Preset timer operation being executed	Normal
000017	Cut torque operation being executed	Cut torque operation being executed	Normal
000018	Inching operation being executed	Inching operation being executed	Normal
000019	_	_	_
000020	Zero adjustment being executed	Zero adjustment being executed	Normal
000021	Span adjustment being executed	Span adjustment being executed	Normal
000022	Maximum diameter teaching being executed	Speed teaching being executed	Normal
000023	Minimum diameter teaching being executed	Speed teaching being executed	Normal
000024	Control gain tuning being executed	Control gain tuning being executed	Normal
000025	Speed teaching being executed	Speed teaching being executed	Normal
000026	Tension upper limit detection ON/ OFF	Tension upper limit detection ON	Tension upper limit detection OFF
000027	Tension lower limit detection ON/OFF	Tension lower limit detection ON	Tension lower limit detection OFF
000028	Detection outside tension range ON/ OFF	Detection outside tension range ON	Detection outside tension range OFF
000029	Reel diameter detection 1 ON/OFF	Reel diameter detection 1 ON	Reel diameter detection 1 OFF
000030	Reel diameter detection 2 ON/OFF	Reel diameter detection 2 ON	Reel diameter detection 2 OFF
000031	Reel diameter detection 3 ON/OFF	Reel diameter detection 3 ON	Reel diameter detection 3 OFF
000032	Measurement length/remaining length detection 1 ON/OFF	Measurement length/remaining length detection 1 ON	Measurement length/remaining length detection 1 OFF
000033	Measurement length/remaining length detection 2 ON/OFF	Measurement length/remaining length detection 2 ON	Measurement length/remaining length detection 2 OFF
000034	Measurement length/remaining length detection 3 ON/OFF	Measurement length/remaining length detection 3 ON	Measurement length/remaining length detection 3 OFF
000035	Peripheral speed synchronization detection ON/OFF	Peripheral speed synchronization detection ON	Peripheral speed synchronization detection OFF
000036	Alarm occurrence detection	Alarm occurrence	Normal
000037	Parameter protection being executed	Parameter protection being executed	Normal
000038	Settings password matching being executed	Settings password matching being executed	Settings password does not match
000039	Monitor password matching being executed	Monitor password matching being executed	Monitor password does not match

Device No.	Signal name	Signal name ON (data value=1)	OFF (data value=0)
000040	_	_	_
000041	Data copy being executed	Data copy being executed	Normal
000042	Data initial being executed	Data initial being executed	Normal
000043	_	_	_
000044	_	_	_
000045	_	_	_
000046	Continuous settings being executed	Continuous settings being executed	Normal
000047	Continuous monitor being executed	Continuous monitor being executed	Normal
000048	Request command completion	Request command completion	Normal
After 100049	System use area		

## **Word device**

The word device uses 12 points for both the holding register (4) and the input register (3). The remaining area becomes non-functioning and cannot be used.

• Holding register (4) (Master station→Slave station)

Modbus TCP master station→LE7-40GU				
Device No.	Signal name			
400001	Continuous settings 1			
400002	Continuous settings 2			
400003	Request command 0	Request code 0		
400004	Setting data 0	·		
400005	Request command 1	Request code 1		
400006	Setting data 1			
400007	Continuous settings 3			
400008	Continuous settings 4			
400009	Request command 2	Request code 2		
400010	Setting data 2			
400011	Request command 3	Request code 3		
400012	Setting data 3			
400013 to 16	Unavailable			

• Input register (3) (Slave station→Master station)

Modbus TCP master station→LE7-40GU				
Device No.	Signal name			
400001	Continuous settings 1			
400002	Continuous settings 2			
400003	Request command 0	equest command 0 Request code 0		
400004	Setting data 0			
400005	Request command 1	Request code 1		
400006	Setting data 1			
400007	Continuous settings 3			
400008	Continuous settings 4			
400009	Request command 2	Request code 2		
400010	Setting data 2			
400011	Request command 3	Request code 3		
400012	Setting data 3			
400013 to 16	Unavailable			

## **Function code**

The LE7-40GU (slave) supports the following function codes (subfunction codes).

Function code (Subfunction code)	Function	Number of accessible device one [unit: points]
0x01	Read Coils	1 to 2000
0x02	Read Discrete Inputs	1 to 2000
0x03	Read Holding Registers	1 to 125
0x04	Read Input Registers	1 to 125
0x05	Write Single Coil	1
0x06	Write Single Register	1
0x0F	Write Multiple Coils	1 to 1968
0x10	Write Multiple Register	1 to 123

# Continuous setting/continuous monitoring

Data specified in advance can be set and monitored continuously by setting the continuous setting execution (RY2E) and continuous monitor execution (RY2E) in the master station to ON.

For continuous setting data, the data set for RAM writing is not stored during a power failure.

The latest data existing in LE7-40GU when the master station gives the send request can be monitored continuously. However, regarding the update of parameters for which the monitor update cycle is specified by the setting in LE7-40GU, the data is updated in the specified update cycle if the specified update cycle is longer than the monitor update cycle in the send request given by the master station.

#### **Continuous settings**

- Data write to devices with continuous settings 1 to 16
- **2.** Turn on continuous settings execution

#### **Continuous monitor**

- 1. Turn on continuous monitor execution
- 2. Read the data of the devices of continuous monitors 1 to 16

## Access by request command

For any access to data in LE7-40GU from the master station, data can be read and written by handshake between the "request command execution (RY2F)" flag and the "request command completion (RX2F)" flag.

This access is performed using a 2-word word device of the master station.

This 2-word data is comprised of the request command, to which the upper 4 bits of the first word are assigned, and the request code, to which the lower 12 bits are assigned, and the setting data, to which the next word is assigned.

bit 15 to 12	bit 11 to 0
Request command	Request code
Setting data	·

There are three types of request command, Data Monitor, Writing to RAM, and Writing to RAM + ROM, according to the selection of data reading and writing method.

Monitor	Writing to RAM	Writing to RAM + ROM
Writing data is reflected in the settings based on a	Writing data is reflected in the settings based on a	Perform the above RAM write + data power failure
data read request from the master station but is	data write request from the master station but is	write.
not stored in the case of a power failure.	not stored in the case of a power failure.	

In the ROM for storage against power interruption, the allowable number of times of writing is limited. Accordingly, data cyclically written and updated by the PLC must be written only to the RAM.

Request command	Contents of execution	Execution result
Н0	Monitor	Monitored value
H1	Writing to RAM	Writing result
H2	Writing to RAM + ROM	Writing result

The request code is the data number (address) of the data that executes the request command. The subsequent data setting is the data to be written to the data number, and if the request command is the monitor, the data setting data is ignored. When double word data is written to send data in the master station, and the handshake is executed by turning ON/OFF the request command execution flag and request command completion flag as follows, LE-70GU sends back the request command execution request.

- **1.** The master station is set to request command execution ON.
- **2.** LE7-40GU executes processing when receiving turning ON of the request command execution by the master station.
- **3.** LE7-40GU turns ON the request command completion.
- 4. The master station receives the request command completion ON.
- 5. The master station is set to request command execution OFF.
- **6.** LE7-40GU receives turning OFF of the request command execution by the master station.
- 7. LE7-40GU turns OFF the request command completion.
- **8.** The master station receives the request command completion OFF.

Please perform reading of the execution results of the request command between step 4 and 5 of the handshake procedure. If an error occurs, in the execution result with respect to the request command from the master station, turn on the network alarm occurrence flag and output the device number where the alarm occurred to the network alarm device number monitor. For the request command execution result, refer to the following.

**LILE7-CCL APPLICATION MANUAL** 

# Request code

The numerical value of each parameter corresponding to the request code is treated as real number data without a decimal point.

In addition, the minimum and maximum values are determined for LE7-40GU, and when a value exceeding this data is written, it is automatically rewritten to the minimum or maximum value.

In this case, an "Out of data range" alarm is generated.

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H000(0)	_	_	_	_	_	_
H001(1)	Total tension	Monitor	_	0 or less	2000 or more	N/×10 N
H002(2)	Left tension	Monitor	_	0 or less	2000 or more	N/×10 N
H003(3)	Right tension	Monitor	_	0 or less	2000 or more	N/×10 N
H004(4)	Left input voltage	Monitor	_	-1500 or less	1500 or more	mV
H005(5)	Right input voltage	Monitor	_	-1500 or less	1500 or more	mV
H006(6)	_	_	_	_	_	_
H007(7)	_	_	_	_	_	_
H008(8)	_	_	_	_	_	_
H009(9)	_	_	_	_	_	_
H00A(10)	_	_	_	_	_	_
H00B(11)	_	_	_	_	_	_
H00C(12)	_	_	_	_	_	_
H00D(13)		_	_	_	_	_
H00E(14)	_		_	_	_	_
H00F(15)	_	_	_	_		_
H010(16)	Tension upper limit detection	Setting	_	0	Tension full scale	N/×10 I
H011(17)	Tension lower limit detection	Setting	_	0	Tension full scale	N/×101
H012(18)	Detection outside target tension range	Setting	_	0	50	%
H013(19)	Tension display filter	Setting	_	5	80	sec
H014(20)	Tension detection filter	Setting	_	0	80	sec
H015(21)	Tension output filter	Setting	_	0	80	sec
H016(22)	—	—	_	_	_	
H017(23)	_		_	_	_	_
* *	<u>                                     </u>		_			<del> </del>
H018(24)	_		_	_	_	-
H019(25)	_		_	_	_	_
H01A(26)	_		_	_	_	_
H01B(27)	-		_	_	_	_
H01C(28)	_		_	_	_	_
H01D(29)	_	_	_	_	_	-
H01E(30)	_		_	_	_	_
H01F(31)	_	_	_	_	<u> </u>	_
H020(32)	Sensor input type selection	Setting	_	0 (LX type), 1 (strain		_
H021(33)	Tension full scale	Setting	_	1	2000	N/×10 N
H022(34)	Tension display decimal point selection	Setting	_	0 (1), 1 (0.1), 2 (0.01)	)	_
H023(35)	Tension display unit selection	Setting	_	0 (N), 1 (×10 N)	T	-
H024(36)	Span target tension	Setting	_	1	Tension full scale	N/×10 N
H025(37)	Left manual zero calibration	Setting	_	-999	999	N/×10 N
H026(38)	Right manual zero calibration	Setting	_	-999	999	N/×10 I
H027(39)	Left manual span calibration	Setting	_	50	300	%
H028(40)	Right manual span calibration	Setting	_	50	300	%
H029(41)	_	_	_	_	_	_
H02A(42)	_	_	_	_	_	_
H02B(43)	_	_	_	_	_	_

Request	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
		Settings	-			
H02C(44)	_		_	_	_	_
H02D(45)	_		_	_	_	_
H02E(46)			_	_	_	_
H02F(47)	<u> </u>		_	_	_	_
H030(48)	Reel diameter	Monitor	_	1	2000	mmφ
H031(49)	Target line velocity	Monitor	LE7-DCA	0	10000	m/min
H032(50)	Line acceleration	Monitor	LE7-DCA	0	50	m/min/sec
H033(51)	Measurement length/remaining length	Monitor	LE7-DCA	_	_	m
H034(52)	Reel rotational speed	Monitor	LE7-DCA	65000	1	r/min
H035(53)	New reel rotational speed	Monitor	LE7-DCA	3600	1	r/min
H036(54)	Constant slip ROTO speed command output	Monitor	LE7-DCA	1000	0.1	%
H037(55)	Predrive rotation speed command output	Monitor	LE7-DCA	1000	0.1	%
H038(56)	Predrive target rotation speed	Monitor	LE7-DCA	3600	1	r/min
H039(57)	Reel diameter CALC adapter ROM version	Monitor	LE7-DCA	999	0.01	_
H03A(58)	_	_	_	_	_	_
H03B(59)	_		_	_		_
H03C(60)	_	_	_	_	_	_
H03D(61)	_	_	_	_	_	_
H03E(62)	_	_	_	_	_	_
H03F(63)	_	_	_	_	_	_
H040(64)	Initial diameter	Setting	LE7-DCA	1	2000	mmφ
H041(65)	Material thickness	Setting	LE7-DCA	0	10000	μm
H042(66)	Reel diameter detection 1	Setting	LE7-DCA	0	2000	mmφ
H043(67)	Reel diameter detection 2	Setting	LE7-DCA	0	2000	mmφ
H044(68)	Reel diameter detection 3	Setting	LE7-DCA	0	2000	mmφ
H045(69)	Measurement/remaining length detection 1	Setting	LE7-DCA	0	65000	m
H046(70)	Measurement/remaining length detection 2	Setting	LE7-DCA	0	65000	m
H047(71)	Measurement/remaining length detection 3	Setting	LE7-DCA	0	65000	m
H048(72)	Accelerating judgment acceleration	Setting	LE7-DCA	0	10	m/min/sec
H049(73)	Reel rotational speed gain	Setting	LE7-DCA	0	150	%
H04A(74)	Reel rotational speed bias	Setting	LE7-DCA	0	100	%
H04B(75)	Reel rotational speed startup gain	Setting	LE7-DCA	1	5	Time (s)
H04C(76)	Reel rotational speed startup timer	Setting	LE7-DCA	0	10	sec
H04D(77)	Predrive time	Setting	LE7-DCA	0	200	sec
H04E(78)	Predrive bias	Setting	LE7-DCA	-10	10	%
	Fiedlive bias	Setting	LL1-DCA	-10	-	70
H04F(79)	Maximum diameter	Cotting		Minimum diameter	2000	mm l
H050(80)	Maximum diameter	Setting	_	+	2000	mmφ
H051(81)	Minimum diameter	Setting		1	Maximum diameter	mmφ
H052(82)	Teaching speed	Setting	LE7-DCA	1	10000	m/min
H053(83)	Velocity electronic gear ratio	Setting	LE7-DCA	9000	18000	%
H054(84)	Reel selection	Setting	LE7-DCA	0(unwinding), 1(wind		_
H055(85)	Number of reel pulse	Setting	LE7-DCA	0 (1 pulse), 1 (2 puls pulses), 4 (16 pulses	es), 2 (4 pulses), 3 (8	_
H056(86)	Reel diameter calculation cycle	Setting	LE7-DCA		0 (1 pulse), 1 (2 pulses), 2 (4 pulses), 3 (8 pulses), 4 (16 pulses)	
H057(87)	MEAS/RMN length calculation switch	Setting	LE7-DCA	0 (measurement length)	gth), 1 (remaining	_
H058(88)	Material thickness unit	Setting	LE7-DCA	0 (×1), 1 (×0.1)		_
H059(89)	Maximum line acceleration	Setting	LE7-DCA	1	50	m/min/sec
H05A(90)	Maximum reel rotational speed	Setting	LE7-DCA	1	3600	r/min
H05B(91)	Detection output selection	Setting	LE7-DCA	0 (Reel diameter), (n	neasurement length/	_
H05C(92)	Detection output holding selection	Setting	LE7-DCA	0 (non-holding), 1 (h	olding)	_
()		9		- , (II	J,	

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H05D(93)	Run/Stop judgment selection	Setting	LE7-DCA	0 (contact + internal), (internal)	1 (contact), 2	_
H05E(94)	Run judgment speed	Setting	LE7-DCA	Stop judgment speed	30	m/min
H05F(95)	Stop judgment speed	Setting	LE7-DCA	1	Run judgment speed	m/min
H060(96)	_	_	_	_	_	_
H061(97)	_	_	_	_	_	_
H062(98)	_	_	_	_	_	_
H063(99)	_	_	_	_	_	_
H064(100)	_	_	_	_	_	_
H065(101)	_	_	_	_	_	_
H066(102)	_	_	_	_	_	_
H067(103)	_	_	_	_	_	_
H068(104)	_	_	_	_	_	_
H069(105)	_	_	_	_	_	_
H06A(106)	_	_	_	_	_	_
H06B(107)	<u> </u>	_	_	_	_	_
H06C(108)	_	_	_	_	_	_
H06D(109)	_	_	_	_	_	_
H06E(110)	_		_	_	_	
H06F(111)	_		_	_	_	
H070(112)	Target tension	Monitor	_	0	2000	N/×10 N
	-	Monitor	_	-1000 or less	1000 or more	%
H071(113)	Control output		-  -			%
H072(114)	Torque output	Monitor		-1000 or less	1000 or more	70
H073(115)	-  -	_	_	_	_	_
H074(116)	_		_	_	_	_
H075(117)	Control output voltage for powder	Monitor	_	260 or more	0.1	V
H076(118)	Control output current for powder	Monitor	_	400 or more	0.01	Α
H077(119)	_	_	_	_	_	_
H078(120)	_	_	_	_	_	_
H079(121)	_	_	_	_	_	_
H07A(122)	_	_	_	_	_	_
H07B(123)	_	_	_	_	_	_
H07C(124)	_	_	_	_	_	_
H07D(125)	_	_	_	_	_	_
H07E(126)	_	_	_	_	_	_
H07F(127)	_	_	_	_	_	_
H080(128)	Tension setting	Setting	_	1	Tension full scale	N/×10 N
H081(129)	Manual setting	Setting	_	-1000	1000	%
H082(130)	Stall setting	Setting	_	0	1000	%
H083(131)	Start timer	Setting	_	0	300	sec
H084(132)	Stop timer	Setting	_	0	1000	sec
H085(133)	Stop gain	Setting	_	5	400	%
H086(134)	Stop bias	Setting	_	0	100	%
H087(135)	Acceleration/deceleration torque setting	Setting	LE7-DCA	0	1000	%
H088(136)	Gain 1	Setting	_	5	400	%
H089(137)	Gain 2	Setting	_	5	400	%
H08A(138)	Internal taper ratio	Setting	_	0	80	%
H08B(139)	External linear line taper ratio	Setting	_	0	100	%
H08C(140)	New reel preset	Setting	_	0	1000	%
H08D(141)	New reel preset timer	Setting	_	0	300	sec
H08E(142)	Cutting torque	Setting	_	0	1000	%

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H08F(143)	_		_	_	_	_
H090(144)	Broken line taper corner 1	Setting	_	1	2000	mmφ
H091(145)	Broken line taper ratio 1	Setting	_	0	100	%
H092(146)	Broken line taper corner 2	Setting	_	1	2000	mmφ
H093(147)	Broken line taper ratio 2	Setting	_	0	100	%
H094(148)	Broken line taper corner 3	Setting	_	1	2000	mmφ
H095(149)	Broken line taper ratio 3	Setting	_	0	100	%
H096(150)	Broken line taper corner 4	Setting	_	1	2000	mmφ
H097(151)	Broken line taper ratio 4	Setting	_	0	100	%
H098(152)	Broken line taper corner 5	Setting	_	1	2000	mmφ
H099(153)	Broken line taper ratio 5	Setting	_	0	100	%
H09A(154)	Broken line taper corner 6	Setting	_	1	2000	mmφ
H09B(155)	Broken line taper ratio 6	Setting	_	0	100	%
H09C(156)	Broken line taper corner 7	Setting	_	1	2000	mmφ
H09D(157)	Broken line taper ratio 7	Setting	_	0	100	%
	'		_	1	2000	
H09E(158)	Broken line taper corner 8  Broken line taper ratio 8	Setting		0		mmφ %
H09F(159)	'	Setting	_		100	
H0A0(160)	Proportional gain	Setting	_	0	100	%
H0A1(161)	Integral time	Setting	_	0	100	%
H0A2(162)	Dead band gain	Setting	_	0	100 - Proportional gain	%
H0A3(163)	Dead band width	Setting	_	0	100	%
H0A4(164)	Tension control filter	Setting	_	0	40	sec
H0A5(165)	Static mechanical loss A	Setting	_	-1000	1000	%
H0A6(166)	Static mechanical loss B	Setting	_	-1000	1000	%
H0A7(167)	Kinetic mechanical loss A	Setting	LE7-DCA	-1000	1000	%
H0A8(168)	Kinetic mechanical loss B	Setting	LE7-DCA	-1000	1000	%
H0A9(169)	Mass correction gain A	Setting	LE7-DCA	0	100	%
H0AA(170)	Mass correction gain B	Setting	LE7-DCA	0	100	%
H0AB(171)	Mass correction bias A	Setting	LE7-DCA	0	100	%
H0AC(172)	Mass correction bias B	Setting	LE7-DCA	0	100	%
H0AD(173)	-	_	_	_	_	_
H0AE(174)	_	_	_	_	_	_
H0AF(175)	_	_	_	_	_	_
H0B0(176)	Control mode selection	Setting	LE7-DCA	0 (feedback control),	1 (open loop control)	_
H0B1(177)	Integral feedback limit	Setting	_	0	101	%
H0B2(178)	Feedback selection during the stop timer	Setting	_	0 (invalid), 1 (valid)		_
H0B3(179)	Automatic control output polarity selection	Setting	_	0 (forward), 1 (revers	e)	_
H0B4(180)	Open-loop control ratio	Setting	LE7-DCA	0	100	%
H0B5(181)	Taper function selection	Setting	_	0 (no function), 1 (internal taper), 2 (linear line taper (external)), 3 (broken line taper (external)), 4 (direct taper)		_
H0B6(182)	Selection of two reel's switching FUNC	Setting	_	0 (invalid), 1 (valid)		_
H0B7(183)	Internal taper standard selection	Setting	_	0 (zero standard), 1 (	stall standard)	_
H0B8(184)	_		_	_	<u> </u>	_
H0B9(185)	Mechanical loss function selection	Setting	LE7-DCA	O (fixed mechanical loss), 1 (high function mechanical loss)		_
H0BA(186)	Stall automatic calculation gain	Setting	LE7-DCA	0	100	%
H0BB(187)	New reel preset AUTO calculation gain	Setting	LE7-DCA	0	100	%
H0BC(188)	Control output upper limit	Setting	_	Control output lower limit	101	%
	Control output lower limit	Setting	_	-101	Control output	%
H0BD(189)	Control output lower limit	9			upper limit	

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H0BF(191)	_	_	_	_	_	_
H0C0(192)	Load model	Setting	_	0	200	_
H0C1(193)	Rated current	Setting	_	0	400	Α
H0C2(194)	Maximum torque correction	Setting	_	50	250	%
H0C3(195)	Nonlinear correction 0	Setting	_	0	1000	%
H0C4(196)	Nonlinear correction 10	Setting	_	0	1000	%
H0C5(197)	Nonlinear correction 20	Setting	_	0	1000	%
H0C6(198)	Nonlinear correction 30	Setting	_	0	1000	%
H0C7(199)	Nonlinear correction 40	Setting	_	0	1000	%
H0C8(200)	Nonlinear correction 50	Setting	_	0	1000	%
H0C9(201)	Nonlinear correction 60	Setting	_	0	1000	%
H0CA(202)	Nonlinear correction 70	Setting	_	0	1000	%
H0CB(203)	Nonlinear correction 80	Setting	_	0	1000	%
H0CC(204)	Nonlinear correction 90	Setting	_	0	1000	%
H0CD(205)		—	_	_	_	_
H0CE(206)	_		_	_	_	_
H0CF(207)	_		_	_	_	_
H0D0(208)	_	_	_	_	_	_
H0D1(209)	Weak excitation	Cotting	_	0	1000	%
H0D1(209) H0D2(210)		Setting	_	0	20	
	Over current detection filter	Setting		0	20	sec
H0D3(211)	_	+	_	_	_	-
H0D4(212)	_		_	_	_	_
H0D5(213)	<u> </u>		_	_	_	_
H0D6(214)	_		_	_	_	_
H0D7(215)	<u> </u>		_	_	_	_
H0D8(216)	_		_	_	_	_
H0D9(217)	_		_	_	_	_
H0DA(218)	_		_	_	_	_
H0DB(219)	_		_	_	_	_
H0DC(220)	_		_	_	_	_
H0DD(221)	_		_	_	_	_
H0DE(222)	_		_	_	_	_
H0DF(223)	_		_	_	_	_
H0E0(224)	Contact input monitor	Monitor	_	0	0xFFFF	_
H0E1(225)	Contact output monitor	Monitor	_	0	0xFFFF	_
H0E2(226)	General-purpose analog input 1 monitor	Monitor	_	0	100	%
H0E3(227)	General-purpose analog input 2 monitor	Monitor	_	0	100	%
H0E4(228)	General-purpose analog input 3 monitor	Monitor	_	0	100	%
H0E5(229)	General-purpose analog output 1 monitor	Monitor	_	0	100	%
H0E6(230)	General-purpose analog output 2 monitor	Monitor	_	0	100	%
H0E7(231)	Analog output monitor for TENS control	Monitor	_	0	100	%
H0E8(232)	Analog output monitor for new reel preset	Monitor	_	0	100	%
H0E9(233)	Contact input monitor for reel DIA CALC	Monitor	LE7-DCA	0	0xFFFF	_
H0EA(234)	Contact output monitor for reel DIA CALC	Monitor	LE7-DCA	0	0xFFFF	_
H0EB(235)	Alarm display	Monitor	_	0	63	_
H0EC(236)	Network alarm device No.	Monitor	_	0	999	_
H0ED(237)	Main unit ROM version	Monitor	_	0	999	_
H0EE(238)	Network adapter ROM version	Monitor	LE7-CCL	0	999	_
H0EF(239)	Communication signal monitor	Monitor	_	0	0xFFFF	_

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit	
H0F0(240)	Contact input 1 function selection	Setting	_	0 (no function), 1 (rur	n/stop), 2 (control	_	
H0F1(241)	Contact input 2 function selection	Setting	_	output OFF/ON), 3 (s	• * *	_	
H0F2(242)	Contact input 3 function selection	Setting	_	<ul><li>(inching ON/OFF), 5</li><li>OFF), 6 (gain 1 ON/OFF)</li></ul>	(constant tension ON/	_	
H0F3(243)	Contact input 4 function selection	Setting	_	- · · · · · -	nanual), 9 (reel change	_	
H0F4(244)	Contact input 5 function selection	Setting	_	ON/OFF), 10 (cut tor	,	_	
H0F5(245)	Contact input 6 function selection	Setting	_	(alarm reset ON/OFF)			
H0F6(246)			_				
* *	+			_			
H0F7(247)	Contact subset 4 for other collection	Cattian		0 ( function) 4 (ton	- i I liit		
H0F8(248)	Contact output 1 function selection	Setting	-	0 (no function), 1 (ter	upper limit detection),		
H0F9(249)	Contact output 2 function selection	Setting	_	3 (detection outside t	_		
H0FA(250)	_	_	_	_	_	_	
H0FB(251)	FB(251) — —		_	_	_	_	
H0FC(252)	_	_	_	_	_	_	
H0FD(253)	_	_	_	_	_	_	
H0FE(254)	_	_	_	_	<del> </del>	_	
H0FF(255)	<u> </u> _	_	_	_	_	_	
H100(256)	Analog input mode selection	Setting	_	0 (0 to 5 V mode), 1	(0 to 10 V mode)	_	
H101(257)	Analog input 1 function selection	Setting	_	0 (no function), 1 (ter	,	_	
H102(258)	Analog input 2 function selection	Setting	_		ne taper ratio setting),		
` '	<u> </u>	,		4 (new axis preset setting), 5 (manual			
H103(259)	Analog input 3 function selection	Setting	_	setting), 6 (tension in input)			
H104(260)		_	_	_	_	_	
H105(261)			_	_	_	_	
H106(262)	_	_	_	_	_	_	
H107(263)	-	_	_	_	_	_	
H108(264)	Analog output mode selection	Setting	_	0 (0 to 5 V mode), 1 (0 to 10 V mode)		_	
H109(265)	Analog output 1 function selection	Setting	_	0 (no function), 1 (tension monitor), 2 (Reel			
H10A(266)	Analog output 2 function selection	Setting	_	diameter monitor), 3 monitor), 4 (A-axis Rospeed output), 5 (B-arotational speed outp	eel shaft rotational	_	
H10B(267)	Analog output 1 gain	Setting	_	500	3000	%	
H10C(268)	Analog output 2 gain	Setting	_	500	3000	%	
H10D(269)	Analog output 1 bias	Setting	_	-500	500	%	
H10E(270)	Analog output 2 bias	Setting	_	-500	500	%	
H10F(271)	<u> </u>		_	_	<del> </del>	_	
H110(272)	Two reel's switching FUNC output mode	Setting	_	0 (no internal switchin switching)	ng), 1 (with internal	_	
H111(273)	Control output mode selection	Setting	_	0 (0 to 5 V mode), 1 to 10 V mode), 3 (-10 8 V mode), 5 (-8 to 8 mode), 7 (-2.7 to 2.7 mode)	_		
H112(274)	Control output gain	Setting	_	500	3000	%	
H113(275)	New reel preset output gain	Setting	_	500	3000	%	
H114(276)	Control output bias	Setting	_	-500	500	%	
H115(277)	New reel preset output bias	Setting	_	-500	500	%	
H116(278)	_	_	_	_	_	_	
H117(279)	_	_	_	_	_	_	
H118(280)	_	_	_	_	_	_	
H119(281)	_	_	_	_	<del> </del> _	_	
H11A(282)	_	_	_	_	_	_	
(202)						1	

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H11C(284)	_	_	_	_	_	_
H11D(285)	_	_	_	_	_	_
H11E(286)	_	_	_	_	_	_
H11F(287)	_	_	_	_	_	_
H120(288)	Set setting password	Setting	_	0	32000	_
H121(289)	Input setting password	Setting	_	0	32000	_
H122(290)	Set monitor password	Setting	_	0	32000	_
H123(291)	Input monitor password	Setting	_	0	32000	_
H124(292)	_	_	_	_	_	_
H125(293)	_	_	_	_	_	_
H126(294)	_	_	_	_	_	_
H127(295)	_	_	_	_	_	_
H128(296)	_	_	_	_	_	_
H129(297)	_	_	_	_	_	_
H12A(298)	_	_	_	_	_	_
H12B(299)	_	_	_	_	_	_
H12C(300)	_	_	_	_	_	_
H12D(301)	_	_	_	_	_	_
H12E(302)	_	_	_	_	_	_
H12F(303)	_	_	_	_	_	_
H130(304)	Alarm history 1	Monitor	_	0	63	_
H131(305)	Alarm history 2	Monitor	_	0	63	_
H132(306)	Alarm history 3	Monitor	_	0	63	_
H133(307)	Alarm history 4	Monitor	_	0	63	_
H134(308)	Alarm history 5	Monitor	_	0	63	_
H135(309)	Alarm history 6	Monitor	_	0	63	_
H136(310)	Alarm history 7	Monitor	_	0	63	_
H137(311)	Alarm history 8	Monitor	_	0	63	_
H138(312)	Alarm history holding selection	Setting	_	0 (no holding), 1 (hold		_
H139(313)	Alarm display time	Setting	_	0	301	sec
H13A(314)	Alarm operation selection 1	Setting	_	0	0xFFFF	_
H13B(315)	Alarm operation selection 2	Setting	_	0	0xFFFF	_
H13C(316)	Alarm operation selection 3	Setting	_	0	0xFFFF	_
H13D(317)	Alarm operation selection 4	Setting	_	0	0xFFFF	_
H13E(318)	_		_	_	_	_
H13F(319)	_	_	_	_	_	_
H140(320)	_	_	_	_	_	_
H141(321)	_	_	_	_	_	_
H142(322)	_	_	_	_	_	_
H143(323)	_	_	_	_	_	_
H144(324)	_	_	_	_	_	_
H145(325)	_	_	_	_	_	_
H146(326)	_	_	_	_	_	_
H147(327)	_	_	_	_	_	_
H148(328)	_	_	_	_	_	_
H149(329)	_	_	_	_	_	_
H14A(330)	_	_	_	_	_	_
H14B(331)	_	_	_	_	_	_
H14C(332)	_	_  _	_	_	_	_
		_	_	_	_	-  -
H14D(333)	_					
H14E(334)	<del>-</del>	_	_	_	_	-
H14F(335)	_	_	-	_	_	_

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H150(336)	_	_	_	_	_	_
H151(337)	_	_	_	_	_	_
H152(338)	_	_	_	_	_	_
H153(339)	_	_	_	_	_	_
H154(340)	_	_	_	_	_	_
H155(341)	_	_	_	_	_	_
H156(342)	_	_	_	_	_	_
H157(343)	_	_	_	_	_	_
H158(344)	_	_	_	_	_	_
H159(345)	_	_	_	_	_	_
H15A(346)	_	_	_	_	_	_
H15B(347)	_	_	_	_	_	_
H15C(348)	_	_	_	_	_	_
H15D(349)		_	_	_	_	_
H15E(350)	_	_	_	_	_	_
H15F(351)	_	_	_	  -	_	_
H160(352)	_	_	_	_	<u> </u>	_
H161(353)	_	_	_	_	_	_
H162(354)	_	_	-  -	<del>-</del>	_	_
H162(354)	_		_	_		
	_	_	-  -	<del>-</del>	_	_
H164(356)		_			_	_
H165(357)	<u> </u>		_	_	_	_
H166(358)	_	_	_	_	_	_
H167(359)	<del>-</del>	_	_	_	_	_
H168(360)	_	_	_	_	_	_
H169(361)	_	_	_	_	_	_
H16A(362)	_	_	_	_	_	_
H16B(363)	_	_	_	_	_	_
H16C(364)	_	_	_	_	_	_
H16D(365)	_	_	_	_	_	_
H16E(366)	_	_	_	_	_	_
H16F(367)	_	_	_	_	_	_
H170(368)	_	_	_	_	_	_
H171(369)	_	_	_	_	_	_
H172 (370)	_	_	_	_	_	_
H173(371)	_	_	_	_	_	_
H174(372)	_	_	_	_	_	_
H175(373)	_	_	-	_	_	-
H176(374)	_	_	_	_	_	_
H177(375)	_	_	_	_	_	_
H178(376)	_	_	_	_	_	_
H179(377)	_	_	_	_	_	_
H17A(378)	_	_	_	_	_	_
H17B(379)	_	_	_	_	_	<u> </u>
H17C(380)	_	_	_	_	_	_
H17D(381)	_	_	_	_	_	_
H17E(382)	_	_	_	_	_	_
H17F(383)	_	_	_	_	_	_
H180(384)	Open-loop control base torque	Setting	LE7-DCA	0	1000	%
H181(385)	Direct taper ratio	Setting	_	0	1000	%
H182(386)	Link tension monitor filter	Setting	_	0	80	sec
H183(387)	Tension input	Setting	_	0	2000	N/×10 N

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H184(388)	Reel diameter input	Setting	_	0	2000	mmφ
H185(389)	-	_	_	_	_	_
H186(390)	-	_	_	_	_	_
H187(391)	-	_	_	_	_	_
H188(392)	-	_	_	_	_	_
H189(393)	-	_	_	_	_	_
H18A(394)	-	_	_	_	_	_
H18B(395)	_	_	_	_	_	_
H18C(396)	_	_	_	_	_	_
H18D(397)	_	_	_	_	_	_
H18E(398)	_	_	_	_	_	_
H18F(399)	_	_	_	_	_	_

### **Precautions**

### ■About transmission delay

"Transmission delay" is a setting for low-speed devices that cannot respond quickly to transmission responses.

GOT2000 Series Connection Manual (Microcomputers, MODBUS/Fieldbus Products, Peripherals)

# ■Error code (MODBUS Exception Codes) returned by LE7-40GU (slave) to the MODBUS master equipment

LE7-40GU (slave) supports the following error codes (MODBUS Exception Codes) in response to a request from the MODBUS master equipment.

When the following errors occur, LE7-40GU will not generate a system alarm.

This section explains the contents, cause, and remedy for each error code.

· Commonly generated error codes for requests from master equipment

Error code (HEX)	Category	Contents	Cause	Remedy		
0x01	_	ILLEGAL FUNCTION (illegal	A function code not supported	A function code not supported by LE7-40GU was		
		function code)	by LE7-40GU was received.	received.		

• Error code generated in response to a read request from the master equipment

Error code (HEX)	Category	Contents	Cause	Remedy
0x02	Read/Write	ILLEGAL DATAADDRESS (illegal data address)	You have accessed a device out of range.	Please check whether the device to be accessed is incorrect.

• Error code generated in response to a write request from the master equipment

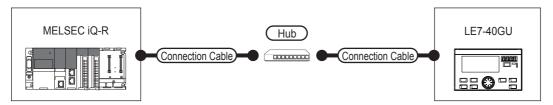
Error code (HEX)	Category	Contents	Cause	Remedy
0x02	Read/Write	ILLEGAL DATAADDRESS (illegal data address)	You have accessed a device out of range.	Please check whether the device to be accessed is incorrect.
0x03	Write	ILLEGAL DATA VALUE (illegal data value)	The consistency of the request packet (the number of writing points, the number of bytes of write data and the number of write data) is not established.	Make sure that normal packets are being transmitted from the master equipment.

<sup>&</sup>quot;Transmission delay" is initially set to 0 ms and it is necessary to set it with GT Designer3 (GOT2000) in order to change it. For details on settings, refer to the following..

# **5.3** Reference Program

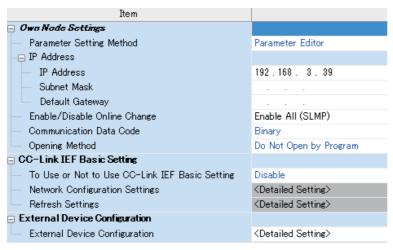
A basic example program (GX Works3) for MODBUS/TCP (SLAVE) communication is described.

# System configuration



# **Settings**

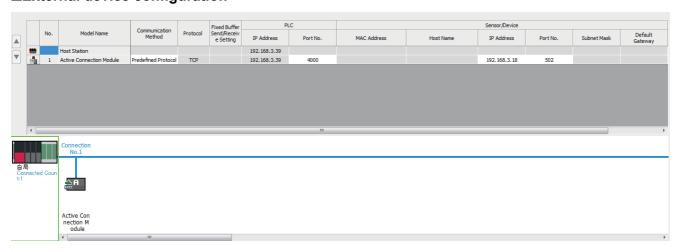
## **■**Own node settings



### **■CC-Link IEF Basic setting**

To use or not use CC-Link IEF Basic setting: Disable

## **■**External device configuration



## **■**Predefined protocol support function

Protocol setting

Protocol No.	Manufacturer	Model	Protocol Name	Communication Type	-> Send <- Receive	Packet Name	Packet Setting
1	General-purpose protocol	MODBUS/TCP	04: RD IN Registers	Send&Receive			
					->	Request	<u>Variable Set</u>
					<-(1)	Normal response	<u>Variable Set</u>
					<-(2)	Error response	<u>Variable Set</u>
2	General-purpose protocol	MODBUS/TCP	16: WR Multi Registers	Send&Receive			
					->	Request	<u>Variable Set</u>
					<-(1)	Normal response	<u>Variable Set</u>
					<-(2)	Error response	<u>Variable Set</u>
<u>Add</u>							

For packet setting, set in edit→device batch setting.

Protocol No. 1: D1000 and later Protocol No. 2: D2000 and later

For the detailed setting method, refer to the following.

MELSEC iQ-R Ethernet User's Manual (Application)

# Program example

Write			2	3	4	5	6	7	8	9	10	11	12
	OPEN pn	1 :					M_RCPU_ConnectionOp	en 00C 1 ( <b>M+R</b> 0	~]				
2	(0)	X10					Connect (		1				Y100
		Hì					– B:I_bEN	o_bENO:	3				
3		Communi					Execution command	Execution status					OPEN
		cation start					Command						execution status flag
		stal t											Y101
							DUT:i_stModule	o_bOK:E	3				Y 101
4							Module label	Normally complete	ed				OPEN normal
													completion
													flag
						-{ K1	} UW:i_uConnectionNo	o_bErr:E	3				Y102 ———O
5							Connection number	Unnormally					OPEN
								completed					abnormal
													completion flag
								o_uErrID:UV	v ( D50 }				
6								Error code					
0									Error code during				
									OPEN error				
							pbi_bUseParameters	0					
_							pbi_uProtocol pbi_uOpen_System pbi_uLocal_Port_No	0 4096					
7							pbi_uTarget_Port_No pbi_u2IP_Address	4096					
							pbi_uzii _maaress						
	OLOSE p	1					Luciani di di		-1				
9	(114)	X10					M_RCPU_ConnectionCk Connect (						Y103
		1					– B:i_bEN	o_bENO:	3				¥ 103
10		Communi					Execution	Execution status					CLOSE
		cation					command						execution
		start											status flag
		-					DUT:i_stModule	o_bOK:E	3				Y104
11							Module label	Normally complete	ed				CLOSE
11													normal
													completion flag
						-{ K1	] 	o_bErr:8	3				Y105
						-	Connection number						_
12							- Cormodition Trained	completed					CLOSE abnormal
													completion flag
					<u>.</u>			o_uErrID:UV	V DE1 7				1.76
								_	, L , ,				
13								Error code	Error code				
									during CLOSE				
							pbo_uErrConn_No	0	error				
14													

Write	· 1	2	3	4	5	6	7	8	9	10	11	12
15			rt functio	on Desig	nation of	protocol execution order		:			:	:
	SM40	,									K1	D2
											131	Protocol No.
16	(215) Always									MOV		1
	ON											
											K2	D3
											NZ	Protocol No.
17										MOV		2
18 0	Communication p	rotocol suppo	rt functio	n Proto	col 1 set	ting	.:	:			i	<u>.:</u>
	X10										L/A	D1000
	''										K0	D1000 Protcol 1
19	(301) <sub>Commu</sub>	ni								MOV		Transaction
	cation											D
	start											-
		-									K255	D1001
20										MOV		Protool 1
20										MOV		Protool ID
											IVO.	D1000
											K0	D1002 Protcol 1
21										MOV		Head holding
												register
												number
											K16	D1003
												Protcol 1
22										MOV		Read points
23	Communication p	rotocol suppo	rt functio	on Proto	∞l2 set	ting						
	X10											
											K0	Danno
24											K0	D2000 Proteol 2
24		ni								MOV	K0	Proteol 2 Transaction
24	(370) <sub>Commu</sub>	ni								MOV	K0	Protool 2
24	(370) <sub>Comm</sub> ı	ni								MOV	K0	Proteol 2 Transaction
24	(370) <sub>Commu</sub>	ni								MOV	KO	Proteol 2 Transaction
24	(370) <sub>Commu</sub>	ni								MOV	K0 K255	Proteol 2 Transaction
	(370) <sub>Commu</sub>	ni										Protcol 2 Transaction ID  D2001 Protcol 2
25	(370) <sub>Commu</sub>	ni								MOV		Proteol 2 Transaction ID
	(370) <sub>Commu</sub>	ni										Protcol 2 Transaction ID  D2001 Protcol 2
	(370) <sub>Commu</sub>	ni										Proteol 2 Transaction ID  D2001  Proteol 2
	(370) <sub>Commu</sub>	ni									K255	Protool 2 Transaction ID  D2001 Protool 2 Protool ID
	(370) <sub>Commu</sub>	ni										Protool 2 Transaction ID  D2001 Protool 2 Protool ID  D2002
	(370) <sub>Commu</sub>	ni									K255	Protool 2 Transaction D D2001 Protool 2 Protool ID D2002 Protool 2
25	(370) <sub>Commu</sub>	ni								MOV	K255	Protool 2 Transaction  D  D2001 Protool 2 Protool ID  D2002 Protool 2 Head holding register
25	(370) <sub>Commu</sub>	ni								MOV	K255	Protool 2 Transaction  D  D2001 Protool 2 Protool ID  D2002 Protool 2 Head holding
25	(370) <sub>Commu</sub>	ni								MOV	K255	Protcol 2 Transaction  D  D2001 Protcol 2 Protcol ID  D2002 Protcol 2 Head holding register
25	(370) <sub>Commu</sub>	ni								MOV	K255	Protcol 2 Transaction  D  D2001 Protcol 2 Protcol ID  D2002 Protcol 2 Head holding register
25	(370) <sub>Commu</sub>	ni								MOV	K255	Protool 2 Transaction  D  D2001 Protool 2 Protool ID  D2002 Protool 2 Head holdins register number  D2003 Protool 2
25	(370) <sub>Commu</sub>	ni								MOV	K255	Protcol 2 Transaction ID  D2001 Protcol 2 Protcol ID  D2002 Protcol 2 Head holding register number  D2003
25	(370) <sub>Commu</sub>	ni								MOV	K255	Protool 2 Transaction  D  D2001 Protool 2 Protool ID  D2002 Protool 2 Head holdins register number  D2003 Protool 2
25	(370) <sub>Commu</sub>	ni								MOV	K255	Protool 2 Transaction  D  D2001 Protool 2 Protool ID  D2002 Protool 2 Head holdins register number  D2003 Protool 2
25	(370) <sub>Commu</sub>	ni								MOV	K255	Protool 2 Transaction  D  D2001 Protool 2 Protool ID  D2002 Protool 2 Head holding register number  D2003 Protool 2 Read points
25	(370) <sub>Commu</sub>	ni								MOV	K255	Protool 2 Transaction D  D2001 Protool 2 Protool ID  D2002 Protool 2 Head holding register number  D2003 Protool 2 Read points
25 26 27	(370) <sub>Commu</sub>	ni								MOV	K255	Protool 2 Transaction ID  D2001 Protool 2 Protool ID  D2002 Protool 2 Head holding register number  D2003 Protool 2 Read points  D2004 Protool 2
25	(370) <sub>Commu</sub>	ni								MOV	K255	Protool 2 Transaction D  D2001 Protool 2 Protool ID  D2002 Protool 2 Head holding register number  D2003 Protool 2 Read points
25 26 27	(370) <sub>Commu</sub>	ni								MOV	K255	Protool 2 Transaction D  D2001 Protool 2 Protool ID  D2002 Protool 2 Head holding register number  D2003 Protool 2 Read points  D2004 Protool 2 Device data
25 26 27	(370) Communication start									MOV	K255	Protool 2 Transaction  D  D2001 Protool 2 Protool ID  D2002 Protool 2 Head holding register number  D2003 Protool 2 Read points  D2004 Protool 2 Device data
25 26 27 28	(370) Communication start	function exect	sution							MOV	K255	Protool 2 Transaction  D  D2001 Protool 2 Protool ID  D2002 Protool 2 Head holding register number  D2003 Protool 2 Read points  D2004 Protool 2 Device data
25 26 27	(370) Communication start	function exec	sution					Uo	K1	MOV	K255	Protool 2 Transaction  D  D2001 Protool 2 Protool ID  D2002 Protool 2 Head holding register number  D2003 Protool 2 Read points  D2004 Protool 2 Device data
25 26 27 28 29 F	Oommucation start  Protocol support SM41	function exection of the second of the secon	sution				SPECPRT	Uo	K1	MOV MOV	K255  K0  K16  K32	Protocol 2 Transaction ID  D2001 Protocol 2 Protocol ID  D2002 Protocol 2 Head holding register number  D2003 Protocol 2 Read points  D2004 Protocol 2 Device data length
25 26 27	(370) Commucation start	function exect 1 Y101 1 H	cution				SP.E.CPRT OL	Uo	K1	MOV MOV	K255  K0  K16  K32	Protocol 2 Transaction ID  D2001 Protocol 2 Protocol ID  D2002 Protocol 2 Head holding register number  D2003 Protocol 2 Read points  D2004 Protocol 2 Device data length  Y106 Protocol execution
25 26 27 28 29 F	Oommucation start  Protocol support SM41	function exect 1 Y101 - I I- ck OPEN normal					SP.ECPRT CL	UO	K1	MOV MOV	K255  K0  K16  K32	Protocol 2 Transaction ID  D2001 Protocol 2 Protocol ID  D2002 Protocol 2 Head holding register number  D2003 Protocol 2 Read points  D2004 Protocol 2 Device data length
25 26 27 28 29 [F	Oommucation start  Protocol support SM41	function exect 1 Y101 1 H					SP.E.OPRT CL	Uo	K1	MOV MOV	K255  K0  K16  K32	Protool 2 Transaction D  D2001 Protool 2 Protool ID  D2002 Protool 2 Head holding register number  D2003 Protool 2 Read points  D2004 Protool 2 Device data length

Write		1 ata transfe	2	3	4	5	6	7	8	9	10	11	12
32		X10 X10 Communi cation start								BMOV	K4Y1000 Run/Sto P	D2005 Protocol 2 Storage data	K3
33										BMOV	D1007 Protocol 1 Storage data	K4X1000 Run/Stop	K3
34										BMOV	W1000 400004	D2008 Protocol 2 Storage data	K12
:5										BMOV	D1010 Protocol 1 Storage data	W0 300001	K12
36 🕸	Request	command a	access pro X102F	œssing									
37	(527)	Request command access	Request command completio								MOV	D100 Request command 0 + request code 0	W1002 400006
38		start	<u>n</u>								MOV	D101 Setting data 0	W1003 400007
39											MOV	D102 Request command 1 + request code 1	W1004 400008
10											MOV	D103 Setting data 1	W1005 400009
11												SET	Y102F Request command execution
12			X102F  Request command completio								MOV	W4 300005	D110 Request command execution result 0
13			n								MOV	W5 300006	D111 Request command execution result 1
44	(546)	X20  Arrow A										RST	Y102F Request command execution

Write	*	1	2	3	4	5	6	7	8	9	10	11	12
15 ×	Continu	ous monitor	processin	g			<u> </u>	:					:
		X21										_	Y102E
		' '											
16	(548)	Continuou										SET	Continuous monitor
10	(040)	Continuou										021	execution
		monitorin											OXCOGCIOI1
		g start											
												Wo	D120
												300001	Continuous
17											MOV		monitor 1
													(Total
													tension)
												W1	D121
												300002	Continuous
18											MOV		monitor 2
													(Target
													tension)
					<u></u>								
												100	D100
												W2	D122
0											MOV	300003	Continuous
19											IVIOV		monitor 3
													(Control
													output)
-					ļ				<u>:</u>	<u>:</u>			
												W3	D123
0											MOV	300004	Continuous
0											10100		monitor 4 (Alarm
													display)
													310p10))
		X21					<u> </u>		:	<u>:</u>			
		1				-		ļ					Y102E
1	(559)	C										RST	Continuous
51	(559)	Continuou										RST	monitor
51	(559)	S										RST	
51	(559)	Continuou s monitorin g start										RST	monitor
		s monitorin	; processir	g								RST	monitor
		s monitorin g start ous settings   X22	s processir	g									monitor execution
		s monitorin g start ous settings	; processir									RST D130	monitor
i2 [ж(	Continu	s monitorin g start ous settings X22	s processir	<u>E</u>								D130 Continuous	monitor execution W1000
2 (ж(	Continu	s monitorin g start ous settings X22	s processir	<u>Je</u>							MOV	D130 Continuous settings 1	monitor execution W1000
	Continu	s monitorin g start ous setting X22 I Continuou s setting	s proæssir	<b>E</b>							MOV	D130 Continuous settings 1 (Tension	monitor execution W1000
2 (ж(	Continu	s monitorin g start ous setting X22 I Continuou	s processir	<b>E</b>							MOV	D130 Continuous settings 1	monitor execution W1000
2 (ж(	Continu	s monitorin g start ous setting X22 I Continuou s setting	s processir	] <u>e</u>							MOV	D130 Continuous settings 1 (Tension	monitor execution W1000
2 (ж(	Continu	s monitorin g start ous setting X22 I Continuou s setting	s processir	E							MOV	D130 Continuous settings 1 (Tension setting)	with with with with with with with with
2 (ж(	Continu	s monitorin g start ous setting X22 I Continuou s setting	s processir	g							моу	D130 Continuous settings 1 (Tension setting)	w1000 400004 W1001
3	Continu	s monitorin g start ous setting X22 I Continuou s setting	s processir	g.								D130 Continuous settings 1 (Tension setting)  D131 Continuous	w1000 400004 W1001
2 ×(	Continu	s monitorin g start ous setting X22 I Continuou s setting	processir	E							MOV	D130 Continuous settings 1 (Tension setting)  D131 Continuous settings 2	w1000 400004 W1001
2 ×(	Continu	s monitorin g start ous setting X22 I Continuou s setting	processir	Œ								D130 Continuous settings 1 (Tension setting) D131 Continuous settings 2 (Manual	w1000 400004 W1001
2 ×(	Continu	s monitorin g start ous setting X22 I Continuou s setting	s processir	DE								D130 Continuous settings 1 (Tension setting)  D131 Continuous settings 2	w1000 400004 W1001
i2 [ж(	Continu	s monitorin g start ous setting X22 I Continuou s setting	s processir	S								D130 Continuous settings 1 (Tension setting) D131 Continuous settings 2 (Manual	w1000 400004 W1001
i2   <b>*</b> (	Continu	s monitorin g start ous setting X22 I Continuou s setting	processir	E								D130 Continuous settings 1 (Tension setting)  D131 Continuous settings 2 (Manual setting)	w1000 400004 W1001 400005
2 ×(	Continu	s monitorin g start ous setting X22 I Continuou s setting	processir	E								D130 Continuous settings 1 (Tension setting)  D131 Continuous settings settings 2 (Manual setting)	w1000 400004 W1001 400005
33	Continu	s monitorin g start ous setting X22 I Continuou s setting	processir	E							MOV	D130 Continuous settings 1 (Tension setting)  D131 Continuous settings 2 (Manual setting)  D132 Continuous	w1000 400004 W1001 400005
3	Continu	s monitorin g start ous setting X22 I Continuou s setting	s processir	E								D130 Continuous settings 1 (Tension setting)  D131 Continuous settings 2 (Manual setting)  D132 Continuous settings 3	w1000 400004 W1001 400005
3	Continu	s monitorin g start ous setting X22 I Continuou s setting	processir	E							MOV	D130 Continuous settings 1 (Tension setting)  D131 Continuous settings 2 (Manual setting)  D132 Continuous settings 3 (Stall	w1000 400004 W1001 400005
3	Continu	s monitorin g start ous setting X22 I Continuou s setting	processir	E							MOV	D130 Continuous settings 1 (Tension setting)  D131 Continuous settings 2 (Manual setting)  D132 Continuous settings 3	w1000 400004 W1001 400005
3	Continu	s monitorin g start ous setting X22 I Continuou s setting	processir	E							MOV	D130 Continuous settings 1 (Tension setting)  D131 Continuous settings 2 (Manual setting)  D132 Continuous settings 3 (Stall	w1000 400004 W1001 400005
33	Continu	s monitorin g start ous setting X22 I Continuou s setting	s processir	<b>E</b>							MOV	D130 Continuous settings 1 (Tension setting)  D131 Continuous settings 2 (Manual setting)  D132 Continuous settings 3 (Stall	w1000 400004 W1001 400005
3	Continu	s monitorin g start ous setting X22 I Continuou s setting	processir	E							MOV	D130 Continuous settings 1 (Tension setting)  D131 Continuous settings 2 (Manual setting)  D132 Continuous settings 3 (Stall	w1000 400004 W1001 400005 W1006 400010
2 **(	Continu	s monitorin g start ous setting X22 I Continuou s setting	processir	E							MOV	D130 Continuous settings 1 (Tension setting)  D131 Continuous settings 2 (Manual setting)  D132 Continuous settings 3 (Stall	W1000 400004 W1001 400005 W1006 400010 Y102D Continuous
2 **(	Continu	s monitorin g start ous setting X22 I Continuou s setting	processir	<b>E</b>							MOV	D130 Continuous settings 1 (Tension setting)  D131 Continuous settings 2 (Manual setting)  D132 Continuous settings 3 (Stall setting)	w1000 400004  W1000 400005  W1006 400010  Y102D Continuous settings
33	Continu	s monitorin g start ous setting X22 I Continuou s setting	processir	E							MOV	D130 Continuous settings 1 (Tension setting)  D131 Continuous settings 2 (Manual setting)  D132 Continuous settings 3 (Stall setting)	W1000 400004 W1001 400005 W1006 400010 V102D Continuous
2 **(	Continu	s monitorin g start ous setting X22 I Continuou s setting	processir	E							MOV	D130 Continuous settings 1 (Tension setting)  D131 Continuous settings 2 (Manual setting)  D132 Continuous settings 3 (Stall setting)	w1000 400004  W1000 400005  W1006 400010  Y102D Continuous settings
2 **(	Continu	s monitorin g start ous setting X22 I Continuou s setting	processir	<b>E</b>							MOV	D130 Continuous settings 1 (Tension setting)  D131 Continuous settings 2 (Manual setting)  D132 Continuous settings 3 (Stall setting)	w1000 400004  W1000 400005  W1006 400010  Y102D Continuous settings
2 **(	Continu	s monitorin g start pus setting X22 I I Continuou s setting start	processir								MOV	D130 Continuous settings 1 (Tension setting)  D131 Continuous settings 2 (Manual setting)  D132 Continuous settings 3 (Stall setting)	w1000 400004  W1001 400005  W1006 400010  V102D Continuous settings execution
2 **(	Continu	smonitoring start  start  start  start  start  start  continuous setting  start  x22  I I  continuous setting  start	processir	<b>E</b>							MOV	D130 Continuous settings 1 (Tension setting)  D131 Continuous settings 2 (Manual setting)  D132 Continuous settings 3 (Stall setting)	w1000 400004  W1001 400005  W1006 400010  V102D Continuous settings execution
2 (xd) 3 4	(561)	smonitoring start  pus setting  X22  I Continuous setting start  Continuous setting start  X22  X22  X22	processir	<b>E</b>							MOV	D130 Continuous settings 1 (Tension setting)  D131 Continuous settings 2 (Manual setting)  D132 Continuous settings 3 (Stall setting)  SET	w1000 400004  W1001 400005  W1006 400010  Y102D Continuous settings execution  Y102D Continuous
2 **(	(561)	smonitorin g start  pus setting  X22  I Continuou s setting start   X22  V 22  V 22  V Continuou	processir	<b>E</b>							MOV	D130 Continuous settings 1 (Tension setting)  D131 Continuous settings 2 (Manual setting)  D132 Continuous settings 3 (Stall setting)	w1000 400004  W1001 400005  W1006 400010  V102D Continuous settings execution
2 (xd) 3 4	(561)	smonitoring start  pus setting  X22  I Continuous setting start  Continuous setting start  X22  X22  X22	processir	E							MOV	D130 Continuous settings 1 (Tension setting)  D131 Continuous settings 2 (Manual setting)  D132 Continuous settings 3 (Stall setting)  SET	w1000 400004  W1001 400005  W1006 400010  Y102D Continuous settings execution  Y102D Continuous

10   10   10   10   10   10   10   10		-		2	3	4	5	6	7	8	9	10	11	12
10	58  ×	Feedbac	X23	equence p	roœssing			 						LHAAA
Start the   Controller   Start the   Controller   Start the   St	59	(572)											SET	Auto/Manual
Year	60			Start the									SET	Y1000 Run/Stop
Start the controller   Start the								 						
Status rentioning processing	61			Start the									RST	
	62	(581)											RST	Y1000 Run/Stop
1000   1000	63												RST	Y1003 Auto/Manual
100	64 ×	Statusin	nonitoring n	mnessina				 						
X1008			X1000											
Manual   Control   Contr	65	(584)	Run/Stop											Running lamp
Control   Cont			X1008					 						Y31
Automatic control and	66	(587)	Manual control											Manual control lamp
68 (591) Auto lamp flicker in operation / stopped								 						Y32
68 (591) Auto lamp filicker in operation / stopped	67	(589)	Automati c control											Automatic control lamp
68 (591) Auto lamp flicker in operation / stopped			X100A					 						
Request command completio n  X102E  70 (595) Continuou s monitor being executed  X102D  71 (597) Continuou s settings being executed  X102D  Continuou s settings being executed	68	(591)	flicker in operation /stopped											flicker in operation lamp
completion  X102E  1   Y35  Continuou s monitor being executed lamp  X102D  1   (597) Continuou s settings being executed execute	69	(593)	Request											Request
s monitor being executed  X102D  X102D  1   Continuou s settings being executed  settings being executed  END-			completio n X102E					 						completion lamp
71 (597) Continuou s settings being executed Continuou settings be executed CEND-	70	(595)	s monitor being executed X102D											lamp Y36
	71		Continuou s settings being											Continuous settings being executed
	72	(599)						 						(END)

# Using method of ladder

- 1. Turn ON X10 (start communication), and connect with LE7-40GU.
- **2.** After X10 is executed, the required data for D100 to D133 are stored, and each function is executed in X20 to X24. List of used devices (The allocation is an example.)

Device name	Classification*1	Allocation function	Use
X10	Setting	Communication start	OPEN process to LE7-40GU (Active device) is performed, and after OPEN normal completion, communication by MODBUS/TCP protocol is started. (Turn on 5 seconds after turning on the power supply of LE7-40GU.)*2*3
D100 to D106	Setting	Request command + request code/data setting 0 to 3	Device set to use the request command
D110 to D113	Setting	Request command execution result 0 to 3	Request command execution result is stored.
D120 to D127	Setting	Continuous monitor 1 to 4	Continuous monitor execution result is stored.
D130 to D133	Setting	Continuous setting 1 to 3	Setting value of continuous setting is stored.
X20	Setting	Start request command access execution	Execute request command.
X21	Setting	Start continuous monitor execution	Start to execute continuous monitor.
X22	Setting	Start continuous setting execution	Start to execute continuous setting.
X23	Setting	Start stall execution	Start to execute stall.
X24	Setting	Start operation	Start to operate.
Y30	Monitoring	Run	Run: ON/Stop: OFF
Y31	Monitoring	Manual control	Manual control ON
Y32	Monitoring	Automatic control	Automatic control ON
Y33	Monitoring	Auto lamp flicker in operation	Auto lamp flicker in operation ON
Y34	Monitoring	Request command completion	ON when request command is completed
Y35	Monitoring	Continuous monitor being executed	ON when continuous monitor is being executed.
Y36	Monitoring	Continuous settings being executed	ON when continuous setting is being executed.
Y100	Monitoring	OPEN execution status flag	This flag is turned on during the execution of FB for OPEN process.*2
Y101	Monitoring	OPEN normal completion flag	This flag is turned on when FB for OPEN process is completed normally.*2
Y102	Monitoring	OPEN abnormal completion flag	This flag is turned on when FB for OPEN process is completed abnormally.*2
Y103	Monitoring	CLOSE execution status flag	This flag is turned on during the execution of FB for CLOSE process.*2
Y104	Monitoring	CLOSE normal completion flag	This flag is turned on when FB for CLOSE process is completed normally.*2
Y105	Monitoring	CLOSE abnormal completion flag	This flag is turned on when FB for CLOSE process is completed abnormally.*2
Y106	Monitoring	Protocol execution complete flag	ON for one scan by a completion of SP.ECPRTCL instruction*2
D50	Monitoring	Error code during OPEN error	An error code is stored at the time of abnormal completion.*2
D51	Monitoring	Error code during CLOSE error	An error code is stored at the time of abnormal completion.*2
D0 to D16	System	Device for SP.ECPRTCL	Device used in an application instruction SP.ECPRTCL*3
D1000 to D1134	System	Device for protocol No. 1 (04: RD IN Register)	Store the data used in protocol communication.*4
D2000 to D2134	System	Device for protocol No. 2 (16: WR Multi Register)	

#### \*1 Classification

Setting: items to be set/input when using functions Monitoring: items to monitor output when using functions System: Used for internal processing, setting is unnecessary

- \*2 For details of the device, refer to the following.
  - MELSEC iQ-R Ethernet/CC-Link IE Function Block Reference
- \*3 For details of the device, refer to the following.
  - MELSEC iQ-R Programming Manual (Instructions, Standard Functions/Function Blocks)
- \*4 For details of the device, refer to the following.
  - MELSEC iQ-R Ethernet User's Manual (Application)

# 6 N:N NETWORK

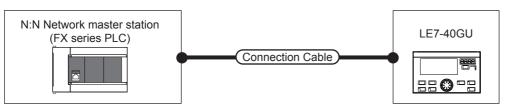
LE7-40GU can be operated as a local station for FX PLC N:N network communication.

Data monitoring and parameter writing from a master station FX PLC for up to seven local stations (LE7-40GU units) can be carried out.

### **Precautions**

- For 5 seconds after turning on the power of LE7-40GU, data from master station will not be accepted.
- Initial setting of LE7-40GU can not be done only with N:N Network.
- Simultaneous use of N:N Network and CC-Link communication is not possible.

# **6.1** System Configuration



Connection equipment	Communication form	Connection cable	Tension controller (Local station)		Connectable No. of units
		Cable type name	Optional equipment	Main unit	
FX5 PLC (master station)	RS-485	User created	— (Built-in to main unit)	LE7-40GU	Up to seven local stations (LE7- 40GU) from the master station

# 6.2 Wiring

This section describes wiring.

## Selection of cable

Use the following procedure to select cables.

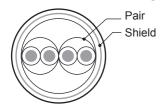
## Twisted pair cable

Use a shield twisted pair wire for connection with RS-485 communication equipment.

## ■RS-485 cable specification

Item	Specifications
Cable type	Shielded cable
Pairs	2 p, 3 p
Conductor resistance (20°C)	88.0 $\Omega$ /km or less
Insulation resistance	10000 M $\Omega$ -km or more
Withstand voltage	500 V DC1 minute
Capacitance (1 kHz)	An average of 60 nF/km or less
Characteristic impedance (100 kHz)	110±10 Ω

### **■**Construction drawing of the cables (reference)



Construction drawing example of a two twisted-pair cable



Construction drawing example of a three twisted-pair cable

# Spring clamp terminal block

Connection to LE7-40GU should be performed as the following procedure.

#### **■**Wire size

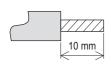
No. of wire per terminal	Wire size							
	Single wire/Strandwire	Ferrules with insulation sleeve	Ferrules withoutinsulation sleeve					
One wire	AWG24 to 16	AWG23 to 16	AWG23 to 16					

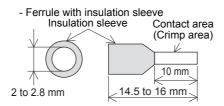
#### **■**Treatment of wire ends

Strip the cable about 10 mm from the tip to connect a wire ferrule at the striped area. Failure to do so may result in electric shock or short circuit between adjacent terminals because of the conductive part. If the wire strip length is too short, it may result in the poor contact to the spring clamp terminal part.

When using a wire ferrule with an insulating sleeve, choose a wire with proper cable sheath referring to the above outside dimensions, otherwise the wire cannot be inserted easily.

- Strand wire/single wire





The following table shows wire ferrules and tools for wire ferrules compatible with the terminal block. Use of items other than these may result in not being able to remove the wire ferrule, so carefully check that the wire ferrule can be unplugged. <Reference product>

Manufacturer	Model	Wire size	Crimp tool
PHOENIX CONTACT	AI 0.5-10 WH	0.5 mm <sup>2</sup>	CRIMPFOX 6
GmbH & Co. KG	AI 0.75-10 GY	0.75 mm <sup>2</sup>	
	A 1.0-10	1.0 mm <sup>2</sup>	
	A 1.5-10	1.5 mm <sup>2</sup>	

#### **■**Connection and disconnection of the cable

Spring clamp terminal block is push-in type, therefore, wiring without a tool is possible by simply inserting the connecting terminal to the terminal block. However, the stranded wire does not comply with the push-in type, and a tool is required for connecting cables.

· Connection of the cable

Fully insert a cable or bar solderless terminal whose end has been properly processed into the wire insertion opening. If the cable or bar solderless terminal cannot be inserted with this procedure, fully insert the cable or bar solderless terminal while pushing the open/close button with a flathead screwdriver having a tip width of 2.0 to 2.5 mm. After fully inserting the cable, remove the screwdriver.

Do not tighten terminal screws exceeding the specified torque range. Otherwise it may cause equipment failure or malfunction

When wiring with the thick electric wire, make sure to prevent the conductive parts from protruding to the front of the terminal block.

#### <Reference>

Manufacturer	Model
PHOENIX CONTACT GmbH & Co. KG	SZS 0.4×2.5 VDE

#### · Disconnection of the cable

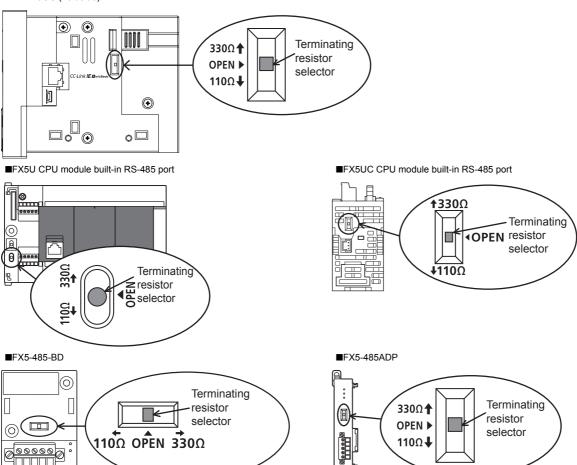
While pushing the open/close button with a flathead screwdriver having a tip width of 2.0 to 2.5 mm, disconnect the cable or bar solderless terminal.

# **Terminating resistor settings**

Be sure to install terminating resistors at both ends of the line.

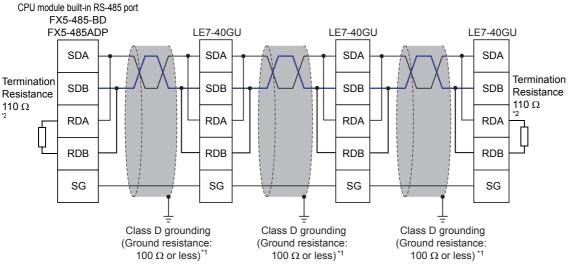
LE7-40GU, the built-in RS-485 port of the CPU module, FX5-485-BD, and FX5-485ADP, have built-in terminating resistors. Set to 110  $\Omega$  with the terminating resistor changeover switch.

■LE7-40GU (Left side)



# **Connection diagram**

Use single pair wiring for N:N Network wiring.

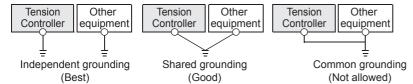


- \*1 Be sure to apply Class D grounding to the shield of the twisted pair cable to be connected.
- \*2 Terminal resistor should be attached to both ends of the line. LE7-40GU, the built-in RS-485 port of the CPU module, FX5-485-BD, and FX5-485ADP, have built-in terminating resistors. Set the terminal resistor with the selector.

# Grounding

Grounding should be performed as stated below.

- Perform Class D grounding. (Ground resistance: 100  $\Omega$  or less)
- · Independent grounding should be performed for best results.
- When independent grounding cannot be performed, perform "shared grounding" as shown in the following figure.



The grounding wire size should be AWG 24 to 16 (cross-section area: 0.2 to 1.5 mm<sup>2</sup>).

The grounding point should be close to the tension controller, and all grounding wires should be as short as possible.

# 6.3 Communication Setting

# **Communication specifications**

The communication specification of the N:N Network is as follows.

# Communication specifications

Item	Specifications
Transmission standard	Conforms to RS-485 standard
Maximum transmission distance	50 m
Communication method	Bidirectional half-duplex
Wiring method	One-pair wiring
Communication procedure	N:N Network (pattern 2 only)
Transmission speed (baud rate)	N:N Network: 38,400 (bps)
Insulation	Non-isolated (between the communication line and CPU)

# Link pattern

LE7-40GU supports pattern 2 as a link pattern.

For pattern 2, it is possible to exchange link data of 64 bit devices (M) and 8 word devices (D) at each station.

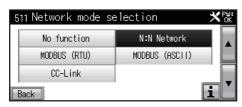
This is used to monitor and configure the local stations from the master station.

Station No.		Pattern 2	
		Bit device (M)	Word device (D)
		64 devices per station	8 devices per station
Master station	Station No. 0	M1000 to M1063	D0 to D7
Local station	Station No. 1	M1064 to M1127	D10 to D17
	Station No. 2	M1128 to M1191	D20 to D27
	Station No. 3	M1192 to M1255	D30 to D37
	Station No. 4	M1256 to M1319	D40 to D47
	Station No. 5	M1320 to M1383	D50 to D57
	Station No. 6	M1384 to M1447	D60 to D67
	Station No. 7	M1448 to M1511	D70 to D77

# **Communication parameter settings**

When using N:N Network, set the communication parameters with the following procedure.

1. On the LE7-40GU screen "Network mode selection" screen, select "N:N Network".



**2.** Change to 1 to 7<sup>\*1</sup> in accordance with the local station No. to be assigned with the "N:N Network station No. setting" on the LE7-40GU screen, in accordance with the local station No. to be assigned.



- 3. Restart LE7-40GU.
- \*1 If the set value is "0", N:N Network will not operate.

# Link data configuration

The contents of the link data differs depending on the master and local station areas.

The following shows the details of device M and D.

• Device M configuration of the master station

Device No.	Signal name	Signal name ON (data value=1)	OFF (data value=0)
M1000	Run/Stop	Run	Stop
M1001	Reel change B axis/A axis	B axis control	A axis control
M1002	Control output OFF/ON	Control output OFF	Control output ON
M1003	Auto/Manual	Automatic control	Manual control
M1004	Stall memory ON/OFF	Stall memory ON	Stall memory OFF
M1005	Gain 1 ON/OFF	Gain 1 ON	Gain 1 OFF
M1006	Gain 2 ON/OFF	Gain 2 ON	Gain 2 OFF
M1007	Inching ON/OFF	Inching ON	Inching OFF
M1008	Cutting torque ON/OFF	Cutting torque ON	Cutting torque OFF
M1009	Constant tension ON/OFF	Constant tension ON	Constant tension OFF
M1010	Predrive ON/OFF	Predrive ON	Predrive OFF
M1011	Memory hold ON/OFF	Memory hold ON	Memory hold OFF
M1012	Reverse run/Forward run	Reverse run operation	Forward run operation
M1013	_	_	_
M1014	_	_	_
M1015	_	_	_
M1016	Alarm reset ON/OFF	Alarm reset ON	Alarm reset OFF
M1017	Reel diameter reset ON/OFF	Reel diameter reset ON	Reel diameter reset OFF
M1018	Measurement length and remaining length	Measurement length and remaining length	Measurement length and remaining length
M4040	reset ON/OFF	reset ON	reset OFF
M1019	_	_	_
M1020	-	<del>-</del>	<u> </u>
M1021	-	<del>-</del>	<u> </u>
M1022		_	<u> </u>
M1023	-		Name I
M1024	Zero adjustment execution	Execution	Normal
M1025	Span adjustment execution	Execution  Start maximum diameter teaching execution	Normal
M1026	Maximum diameter teaching execution	Start maximum diameter teaching execution	Normal
M1027	Minimum diameter teaching execution	Start minimum diameter teaching execution	Normal
M1028	Control gain tuning execution	Start control gain tuning execution	Normal
M1029	Speed teaching execution	Start speed teaching execution	Normal
M1030	-	<del>-</del>	<u> </u>
M1031	-	<del>-</del>	_
M1032	-	<del>-</del>	<u> </u>
M1033	<u> </u>	<del>-</del>	_
M1034	_	_	_
M1035	_	_	_
M1036	_	_	_
M1037	_	_	_
M1038	_	_	_
M1039	_	_	_
M1040	_	-	_
M1041	_	_	_
M1042	_	_	_
M1043	_	_	_
M1044	Link tension monitor digit ×10/×1	Link tension monitor digit ×10	Link tension monitor digit ×1
M1045	Continuous settings execution	Start continuous settings execution	Normal
M1046	Continuous monitor execution	Start continuous monitor execution	Normal

Device No.	Signal name	Signal name ON (data value=1)	OFF (data value=0)
M1047	Request command execution	Start request command execution	Normal
M1048	_	_	_
M1049	_	_	_
M1050	-	-	_
M1051	-	-	_
M1052	-	-	_
M1053	-	-	_
M1054	-	-	_
M1055	-	-	_
M1056	-	-	_
M1057	-	-	_
M1058	-	-	_
M1059	-	-	_
M1060	_	_	_
M1061	_	_	_
M1062	_	_	_
M1063	_	_	_

# Device M configuration of the local station

Mn is the first device of the M device of each local station. (Station No.1: M1064, Station No. 2: M1128...)

Device No.	Signal name	Signal name ON (data value=1)	OFF (data value=0)
Mn+0	Run/Stop	Run	Stop
Mn+1	Output ON/OFF	Output ON	Output OFF
Mn+2	B-axis controlled/A-axis controlled	B-axis controlled	A-axis controlled
Mn+3	Constant tension ON/OFF	Constant tension ON	Constant tension OFF
Mn+4	Predrive being executed	Predrive being executed	Normal
Mn+5	Memory hold being executed	Memory hold being executed	Normal
Mn+6	Reverse running/Forward running	Reverse running	Forward running
Mn+7	_	_	_
Mn+8	Manual control	Manual control	_
Mn+9	Automatic control	Automatic control	_
Mn+10	Auto lamp flicker in operation/stopped	Auto lamp flicker in operation	Auto lamp flicker stopped
Mn+11	Stall setting output being executed	Stall setting output being executed	Normal
Mn+12	Stall memory output being executed	Stall memory output being executed	Normal
Mn+13	Start timer operation being executed	Start timer operation being executed	Normal
Mn+14	Stop timer operation being executed	Stop timer operation being executed	Normal
Mn+15	Preset timer operation being executed	Preset timer operation being executed	Normal
Mn+16	Cut torque operation being executed	Cut torque operation being executed	Normal
Mn+17	Inching operation being executed	Inching operation being executed	Normal
Mn+18	_	_	_
Mn+19	Zero adjustment being executed	Zero adjustment being executed	Normal
Mn+20	Span adjustment being executed	Span adjustment being executed	Normal
Mn+21	Maximum diameter teaching being executed	Speed teaching being executed	Normal
Mn+22	Minimum diameter teaching being executed	Speed teaching being executed	Normal
Mn+23	Control gain tuning being executed	Control gain tuning being executed	Normal
Mn+24	Speed teaching being executed	Speed teaching being executed	Normal
Mn+25	Tension upper limit detection ON/OFF	Tension upper limit detection ON	Tension upper limit detection OFF
Mn+26	Tension lower limit detection ON/OFF	Tension lower limit detection ON	Tension lower limit detection OFF
Mn+27	Detection outside tension range ON/OFF	Detection outside tension range ON	Detection outside tension range OFF
Mn+28	Reel diameter detection 1 ON/OFF	Reel diameter detection 1 ON	Reel diameter detection 1 OFF
Mn+29	Reel diameter detection 2 ON/OFF	Reel diameter detection 2 ON	Reel diameter detection 2 OFF
Mn+30	Reel diameter detection 3 ON/OFF	Reel diameter detection 3 ON	Reel diameter detection 3 OFF

Signal name	Signal name ON (data value=1)	OFF (data value=0)
Measurement length/remaining length detection 1 ON/OFF	Measurement length/remaining length detection 1 ON	Measurement length/remaining length detection 1 OFF
Measurement length/remaining length detection 2 ON/OFF	Measurement length/remaining length detection 2 ON	Measurement length/remaining length detection 2 OFF
Measurement length/remaining length detection 3 ON/OFF	Measurement length/remaining length detection 3 ON	Measurement length/remaining length detection 3 OFF
Peripheral speed synchronization detection ON/OFF	Peripheral speed synchronization detection ON	Peripheral speed synchronization detection OFF
Alarm occurrence detection	Alarm occurrence	Normal
Parameter protection being executed	Parameter protection being executed	Normal
Settings password matching being executed	Settings password matching being executed	Settings password does not match
Monitor password matching being executed	Monitor password matching being executed	Monitor password does not match
_	_	_
_	_	_
_	_	_
_	_	_
_	_	_
_	_	_
Continuous settings being executed	Continuous settings being executed	Normal
Continuous monitor being executed	Continuous monitor being executed	Normal
Request command completion	Request command completion	Normal
_	_	_
_	_	_
_	_	_
_	_	_
_	_	_
_	_	_
_	_	_
_	_	_
_	_	_
_	_	_
_	_	_
_	_	_
_	_	_
_	_	_
_	_	_
1		I .
	Measurement length/remaining length detection 1 ON/OFF  Measurement length/remaining length detection 2 ON/OFF  Measurement length/remaining length detection 3 ON/OFF  Peripheral speed synchronization detection ON/OFF  Alarm occurrence detection  Parameter protection being executed  Settings password matching being executed  Monitor password matching being executed  — — — — — Continuous settings being executed  Continuous monitor being executed  Request command completion — — — — — — — — — — — — — — — — — — —	Measurement length/remaining length detection 1 ON/OFF  Measurement length/remaining length detection 2 ON/OFF  Measurement length/remaining length detection 2 ON/OFF  Measurement length/remaining length detection 3 ON/OFF  Peripheral speed synchronization detection ON/OFF  Alarm occurrence detection  Parameter protection being executed  Settings password matching being executed  Monitor password matching being executed  Monitor password matching being executed  Continuous settings being executed  Continuous settings being executed  Continuous monitor being executed  Request command completion  Request command completion  ———————————————————————————————————

• Device D configuration of the master station and local station

Dn is the first device of the D device of each local station. (Station No. 1: D10, Station No. 2: D20...)

Master station	Master station			
Device No	Signal name			
D0	Station No. command	Station No. command		
D1	Continuous settings 1	Continuous settings 1		
D2	Continuous settings 2	Continuous settings 2		
D3	_			
D4	Request command 0	Request code 0		
D5	Setting data 0	Setting data 0		
D6	Request command 1	Request command 1 Request code 1		
D7	Setting data 1			

Local station		
Device No.	Signal name	
Dn+0	Continuous monitor 1	
Dn+1	Continuous monitor 2	
Dn+2	Continuous monitor 3	
Dn+3	Continuous monitor 4	
Dn+4	Continuous monitor 5	
Dn+5	_	
Dn+6	Request command 0 execution result	
Dn+7	Request command 1 execution result	

# **Station Number command**

The D device (D 0) station No. command of the master station determines the station No. of the local station to be accessed. By setting the station No. command to 0, simultaneous setting and simultaneous monitoring can be performed for all local stations.

Station No. command	Function
1 to 7	Individual access to the specified local station
0	Simultaneous access to all the local stations

# Continuous setting/continuous monitoring

When continuous setting execution and continuous monitor execution of the master station are turning on, data set by continuous setting function selection and continuous monitoring function selection can be set and monitored continuously. For continuous setting data, the data set for RAM writing is not stored in a power failure.

Continuous monitor data can monitor the latest data of the local station at the time when there is a transmission request from the master station.

However, in updating parameters with a monitor update period in the setting of the local station, if this update period setting is longer than the transmission request from the master station, data update is performed by this update cycle.

# Continuous settings

- 1. Data write to devices with continuous settings 1 to 16
- **2.** Turn on continuous settings execution.

#### Continuous monitor

- **1.** Turn on continuous monitor execution.
- 2. Read the data of the devices of continuous monitors 1 to 16.

# Access by request command

For any data access from the master station to the local station, data can be read or written by handshaking between the "request command execution" flag and the "request command completion" flag.

This access is performed using a 2-word word device of the master station.

In the double word data, the 4 high-order bits of the first word are assigned to the request command and the 12 low-order bits are assigned to the request code, and the second word is assigned as the word for the set data.

bit 15 to 12	bit 11 to 0
Request command	Request code
Setting data	·

There are three types of request command, Data Monitor, Writing to RAM, and Writing to RAM + ROM, according to the selection of data reading and writing method.

Monitor	Writing to RAM	Writing to RAM + ROM
Writing data is reflected in the settings based on a	Writing data is reflected in the settings based on a	Perform the above RAM write + data power failure
data read request from the master station but is not	data write request from the master station but is not	write.
stored in the case of a power failure.	stored in the case of a power failure.	

In the ROM for storage against power interruption, the allowable number of times of writing is limited. Accordingly, data cyclically written and updated by the PLC must be written only to the RAM.

Request command	Contents of execution	Execution result
Н0	Monitor	Monitored value
H1	Writing to RAM	Writing result
H2	Writing to RAM + ROM	Writing result

The request code indicates the data No. (address) of data for which the request command is executed. Also, the subsequent data setting is the data to be written to that data number.

If the request command is a monitor, the data setting data is ignored.

When double word data is written to send data in the master station, and the handshake is executed by turning ON/OFF the request command execution flag and request command completion flag as follows, the local station sends back the request command execution request.

- **1.** The master station is set to request command execution ON.
- 2. The local station processes in accordance with the master station request command execution ON.
- 3. The local station is set to request command completion ON.
- **4.** The master station receives the request command completion ON.
- 5. The master station is set to request command execution OFF.
- **6.** The local station receives the request command execution OFF from the master station.
- 7. The local station is set to request command completion OFF.
- 8. The master station receives the request command completion OFF.

Please perform reading of the execution results of the request command between step 4 and 5 of the handshake procedure. If an error occurs, triggered by the request command from the master station, the local station turns ON the network alarm occurrence flag and outputs the device No. that has the error to the monitor of the device number of the network alarm. For the request command execution result, refer to the following.

**LILE7-CCL APPLICATION MANUAL** 

# Request code

The numerical value of each parameter corresponding to the request code is treated as real number data without a decimal point.

In addition, the minimum and maximum values are determined for LE7-40GU, and when a value exceeding this data is written, it is automatically rewritten to the minimum or maximum value.

In this case, an "Out of data range" alarm is generated.

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H000(0)	_	_	_	_	_	_
H001(1)	Total tension	Monitor	_	0 or less	2000 or more	N/×10 N
H002(2)	Left tension	Monitor	_	0 or less	2000 or more	N/×10 N
H003(3)	Right tension	Monitor	_	0 or less	2000 or more	N/×10 N
H004(4)	Left input voltage	Monitor	_	-1500 or less	1500 or more	mV
H005(5)	Right input voltage	Monitor	_	-1500 or less	1500 or more	mV
H006(6)	_	_	_	_	_	_
H007(7)	_	_	_	_	_	_
H008(8)	_	_	_	_	_	_
H009(9)	_	_	_	_	_	_
H00A(10)	_	_	_	_	_	_
H00B(11)	_	_	_	_	_	_
H00C(12)	_	_	_	_	_	_
H00D(13)	_	_	_	_	_	<del> </del>
H00E(14)	_	_	_	_	_	_
H00F(15)	_	_	_	_	_	_
H010(16)	Tension upper limit detection	Setting	_	0	Tension full scale	N/×10 N
H011(17)	Tension lower limit detection	Setting	_	0	Tension full scale	N/×10 N
H012(18)	Detection outside target tension range	Setting	_	0	50	%
H013(19)	Tension display filter	Setting	_	5	80	sec
H014(20)	Tension detection filter	Setting	_	0	80	sec
H015(21)	Tension output filter	Setting	_	0	80	sec
H016(22)	_	_	_	_	_	_
H017(23)	_	_	_	_	_	_
H018(24)	_	_	_	_	_	_
H019(25)	_	_	_	_	_	_
H01A(26)	_	_	_	_	_	_
H01B(27)	_	_	_	_	_	_
H01C(28)	_	_	_	_	_	_
H01D(29)	_		_	_	_	_
H01E(30)	_	_	_	_	_	_
H01F(31)	_		_	_	_	_
H020(32)	Sensor input type selection	Setting	_	0 (LX type), 1 (strain	dande)	_
H021(33)	Tension full scale	Setting	_	1	2000	N/×10 N
H022(34)	Tension display decimal point selection	Setting	_	0 (1), 1 (0.1), 2 (0.01		_
H023(35)	Tension display unit selection	Setting	_	0 (N), 1 (×10 N)	,	_
H024(36)	Span target tension	Setting	_	1	Tension full scale	N/×10 N
H025(37)	Left manual zero calibration	Setting	_	-999	999	N/×10 N
H026(38)	Right manual zero calibration	Setting	_	-999	999	N/×10 N
H027(39)	Left manual span calibration	Setting	_	50	300	%
H028(40)	Right manual span calibration	Setting	_	50	300	%
H029(41)	—		_	_	_	
H029(41)	<del> -</del>		_	_	_	+
H02B(43)	<u> </u>	<u> </u>	-  -		_	1

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H02C(44)	_	_	_	_	_	_
H02D(45)	_	_	_	_	_	_
H02E(46)	-	_	_	_	_	_
H02F(47)	-	_	_	_	_	_
H030(48)	Reel diameter	Monitor	_	1	2000	mmφ
H031(49)	Target line velocity	Monitor	LE7-DCA	0	10000	m/min
H032(50)	Line acceleration	Monitor	LE7-DCA	0	50	m/min/sec
H033(51)	Measurement length/remaining length	Monitor	LE7-DCA	_	_	m
H034(52)	Reel rotational speed	Monitor	LE7-DCA	65000	1	r/min
H035(53)	New reel rotational speed	Monitor	LE7-DCA	3600	1	r/min
H036(54)	Constant slip ROTO speed command output	Monitor	LE7-DCA	1000	0.1	%
H037(55)	Predrive rotation speed command output	Monitor	LE7-DCA	1000	0.1	%
H038(56)	Predrive target rotation speed	Monitor	LE7-DCA	3600	1	r/min
H039(57)	Reel diameter CALC adapter ROM version	Monitor	LE7-DCA	999	0.01	_
H03A(58)	_	_	_	_	_	_
H03B(59)		_	_	_	_	_
H03C(60)	<del> </del> _	_	_			_
H03D(61)	_	_	_	_	_	_
H03E(62)	_	_	_	_	_	_
H03F(63)	_			_	_	_
H040(64)	Initial diameter	Setting	LE7-DCA	1	2000	mmφ
	Material thickness	Setting	LE7-DCA	0	10000	<u> </u>
H041(65)				0	2000	μm
H042(66)	Reel diameter detection 1	Setting	LE7-DCA	-		mmφ
H043(67)	Reel diameter detection 2	Setting	LE7-DCA	0	2000	mmφ
H044(68)	Reel diameter detection 3	Setting	LE7-DCA	0	2000	mmφ
H045(69)	Measurement/remaining length detection 1	Setting	LE7-DCA	0	65000	m
H046(70)	Measurement/remaining length detection 2	Setting	LE7-DCA	0	65000	m
H047(71)	Measurement/remaining length detection 3	Setting	LE7-DCA	0	65000	m
H048(72)	Accelerating judgment acceleration	Setting	LE7-DCA	0	10	m/min/sec
H049(73)	Reel rotational speed gain	Setting	LE7-DCA	0	150	%
H04A(74)	Reel rotational speed bias	Setting	LE7-DCA	0	100	%
H04B(75)	Reel rotational speed startup gain	Setting	LE7-DCA	1	5	Time (s)
H04C(76)	Reel rotational speed startup timer	Setting	LE7-DCA	0	10	sec
H04D(77)	Predrive time	Setting	LE7-DCA	0	200	sec
H04E(78)	Predrive bias	Setting	LE7-DCA	-10	10	%
H04F(79)	_	_	_	_	_	_
H050(80)	Maximum diameter	Setting	_	Minimum diameter	2000	mmφ
H051(81)	Minimum diameter	Setting	_	1	Maximum diameter	mmφ
H052(82)	Teaching speed	Setting	LE7-DCA	1	10000	m/min
H053(83)	Velocity electronic gear ratio	Setting	LE7-DCA	9000	18000	%
H054(84)	Reel selection	Setting	LE7-DCA	0(unwinding), 1(wind	ling)	_
H055(85)	Number of reel pulse	Setting	LE7-DCA	0 (1 pulse), 1 (2 puls pulses), 4 (16 pulses	es), 2 (4 pulses), 3 (8	_
H056(86)	Reel diameter calculation cycle	Setting	LE7-DCA	0 (1 pulse), 1 (2 puls pulses), 4 (16 pulses	es), 2 (4 pulses), 3 (8	_
H057(87)	MEAS/RMN length calculation switch	Setting	LE7-DCA	0 (measurement leng length)	gth), 1 (remaining	_
H058(88)	Material thickness unit	Setting	LE7-DCA	0 (×1), 1 (×0.1)		_
H059(89)	Maximum line acceleration	Setting	LE7-DCA	1	50	m/min/sec
H05A(90)	Maximum reel rotational speed	Setting	LE7-DCA	1	3600	r/min
H05B(91)	Detection output selection	Setting	LE7-DCA	0 (Reel diameter), (n		_
H05C(92)	Detection output holding selection	Setting	LE7-DCA	0 (non-holding), 1 (h	oldina)	_

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H05D(93)	Run/Stop judgment selection	Setting	LE7-DCA	0 (contact + internal), (internal)	1 (contact), 2	_
H05E(94)	Run judgment speed	Setting	LE7-DCA	Stop judgment speed	30	m/min
H05F(95)	Stop judgment speed	Setting	LE7-DCA	1	Run judgment speed	m/min
H060(96)	_	_	_	_	_	_
H061(97)	_	_	_	_	_	_
H062(98)	_	_	_	_	_	_
H063(99)	_	_	_	_	_	_
H064(100)	_	_	_	_	_	_
H065(101)	_	_	_	_	_	_
H066(102)	_	_	_	_	_	_
H067(103)	_	_	_	_	_	_
H068(104)	_	_	_	_	_	_
H069(105)	_	_	_	_	_	_
H06A(106)	_	_	_	_	_	_
H06B(107)	_	_	_	_		_
H06C(108)	_	_	_	_	_	_
H06D(109)	_	_	_	_	_	_
H06E(110)	_	_	_	_	_	_
H06F(111)	_	_	_	_	_	_
H070(112)	Target tension	Monitor	_	0	2000	N/×10 N
H071(113)	Control output	Monitor	_	-1000 or less	1000 or more	%
H072(114)	Torque output	Monitor	_	-1000 or less	1000 or more	%
H073(115)	_	_	_	_	_	_
H074(116)	_	_	_	_	_	_
H075(117)	Control output voltage for powder	Monitor	_	260 or more	0.1	V
H076(118)	Control output current for powder	Monitor	_	400 or more	0.01	A
H077(119)		_	_	_	_	_
H078(120)	_	_	_	_	_	_
H079(121)	_	_	_	_	_	_
H07A(122)		_	_	_	_	_
H07B(123)	_	_	_	_	_	_
H07C(124)	_	_	_	_	_	_
H07D(125)	_		_	_	_	_
H07E(126)	_		_	_	_	_
H07F(127)	_	-  -	_	_	_	_
H080(128)			_	1	Tension full scale	N/×10 N
H081(129)	Tension setting  Manual setting	Setting	_	-1000	1000	%
H082(130)	<u> </u>	Setting	-  -	0	1000	%
H082(130)	Stall setting Start timer	Setting Setting	_	0	300	
			_	0		sec
H084(132)	Stop gain	Setting			1000	sec %
H085(133)	Stop gain	Setting	_	5	400	%
H086(134)	Stop bias	Setting	LEZ DCA	0	100	
H087(135)	Acceleration/deceleration torque setting	Setting	LE7-DCA	0	1000	%
H088(136)	Gain 1	Setting	_	5	400	%
H089(137)	Gain 2	Setting	_	5	400	%
H08A(138)	Internal taper ratio	Setting	_	0	80	%
H08B(139)	External linear line taper ratio	Setting	_	0	100	%
H08C(140)	New reel preset	Setting	_	0	1000	%
H08D(141)	New reel preset timer	Setting	_	0	300	sec
H08E(142)	Cutting torque	Setting	_	0	1000	%

Request	Name	Monitor/	Extension	Minimum value	Maximum value	Unit
code		settings	option			
H08F(143)	_	_	_	_	_	_
H090(144)	Broken line taper corner 1	Setting	_	1	2000	mmφ
H091(145)	Broken line taper ratio 1	Setting	_	0	100	%
H092(146)	Broken line taper corner 2	Setting	_	1	2000	mmφ
H093(147)	Broken line taper ratio 2	Setting	_	0	100	%
H094(148)	Broken line taper corner 3	Setting	_	1	2000	mmφ
H095(149)	Broken line taper ratio 3	Setting	_	0	100	%
H096(150)	Broken line taper corner 4	Setting	_	1	2000	mmφ
H097(151)	Broken line taper ratio 4	Setting	_	0	100	%
H098(152)	Broken line taper corner 5	Setting	_	1	2000	mmφ
H099(153)	Broken line taper ratio 5	Setting	_	0	100	%
H09A(154)	Broken line taper corner 6	Setting	_	1	2000	mmφ
H09B(155)	Broken line taper ratio 6	Setting	_	0	100	%
H09C(156)	Broken line taper corner 7	Setting	_	1	2000	mmφ
H09D(157)	Broken line taper ratio 7	Setting	_	0	100	%
H09E(158)	Broken line taper corner 8	Setting	_	1	2000	mmφ
H09F(159)	Broken line taper ratio 8	Setting	_	0	100	%
H0A0(160)	Proportional gain	Setting	_	0	100	%
H0A1(161)	Integral time	Setting	_	0	100	%
H0A2(162)	Dead band gain	Setting	_	0	100 - Proportional gain	%
H0A3(163)	Dead band width	Setting	_	0	100	%
H0A4(164)	Tension control filter	Setting	_	0	40	sec
H0A5(165)	Static mechanical loss A	Setting	_	-1000	1000	%
H0A6(166)	Static mechanical loss B	Setting	_	-1000	1000	%
H0A7(167)	Kinetic mechanical loss A	Setting	LE7-DCA	-1000	1000	%
H0A8(168)	Kinetic mechanical loss B	Setting	LE7-DCA	-1000	1000	%
H0A9(169)	Mass correction gain A	Setting	LE7-DCA	0	100	%
H0AA(170)	Mass correction gain B	Setting	LE7-DCA	0	100	%
H0AB(171)	Mass correction bias A	Setting	LE7-DCA	0	100	%
H0AC(172)	Mass correction bias B	Setting	LE7-DCA	0	100	%
H0AD(173)		_	_	_	_	_
H0AE(174)	_	_	_	_	_	_
H0AF(175)	_	_	_	_	_	_
H0B0(176)	Control mode selection	Setting	LE7-DCA	0 (feedback control),	1 (open loop control)	_
H0B1(177)	Integral feedback limit	Setting	_	0	101	%
H0B2(178)	Feedback selection during the stop timer	Setting	_	0 (invalid), 1 (valid)	1	_
H0B3(179)	Automatic control output polarity selection	Setting	_	0 (forward), 1 (revers	e)	_
H0B4(180)	Open-loop control ratio	Setting	LE7-DCA	0	100	%
H0B5(181)	Taper function selection	Setting	_	0 (no function), 1 (into line taper (external)), (external)), 4 (direct t	ernal taper), 2 (linear 3 (broken line taper	_
H0B6(182)	Selection of two reel's switching FUNC	Setting	_	0 (invalid), 1 (valid)	- /	_
H0B7(183)	Internal taper standard selection	Setting	_	0 (zero standard), 1 (	stall standard)	_
H0B8(184)	_	_	_	_	_	_
H0B9(185)	Mechanical loss function selection	Setting	LE7-DCA	O (fixed mechanical loss), 1 (high function mechanical loss)		_
H0BA(186)	Stall automatic calculation gain	Setting	LE7-DCA	0	100	%
H0BB(187)	New reel preset AUTO calculation gain	Setting	LE7-DCA	0	100	%
H0BC(188)	Control output upper limit	Setting	_	Control output lower limit	101	%
H0BD(189)	Control output lower limit	Setting	_	-101	Control output	%
					upper limit	

Request code	Name	Monitor/	Extension option	Minimum value	Maximum value	Unit
H0BF(191)	_	_	_	_	_	_
H0C0(192)	Load model	Setting	_	0	200	_
H0C1(193)	Rated current	Setting	_	0	400	A
H0C2(194)	Maximum torque correction	Setting	_	50	250	%
H0C3(195)	Nonlinear correction 0	Setting	_	0	1000	%
H0C4(196)	Nonlinear correction 10	Setting	_	0	1000	%
H0C5(197)	Nonlinear correction 20	Setting	_	0	1000	%
H0C6(198)	Nonlinear correction 30	Setting	_	0	1000	%
H0C7(199)	Nonlinear correction 40	Setting	_	0	1000	%
H0C8(200)	Nonlinear correction 50	Setting	_	0	1000	%
H0C9(201)	Nonlinear correction 60	Setting	_	0	1000	%
H0CA(202)	Nonlinear correction 70	Setting	_	0	1000	%
H0CB(203)	Nonlinear correction 80	Setting	_	0	1000	%
H0CC(204)	Nonlinear correction 90	Setting	_	0	1000	%
H0CD(205)	_	_	_	_	_	_
H0CE(206)	_	_	_	_	_	_
H0CF(207)	_	_	_	_	_	_
H0D0(208)	_	_	_	_	_	_
H0D1(209)	Weak excitation	Setting	_	0	1000	%
H0D2(210)	Over current detection filter	Setting	_	0	20	sec
H0D3(211)	_	_	_	_	_	_
H0D4(212)	_	_	_	_	_	_
H0D5(213)	_	_	_	_	_	_
H0D6(214)	_	_	_	_	_	_
H0D7(215)	_	_	_	_	_	_
H0D8(216)	_	_	_	_	_	_
H0D9(217)	_	_	_	_	_	_
H0DA(218)	_	_	_	_	_	_
H0DB(219)	_	_	_	_	_	_
H0DC(220)	_	_	_	_	_	_
H0DD(221)	_	_	_	_	_	_
H0DE(222)	_	_	_	_	_	_
H0DF(223)	_	_	_	_	_	_
H0E0(224)	Contact input monitor	Monitor	_	0	0xFFFF	_
H0E1(225)	Contact output monitor	Monitor	_	0	0xFFFF	_
H0E2(226)	General-purpose analog input 1 monitor	Monitor	_	0	100	%
H0E3(227)	General-purpose analog input 2 monitor	Monitor	_	0	100	%
H0E4(228)	General-purpose analog input 3 monitor	Monitor	_	0	100	%
H0E5(229)	General-purpose analog output 1 monitor	Monitor	_	0	100	%
H0E6(230)	General-purpose analog output 2 monitor	Monitor	_	0	100	%
H0E7(231)	Analog output monitor for TENS control	Monitor	_	0	100	%
H0E8(232)	Analog output monitor for new reel preset	Monitor	_	0	100	%
H0E9(233)	Contact input monitor for reel DIA CALC	Monitor	LE7-DCA	0	0xFFFF	_
H0EA(234)	Contact output monitor for reel DIA CALC	Monitor	LE7-DCA	0	0xFFFF	_
H0EB(235)	Alarm display	Monitor	_	0	63	_
H0EC(236)	Network alarm device No.	Monitor	_	0	999	_
H0ED(237)	Main unit ROM version	Monitor	_	0	999	_
H0EE(238)	Network adapter ROM version	Monitor	LE7-CCL	0	999	_
H0EF(239)	Communication signal monitor	Monitor	_	0	0xFFFF	_
	I Company of the Comp		1	I.	I.	

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H0F0(240)	Contact input 1 function selection	Setting	_	0 (no function), 1 (rur		_
H0F1(241)	Contact input 2 function selection	Setting	_	output OFF/ON), 3 (stall memory), 4 (inching ON/OFF), 5 (constant tension ON/		_
H0F2(242)	Contact input 3 function selection	Setting	_	OFF), 6 (gain 1 ON/C		_
H0F3(243)	Contact input 4 function selection	Setting	_	1 / "	anual), 9 (reel change	_
H0F4(244)	Contact input 5 function selection	Setting	_	ON/OFF), 10 (cut torque ON/OFF), 11		_
H0F5(245)	Contact input 6 function selection	Setting	_	(alarm reset ON/OFF	)	_
H0F6(246)	-	_	_	_	_	_
H0F7(247)	_	_	_	_	_	_
H0F8(248)	Contact output 1 function selection	Setting	_	0 (no function), 1 (ter	sion lower limit	_
H0F9(249)	Contact output 2 function selection	Setting	_	detection), 2 (tension 3 (detection outside t (alarm occurrence de	• ,.	_
H0FA(250)	_	_	_	_	_	_
H0FB(251)	_	_	_	_	_	_
H0FC(252)	_	_	_	_	_	_
H0FD(253)	_	_	_	_	_	_
H0FE(254)	_	_	_	_	_	_
H0FF(255)	_	_	_	<del> </del>	_	_
H100(256)	Analog input mode selection	Setting	_	0 (0 to 5 V mode), 1	(0 to 10 V mode)	_
H101(257)	Analog input 1 function selection	Setting	_	0 (no function), 1 (ter	,	_
H102(258)	Analog input 2 function selection	Setting	_	setting), 3 (straight lir	• , ,	_
H103(259)	Analog input 3 function selection	Setting	_	4 (new axis preset setting), 5 (manual setting), 6 (tension input), 7 (Reel diameter input)		_
H104(260)	_	_	_	<u> </u>	_	_
H105(261)	_		_	_	_	_
H106(262)	<u> </u>	_	_	_	_	_
H107(263)		_	_	_	_	_
H108(264)	Analog output mode selection	Setting	_	0 (0 to 5 V mode), 1	(0 to 10 V mode)	_
H109(265)	Analog output 1 function selection	Setting	_			_
H10A(266)	Analog output 2 function selection	Setting	_	0 (no function), 1 (tension monitor), 2 (Reel diameter monitor), 3 (tension setting monitor), 4 (A-axis Reel shaft rotational speed output), 5 (B-axis Reel shaft rotational speed output)		_
H10B(267)	Analog output 1 gain	Setting	_	500	3000	%
H10C(268)	Analog output 2 gain	Setting	_	500	3000	%
H10D(269)	Analog output 1 bias	Setting	_	-500	500	%
H10E(270)	Analog output 2 bias	Setting	_	-500	500	%
H10F(271)	-	_	_	_	_	_
H110(272)	Two reel's switching FUNC output mode	Setting	_	0 (no internal switchin switching)	ng), 1 (with internal	_
H111(273)	Control output mode selection	Setting	_	0 (0 to 5 V mode), 1 (-5 to 5 V mode), 2 (0 to 10 V mode), 3 (-10 to 10 V mode), 4 (0 to 8 V mode), 5 (-8 to 8 V mode), 6 (0 to 2.7 V mode), 7 (-2.7 to 2.7 V mode), 8 (1 to 5 V mode)		_
H112(274)	Control output gain	Setting	_	500	3000	%
H113(275)	New reel preset output gain	Setting	_	500	3000	%
H114(276)	Control output bias	Setting	_	-500	500	%
H115(277)	New reel preset output bias	Setting	_	-500	500	%
H116(278)	_	_	_	_	_	_
H117(279)	_	_	_	_	_	_
H118(280)	_	_	_	_	_	_
·/	+		-	-	1	-
H119(281)	_	<b>—</b>	I —	I —	_	I —
H119(281) H11A(282)	_	<u> </u>	_	_	<del>-</del>	_

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H11C(284)	_	_	_	_	_	_
H11D(285)	_	_	_	_	_	_
H11E(286)	_	_	_	_	_	_
H11F(287)	_	_	_	_	_	_
H120(288)	Set setting password	Setting	_	0	32000	_
H121(289)	Input setting password	Setting	_	0	32000	_
H122(290)	Set monitor password	Setting	_	0	32000	_
H123(291)	Input monitor password	Setting	_	0	32000	_
H124(292)	_	_	_	_	_	_
H125(293)	_	_	_	_	_	_
H126(294)	_	_	_	_	_	_
H127(295)	_	_	_	_	_	_
H128(296)	_	_	_	_	_	_
H129(297)	_	_	_	_	_	_
H12A(298)	_	_	_	_	_	_
H12B(299)	_	_	_	_	_	_
H12C(300)	_	_	_	_	_	_
H12D(301)	_	_	_	_	_	_
H12E(302)	_	_	_	_	_	_
H12F(303)	_	_	_	_	_	_
H130(304)	Alarm history 1	Monitor	_	0	63	_
H131(305)	Alarm history 2	Monitor	_	0	63	_
H132(306)	Alarm history 3	Monitor	_	0	63	_
H133(307)	Alarm history 4	Monitor	_	0	63	_
H134(308)	Alarm history 5	Monitor	_	0	63	_
H135(309)	Alarm history 6	Monitor	_	0	63	_
H136(310)	Alarm history 7	Monitor	_	0	63	_
H137(311)	Alarm history 8	Monitor	_	0	63	_
H138(312)	Alarm history holding selection	Setting	_	0 (no holding), 1 (hold		_
H139(313)	Alarm display time	Setting	_	0	301	sec
H13A(314)	Alarm operation selection 1	Setting	_	0	0xFFFF	_
H13B(315)	Alarm operation selection 2	Setting	_	0	0xFFFF	_
H13C(316)	Alarm operation selection 3	Setting	_	0	0xFFFF	_
H13D(317)	Alarm operation selection 4	Setting	_	0	0xFFFF	_
H13E(318)	_		_	_	_	_
H13F(319)	_	_	_	_	_	_
H140(320)	_	_	_	_	_	_
H141(321)	_	_	_	_	_	_
H142(322)	_	_	_	_	_	_
H143(323)	_	_	_	_	_	_
H144(324)	_	_	_	_	_	_
H145(325)	_	_	_	_	_	_
H146(326)	_	_	_	_	_	_
H147(327)	_	_	_	_	_	_
H148(328)	_	_	_	_	_	_
H149(329)	_	_	_	_	_	_
H14A(330)	_	_	_	_	_	_
H14B(331)	_	_	_	_	_	_
H14C(332)	_	_	_	_	_	_
		_	_	_	_	-  -
H14D(333)	_					
H14E(334)	<del>-</del>	_	_	_	_	-
H14F(335)	_	_	-	_	_	_

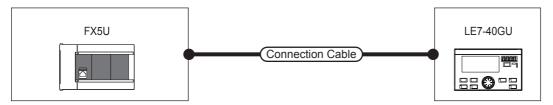
Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H150(336)	_	_	_	_	_	_
H151(337)	_	_	_	_	_	_
H152(338)	_	_	_	_	_	_
H153(339)	_	_	_	_	_	_
H154(340)	_	_	_	_	_	_
H155(341)	_	_	_	_	_	_
H156(342)	_	_	_	_	_	_
H157(343)	_	_	_	_	_	_
H158(344)	_	_	_	_	_	_
H159(345)	_	_	_	_	_	_
H15A(346)	_	_	_	_	_	_
H15B(347)	_	_	_	_	_	_
H15C(348)	_	_	_	_	_	_
H15D(349)		_	_	_	_	_
H15E(350)	_	_	_	_	_	_
H15F(351)	_	_	_	_	_	_
H160(352)	_	_	_	_	_	_
H161(353)	_	_	_	_	_	_
H162(354)	_	_	_	_		_
H163(355)	<u> </u>	_	_	_	_	_
H164(356)	_		_	_	_	_
	_		_	_	_	_
H165(357)	_		_	<u> </u>	-  -	
H166(358)						_
H167(359)	_		_	_	_	_
H168(360)	<u> </u>		_	_	-	_
H169(361)	_		_	_	-	_
H16A(362)	_	_	_	_	_	_
H16B(363)	_	_	_	_	_	_
H16C(364)	_	_	_	_	_	_
H16D(365)	_	_	_	_	_	_
H16E(366)	_	_	_	_	_	_
H16F(367)	_	_	_	_	_	_
H170(368)	_	_	_	_	_	_
H171(369)	_	_	_	_	_	_
H172 (370)	_	_	_	_	_	_
H173(371)	_	_	_	_	_	_
H174(372)	_	_	_	_	_	_
H175(373)	_	_	_	_	_	_
H176(374)	_	_	_	_	_	_
H177(375)	_	_	_	_	_	_
H178(376)	_	_	_	_	_	_
H179(377)	_	_	_	_	_	_
H17A(378)	_	_	_	_	_	_
H17B(379)	_	_	_	_	_	_
H17C(380)	_	_	_	_	_	_
H17D(381)	_	_	_	_	_	_
H17E(382)	_	_	_	_	_	_
H17F(383)	_	_	_	_	_	_
H180(384)	Open-loop control base torque	Setting	LE7-DCA	0	1000	%
H181(385)	Direct taper ratio	Setting	_	0	1000	%
H182(386)	Link tension monitor filter	Setting	_	0	80	sec
H183(387)	Tension input	Setting	-  -	0	2000	N/×10 N

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H184(388)	Reel diameter input	Setting	_	0	2000	mmφ
H185(389)	_	_	_	_	_	_
H186(390)	_	_	_	_	_	_
H187(391)	_	_	_	_	_	_
H188(392)	_	_	_	_	_	_
H189(393)	_	_	_	_	_	_
H18A(394)	_	_	_	_	_	_
H18B(395)	_	_	_	_	_	_
H18C(396)	_	_	_	_	_	_
H18D(397)	_	_	_	_	_	_
H18E(398)	_	_	_	_	_	_
H18F(399)	_	_	_	_	_	_

# **6.4** Reference Program

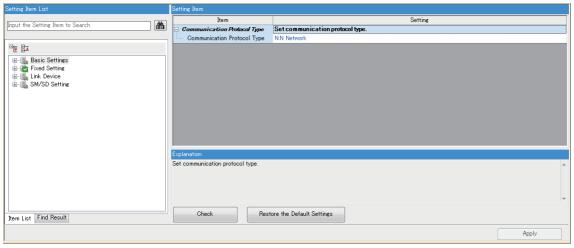
A basic example program (GX Works3) for N:N Network is described.

# System configuration



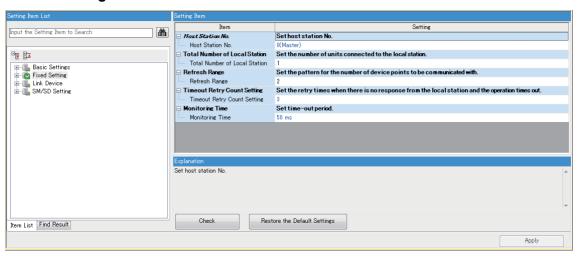
# Setting

### ■Basic settings



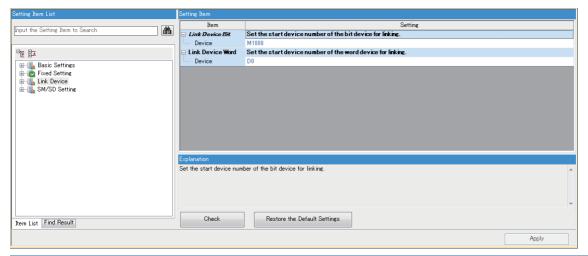
Item	Setting
Communication protocol type	N:N Network

### **■**Fixed setting



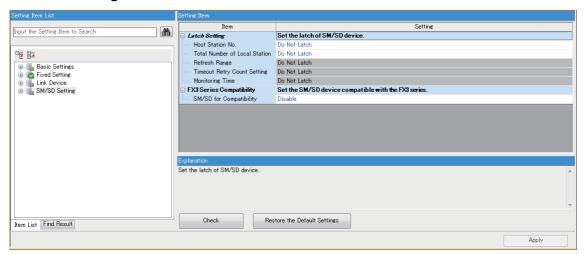
Item	Setting
Host station No.	0(master)
Total number of local station	1
Refresh range	2
Timeout retry count setting	3
Monitoring time	50 ms

### **■Link device**



Item	Setting
Link device bit	M1000
Link device word	D0

### **■SM/SD** setting



### Latch setting

Item	Setting
Host station No.	Do not latch
Total number of local station	Do not latch

#### FX3 series compatibility

Item	Setting
SM/SD for compatibility	Disable

### Program example

Writ	re + 1	2	3	4	5	6	7	8	9	10	11	12
	*Request command acc											
	X0	M1111										
2	(0) Request command access start	Request command completion								MOV	D100 Station No. command	D0 Master station link D data 0
	Start.											
3										MOV	D101 Request command 1 + request code 1	D4 Master station link D data 4
4										MOV	D102 Setting data 1	D5 Master station link D data 5
											D103 Request	D6 Master
5										MOV	command 2 + request code 2	station link D data 6
											D104	D7
6										MOV	Setting data 2	Master station link D data 7
7											SET	M1047 Request command execution
		M1111										
8		Request command completion								моч	D16 Local station 1 link D data 6	D110 Request command execution result 1
9										MOV	D17 Local station 1	D111 Request command
											link D data 7	execution result 2
	L XO											M1047
10	(39) Request										RST	Request command execution
	access start											

Writ		2	3	4	5	6	7	8	9	10	11	12
11	*Continuous monitor prod X1	cessing										
12	(43) Continuou s monitorine start										SET	M1046 Continuous monitor execution
13										MOV	D10 Local station 1 link D data 0	D120 Continuous monitor 1 (Total tension)
14										MOV	D11 Local station 1 link D data 1	D121 Continuous monitor 2 (Target tension)
15										MOV	D12 Local station 1 link D data 2	D122 Continuous monitor 3 (Control output)
16										MOV	D13 Local station 1 link D data 3	D123 Continuous monitor 4 (Alarm display)
17	(64) Continuou s monitorins										RST	M1046 Continuous monitor execution
10	start *Continuous settings pro											
19	(68) Continuou s setting start	UCSSII IĘ								MOV	D130 Continuous settings 1 (Tension setting)	D1 Master station link D data 1
20										MOV	D131 Continuous settings 2 (Manual setting)	D2 Master station link D data 2
21											SET	M1045 Continuous settings execution
22	(81) Continuou s setting start										RST	M1045 Continuous settings execution

Write	+ 1 eedback control seque	2	3	4	5	6	7	8	9	10	11	12
25	X3 											M1003 Auto/Manual
24	(85) Stall start										SET	Hatto Mariadi
		X4 										M1000
25		Start the controller.									SET	Run/Stop
		X4										h
26		Start the									RST	M1000 Run/Stop
	X3	controller.										
27	(100) Stall start										RST	M1000 Run/Stop
20											RST	M1003 Auto/Manual
28											ROI	
29 *5	Status monitoring proc   M1064 	essing			<u> </u>			<u> </u>	<u> </u>			Y10
30	(106) Run/Stop											Running lamp
	M1072											Y11
31	(111) <sub>Manual</sub>											Manual
	control											control lamp
	M1073											V12 O
32	(115) <sub>Automatic</sub> control											Automatic control lamp
	M1074											Y13
33	(119) <sub>Auto lamp</sub>											Auto lamp flicker in
	operation/ stopped M1111											operation lamp Y14
34	(123) Request											Request command
	completion M1110											completion lamp Y15
35	(127) Continuou											Continuous
	s monitor being executed											monitor being executed lamp
	M1109											V16 O
36	(131) Continuou s settings being											Continuous settings being executed
	executed											lamp ——[END ]——
37	(135)											

### Using method of ladder

Required data is stored to D100 to D131, and each function is executed in X0 to X4.

List of used devices (The allocation is an example.)

Device name	Classification*1	Allocation function	Use
D100	Setting	Station No. command	Device set for individual access to each station No.
D101 to D104	Setting	Request command + request code/data setting 1 to 2	Device set to use the request command
D110 to D111	Monitoring	Request command execution result 1 to 2	Request command execution result is stored.
D120 to D123	Monitoring	Continuous monitor 1 to 4	Continuous monitor execution result is stored.
D130 to D131	Setting	Continuous setting 1 to 2	Setting value of continuous setting is stored.
X0	Setting	Start request command access execution	Execute request command.
X1	Setting	Start continuous monitor execution	Start to execute continuous monitor.
X2	Setting	Start continuous setting execution	Start to execute continuous setting.
X3	Setting	Start stall execution	Start to execute stall.
X4	Setting	Start operation	Start to operate.
Y10	Monitoring	Run	Run: ON/Stop: OFF
Y11	Monitoring	Manual control	Manual control ON
Y12	Monitoring	Automatic control	Automatic control ON
Y13	Monitoring	Auto lamp flicker in operation	Auto lamp flicker in operation ON
Y14	Monitoring	Request command completion	ON when request command is completed
Y15	Monitoring	Continuous monitor being executed	ON when continuous monitor is being executed.
Y16	Monitoring	Continuous settings being executed	ON when continuous setting is being executed.

<sup>\*1</sup> Classification

Setting: items to be set/input when using functions Monitoring: items to monitor output when using functions

# 7 MODBUS/RTU, ASCII (SLAVE)

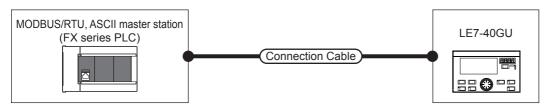
LE7-40GU can be operated as a slave station for MODBUS/RTU and ASCII communication.

Data monitoring and parameter writing from a master station for up to 247 slave stations (LE7-40GU units) can be carried out.

### Precautions

- For 5 seconds after turning on the power of LE7-40GU, data from master station will not be accepted.
- Initial setting of LE7-40GU can not be done only by MODBUS communication.
- Simultaneous use of MODBUS communication and CC-Link communication is not possible.

# 7.1 System Configuration



Connection equipment	Communication form	Connection cable		Tension controller (Slave station)	Number of connectable	
		Cable type name	Longest distance	Optional equipment	Main unit	devices
MODBUS/RTU, ASCII master device	RS-485	User created	1200 m*1	— (Built-in to main unit)	LE7-40GU	Up to 247 slave stations (LE7-40GU) from the master station

<sup>\*1</sup> The shortest specification on the MODBUS/RTU master device side takes precedence.

# 7.2 Wiring

This section describes wiring.

### Selection of cable

Use the following procedure to select cables.

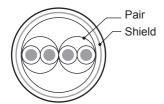
### Twisted pair cable

Use a shield twisted pair wire for connection with RS-485 communication equipment.

### **■RS-485** cable specification

Item	Specifications
Cable type	Shielded cable
Pairs	2 p, 3 p
Conductor resistance (20°C)	88.0 $\Omega$ /km or less
Insulation resistance	10000 M $\Omega$ -km or more
Withstand voltage	500 V DC 1 minute
Capacitance (1 kHz)	An average of 60 nF/km or less
Characteristic impedance (100 kHz)	110±10 Ω

### **■**Construction drawing of the cables (reference)



Construction drawing example of a two twisted-pair cable



Construction drawing example of a three twisted-pair cable

### Spring clamp terminal block

Connection to LE7-40GU should be performed as the following procedure.

#### **■**Wire size

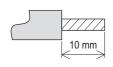
No. of wire per terminal	Wire size					
	Single wire/Strandwire	Ferrules with insulation sleeve	Ferrules withoutinsulation sleeve			
One wire	AWG24 to 16	AWG23 to 16	AWG23 to 16			

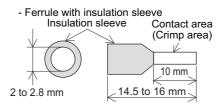
#### **■**Treatment of wire ends

Strip the cable about 10 mm from the tip to connect a wire ferrule at the striped area. Failure to do so may result in electric shock or short circuit between adjacent terminals because of the conductive part. If the wire strip length is too short, it may result in the poor contact to the spring clamp terminal part.

When using a wire ferrule with an insulating sleeve, choose a wire with proper cable sheath referring to the above outside dimensions, otherwise the wire cannot be inserted easily.

- Strand wire/single wire





The following table shows wire ferrules and tools for wire ferrules compatible with the terminal block. Use of items other than these may result in not being able to remove the wire ferrule, so carefully check that the wire ferrule can be unplugged. <Reference product>

Manufacturer	Model	Wire size	Crimp tool
PHOENIX CONTACT	AI 0.5-10 WH	0.5 mm <sup>2</sup>	CRIMPFOX 6
GmbH & Co. KG	AI 0.75-10 GY	0.75 mm <sup>2</sup>	
	A 1.0-10	1.0 mm <sup>2</sup>	
	A 1.5-10	1.5 mm <sup>2</sup>	

### **■**Connection and disconnection of the cable

Spring clamp terminal block is push-in type, therefore, wiring without a tool is possible by simply inserting the connecting terminal to the terminal block. However, the stranded wire does not comply with the push-in type, and a tool is required for connecting cables.

#### · Connection of the cable

Fully insert a cable or bar solderless terminal whose end has been properly processed into the wire insertion opening. If the cable or bar solderless terminal cannot be inserted with this procedure, fully insert the cable or bar solderless terminal while pushing the open/close button with a flathead screwdriver having a tip width of 2.0 to 2.5 mm. After fully inserting the cable, remove the screwdriver.

Do not tighten terminal screws exceeding the specified torque range. Otherwise it may cause equipment failure or malfunction

When wiring with the thick electric wire, make sure to prevent the conductive parts from protruding to the front of the terminal block.

#### <Reference>

Manufacturer	Model
PHOENIX CONTACT GmbH & Co. KG	SZS 0.4×2.5 VDE

#### · Disconnection of the cable

While pushing the open/close button with a flathead screwdriver having a tip width of 2.0 to 2.5 mm, disconnect the cable or bar solderless terminal.

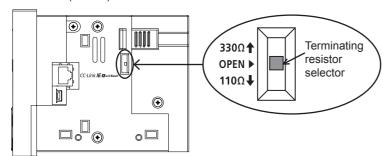
# **Terminating resistor settings**

Be sure to install terminating resistors at both ends of the line.

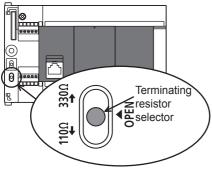
LE7-40GU, the built-in RS-485 port of the CPU module, FX5-485-BD, and FX5-485ADP, have built-in terminating resistors. Set the terminating resistance with the terminating resistor changeover switch.

Wiring	Termination resistance changeover switch		
Two-pair wiring	330 Ω		
One-pair wiring	110 Ω		

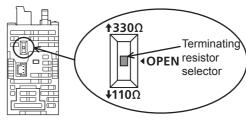
#### ■LE7-40GU (Left side)



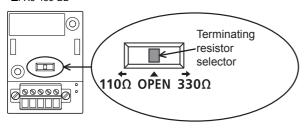
### ■FX5U CPU module built-in RS-485 port



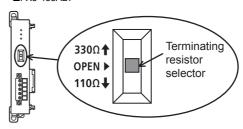








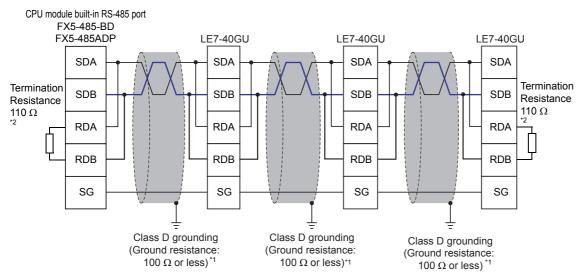
■FX5-485ADP



### **Connection diagram**

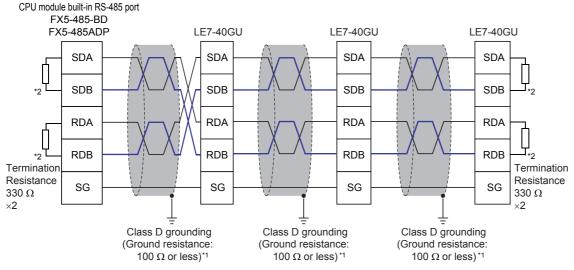
The wiring shown below is a wiring example when the master station is an FX series PLC. If the pin number of the partner side is different, please wire as shown below according to the pin name.

### One-pair wiring (master station: FX series PLC)



- \*1 Be sure to apply Class D grounding to the shield of the twisted pair cable to be connected.
- \*2 Terminal resistor should be attached to both ends of the line. LE7-40GU, the built-in RS-485 port of the CPU module, FX5-485-BD, and FX5-485ADP, have built-in terminating resistors. Set the terminating resistor selector to 110Ω.

### Two-pair wiring (master station: FX series PLC)

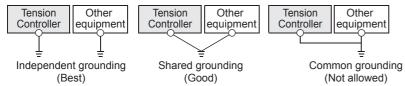


- \*1 Be sure to apply Class D grounding to the shield of the twisted pair cable to be connected.
- \*2 Terminal resistor should be attached to both ends of the line. LE7-40GU, the built-in RS-485 port of the CPU module, FX5-485-BD, and FX5-485ADP, have built-in terminating resistors. Set the terminating resistor selector to 330Ω.

### Grounding

Grounding should be performed as stated below.

- Perform Class D grounding. (Ground resistance: 100  $\Omega$  or less)
- · Independent grounding should be performed for best results.
- · When independent grounding cannot be performed, perform "shared grounding" as shown in the following figure.



The grounding wire size should be AWG 24 to 16 (cross-section area: 0.2 to 1.5 mm<sup>2</sup>).

The grounding point should be close to the tension controller, and all grounding wires should be as short as possible.

# 7.3 Communication Setting

### **Communication specifications**

The communication specifications of MODBUS/RTU, ASCII communication are as follows.

### Communication specifications

Item		Specifications	
Transmission standard		RS-485 standard	
Channels		1 channel	
Transmission specifications	Communication method	Single master/multislave system	
	Wiring method	One-pair wiring, two-pair wiring	
	Transmission speed (baud rate)	The following can be chosen from. 1200, 2400, 4800, 9600, 19200, 38400, 57600, 115200 (bps)	
	Data length*1	7 or 8 bits	
	Frame mode	RTU or ASCII	
Slave function (LE7-40GU)	Number of request messages that can be simultaneously accepted	1 request	
	Station No.	1 to 247	
	Maximum size of data that can be written	64 words <sup>*2</sup> or 1968 coils	
	Maximum size of data that can be read	125 words or 2000 coils	

<sup>\*1</sup> In RTU mode, set the data length to 8 bits.

### Used coil/holding register

The coil and holding register used for MODBUS communication of LE7-40GU are as follows.

The coil is an area to store bit data and the holding register is an area to store word data. Each slave station has coils from H0000 to H02F and H1000 to H102F as well as holding registers from H0000 to H015F and H1000 to H115F.

The usage of each kind of address is as follows.

Coil (for Master station→Slave station)

An area in which the master station writes an instruction to the slave station

Coil (for Slave station→Master station)

An area in which the slave station writes the execution result of the instruction from the master station.

By reading the area of this coil from the master station, it becomes possible to monitor the instruction execution result of the slave station by the master station.

<sup>\*2</sup> Maximum number of write words in one communication of LE7-40GU.

• Holding register (for master station monitoring)

The status of the slave station monitored by the master station is stored in this area.

Slave station monitoring is performed by the master station by reading the area of the holding register by the master station.

• Holding register (for slave station RAM write)

An area to store data to be written to the RAM of the slave station.

• Holding register (for slave station RAM + ROM write)

An area to store the data to be written to the RAM and ROM of the slave station.

Туре		Address	Data reading/writing by the master station
Coil (bit data)	For Master station→Slave station	H0000 to H002F	Writable
	For Slave station→Master station	H1000 to H102F	Readable
Holding register (word data)	For monitoring by the master station	H0000 to H015F	Readable
	For writing to RAM in the slave station	*	Readable/Writable
	For writing to RAM + ROM in the slave station	H1000 to H115F	Writable

### Frame specifications

The frame specification of MODBUS communication is shown below.

The frame specification detail is as below.

No.	Area name	Direction	Contents
1	Address field	Master station→Slave station	Broadcast     to 247: Send the request message to the specified slave station.
		Slave station→Master station	Returns the own station No. of the slave station.
2	Function code	Master station→Slave station	Specify the function code that the master station instructs for the slave station.
		Slave station→Master station	Normal completion: Returns the function code at the time of request.     Abnormal completion: Returns with the most significant bit ON.
3	Data	Master station→Slave station	Stores information for executing the function specified in the function code.
		Slave station→Master station	Normal completion: Returns the execution result of the function specified by the function code.  Abnormal completion: Returns the error response code.
4	Error checking	Master station→Slave station	The sender computes the error check bit and gives it.
		Slave station→Master station	

### Frame mode

There are two kinds of frame modes for the message which reads/writes the coil and holding registers.

#### **■RTU** mode

In RTU mode, frames are transmitted in binary code.

When the message is interrupted for a time corresponding to the communication time (depending on the transmission speed) of 3.5 characters, it is regarded as the end of the message.

Start	Address field	Function code	Data	Error check (CRC)	End (Start)	Address field
Interval of 3.5 character time or more	1 byte	1 byte	0 to 252 bytes	2 bytes	Interval of 3.5 character time or more	1 byte

### **■**ASCII mode

This mode is used to transmit and receive frames in ASCII code characters (2 bytes).

Start	Address field	Function code	Data	Error check (LRC)	End
1 byte (3AH)	2 bytes	2 bytes	N×2 bytes (N=0 to 252)	2 bytes	2 bytes ((0DH)+(0AH))

### List of supported MODBUS standard functions

The following table lists supported MODBUS standard functions.

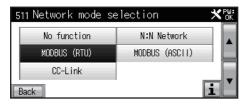
Function code	Function name	Description	Number of devices accessible in one message	Broadcast
01H	Coil reading	Coil reading (multiple points possible)	1 to 2000 points	×
03H	Holding register reading	Holding register reading (multiple points possible)	1 to 125 points	×
05H	Single coil writing	Coil writing (1 point only)	1 point	0
06H	Single register writing	Holding register writing (1 point only)	1 point	0
0FH	Multiple coil writing	Multiple point coil writing	1 to 1968 points	0
10H	Multiple register writing	Multiple point holding register writing	1 to 64 points	0

### **Communication parameter settings**

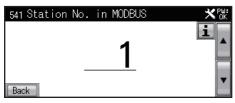
With this communication function, communication setting of LE7-40GU is necessary.

### Communication setting procedure

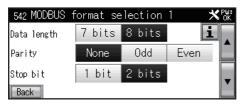
1. Select "MODBUS (RTU)" or "MODBUS (ASCII)" on the "Network mode selection" screen of the LE7-40GU screen.

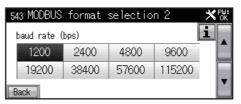


**2.** According to the slave station No. to be assigned, change "Station No. in MODBUS" on the LE7-40GU screen, in accordance with the slave station No. to be assigned to a value within "1" to "247" .



- \*1 If the set value is "0", MODBUS will not operate.
- 3. Change with "MODBUS format selection" on the LE7-40GU screen according to the communication format to be used.





Bit	Name	Description		
		0 (bit=OFF)	1 (bit=ON)	
b0	Data length*1	7 bit	8 bits	
b1 b2	Parity	b2, b1 (0, 0): Unavailable (0, 1): Odd (1, 0): Unavailable*2 (1, 1): Even		
b3	Stop bit	1 bit	2 bits	
b4 b5 b6 b7	Baud rate (bps)	b7, b6, b5, b4 (0, 0, 0, 0): Unavailable*2 (0, 0, 0, 1): Unavailable*2 (0, 0, 1, 0): Unavailable*2 (0, 0, 1, 1): Unavailable*2 (0, 1, 0, 0): Unavailable*2 (0, 1, 0, 1): 1200 (0, 1, 1, 0): 2400 (0, 1, 1, 1): 4800	b7, b6, b5, b4 (1, 0, 0, 0): 9600 (1, 0, 0, 1): 19200 (1, 0, 1, 0): 38400 (1, 0, 1, 1): 57600 (1, 1, 0, 0): Unavailable* <sup>2</sup> (1, 1, 0, 1): 115200 (1, 1, 1, 0): Unavailable* <sup>2</sup> (1, 1, 1, 1): Unavailable* <sup>2</sup>	
b8 to b15	Unavailable	_		

<sup>\*1</sup> When setting network mode selection to 3: MODBUS (RTU), data length (b0)=7 bits cannot be set.

<sup>\*2</sup> When parity (b1-2) and baud rate (b4-7) are made unavailable, network mode selection=0 (no function), N:N Network station No.=1, MODBUS station No.=1, MODBUS communication format=0x0051 can be rewritten at the next power ON after the setting.

<sup>4.</sup> Restart LE7-40GU.

### Data exchange between the master station and the slave station

The master station reads and writes data from/to the coil and holding registers of the slave station, enabling monitoring of the slave station and setting of parameters.

### Coil (bit data)

#### **■**Coil for Master station → Slave station

An area used to write instructions to the slave station.

#### **■**Coil for Slave station → Master station

The execution result of the instruction is an area for writing.

### Holding register (word data)

### ■For monitoring by the master station

The status of the slave station monitored by the master station is stored in this area.

### ■For writing to RAM in the slave station

Data to be written to the RAM in the slave station is stored in this area.

RAM writing data is reflected in the settings, but is not stored in the case of power failure.

It can be written only to LE7-40GU.

### ■For writing to RAM + ROM in the slave station

An area to store data to perform the above RAM writing + data power failure writing.

In the ROM for storage against power interruption, the allowable number of times of writing is limited. Accordingly, data cyclically written and updated by the PLC must be written only to the RAM.



- The numerical value of each parameter is treated as real data without a decimal point. The data defines the minimum value and the maximum value within LE7-40GU and automatically rewrites it to the minimum value or the maximum value when writing data outside the range. At that time, a network alarm "22" is output to the alarm display (H00EB) of the holding register.
- For holding registers where change of password of monitor, parameter list of setting items="\circ", if the password setting and the password input do not match, the holding register cannot be written to, the monitor value of the holding register is rewritten with a numerical value of maximum value +1, and the set numerical value can no longer be monitored.
- If an error occurs triggered by the request from the master station, the slave station turns ON the coil of the network alarm occurrence flag (H101A), and outputs the address of the holding register that has the error to the holding register of the device number of the network alarm (H00EC).

• Configuration of coil (from master station to slave station)

The configuration of the coil is as follows.

Device No.	Signal name	Signal name ON (data value=1)	OFF (data value=0)
H0000(0)	Run/Stop	Run	Stop
H0001(1)	Reel change B axis/A axis	B axis control	A axis control
H0002(2)	Control output OFF/ON	Control output OFF	Control output ON
H0003(3)	Auto/Manual	Automatic control	Manual control
H0004(4)	Stall memory ON/OFF	Stall memory ON	Stall memory OFF
H0005(5)	Gain 1 ON/OFF	Gain 1 ON	Gain 1 OFF
H0006(6)	Gain 2 ON/OFF	Gain 2 ON	Gain 2 OFF
H0007(7)	Inching ON/OFF	Inching ON	Inching OFF
H0008(8)	Cutting torque ON/OFF	Cutting torque ON	Cutting torque OFF
H0009(9)	Constant tension ON/OFF	Constant tension ON	Constant tension OFF
H000A(10)	Predrive ON/OFF	Predrive ON	Predrive OFF
H000B(11)	Memory hold ON/OFF	Memory hold ON	Memory hold OFF
H000C(12)	Reverse run/Forward run	Reverse run operation	Forward run operation
H000D(13)	_	_	_
H000E(14)	_	_	_
H000F(15)	_	_	_
H0010(16)	Alarm reset ON/OFF	Alarm reset ON	Alarm reset OFF
H0011(17)	Reel diameter reset ON/OFF	Reel diameter reset ON	Reel diameter reset OFF
H0012(18)	Measurement length and remaining length reset ON/OFF	Measurement length and remaining length reset ON	Measurement length and remaining length reset OFF
H0013(19)	_	_	_
H0014(20)	_	_	_
H0015(21)	_	_	_
H0016(22)	_	_	_
H0017(23)	_	_	_
H0018(24)	Zero adjustment execution	Execution	Normal
H0019(25)	Span adjustment execution	Execution	Normal
H001A(26)	Maximum diameter teaching execution	Start maximum diameter teaching execution	Normal
H001B(27)	Minimum diameter teaching execution	Start minimum diameter teaching execution	Normal
H001C(28)	Control gain tuning execution	Start control gain tuning execution	Normal
H001D(29)	Speed teaching execution	Start speed teaching execution	Normal
H001E(30)	_	_	_
H001F(31)	_	_	_
H0020(32)	Data copy execution	Start data copy execution	Normal
H0021(33)	Data initial execution	Start data initial execution	Normal
H0022(34)	_	_	_
H0023(35)	_	_	_
H0024(36)	_	_	_
H0025(37)	_	_	_
H0026(38)	-	_	_
H0027(39)	_	_	_
H0028(40)	_	_	_
H0029(41)	_	_	_
H002A(42)	_	_	_
H002B(43)		_	_
H002C(44)	Link tension monitor digit ×10/×1	Link tension monitor digit ×10	Link tension monitor digit ×1
H002D(45)	Continuous settings execution	Start continuous settings execution	Normal
H002E(46)	Continuous monitor execution	Start continuous monitor execution	Normal
	Request command execution	Start request command execution	Normal
H002F(47)	request command execution	Otalt request command execution	Homai

• Configuration of coil (from slave station to master station)

The configuration of the coil is as follows.

		I	I
Device No.	Signal name	Signal name ON (data value=1)	OFF (data value=0)
H1000(4096)	Run/Stop	Run	Stop
H1001(4097)	Output ON/OFF	Output ON	Output OFF
H1002(4098)	B-axis controlled/A-axis controlled	B-axis controlled	A-axis controlled
H1003(4099)	Constant tension ON/OFF	Constant tension ON	Constant tension OFF
H1004(4100)	Predrive being executed	Predrive being executed	Normal
H1005(4101)	Memory hold being executed	Memory hold being executed	Normal
H1006(4102)	Reverse running/Forward running	Reverse running	Forward running
H1007(4103)	_	_	_
H1008(4104)	Manual control	Manual control	_
H1009(4105)	Automatic control	Automatic control	_
H100A(4106)	Auto lamp flicker in operation/ stopped	Auto lamp flicker in operation	Auto lamp flicker stopped
H100B(4107)	Stall setting output being executed	Stall setting output being executed	Normal
H100C(4108)	Stall memory output being executed	Stall memory output being executed	Normal
H100D(4109)	Start timer operation being executed	Start timer operation being executed	Normal
H100E(4110)	Stop timer operation being executed	Stop timer operation being executed	Normal
H100F(4111)	Preset timer operation being executed	Preset timer operation being executed	Normal
H1010(4112)	Cut torque operation being executed	Cut torque operation being executed	Normal
H1011(4113)	Inching operation being executed	Inching operation being executed	Normal
H1012(4114)	_	_	_
H1013(4115)	Zero adjustment being executed	Zero adjustment being executed	Normal
H1014(4116)	Span adjustment being executed	Span adjustment being executed	Normal
H1015(4117)	Maximum diameter teaching being executed	Speed teaching being executed	Normal
H1016(4118)	Minimum diameter teaching being executed	Speed teaching being executed	Normal
H1017(4119)	Control gain tuning being executed	Control gain tuning being executed	Normal
H1018(4120)	Speed teaching being executed	Speed teaching being executed	Normal
H1019(4121)	Tension upper limit detection ON/ OFF	Tension upper limit detection ON	Tension upper limit detection OFF
H101A(4122)	Tension lower limit detection ON/OFF	Tension lower limit detection ON	Tension lower limit detection OFF
H101B(4123)	Detection outside tension range ON/ OFF	Detection outside tension range ON	Detection outside tension range OFF
H101C(4124)	Reel diameter detection 1 ON/OFF	Reel diameter detection 1 ON	Reel diameter detection 1 OFF
H101D(4125)	Reel diameter detection 2 ON/OFF	Reel diameter detection 2 ON	Reel diameter detection 2 OFF
H101E(4126)	Reel diameter detection 3 ON/OFF	Reel diameter detection 3 ON	Reel diameter detection 3 OFF
H101F(4127)	Measurement length/remaining length detection 1 ON/OFF	Measurement length/remaining length detection 1 ON	Measurement length/remaining length detection 1 OFF
H1020(4128)	Measurement length/remaining length detection 2 ON/OFF	Measurement length/remaining length detection 2 ON	Measurement length/remaining length detection 2 OFF
H1021(4129)	Measurement length/remaining length detection 3 ON/OFF	Measurement length/remaining length detection 3 ON	Measurement length/remaining length detection 3 OFF
H1022(4130)	Peripheral speed synchronization detection ON/OFF	Peripheral speed synchronization detection ON	Peripheral speed synchronization detection OFF
H1023(4131)	Alarm occurrence detection	Alarm occurrence	Normal
H1024(4132)	Parameter protection being executed	Parameter protection being executed	Normal
H1025(4133)	Settings password matching being executed	Settings password matching being executed	Settings password does not match
H1026(4134)	Monitor password matching being executed	Monitor password matching being executed	Monitor password does not match
H1027(4135)	_	_	_
H1027(4135) H1028(4136)	— Data copy being executed	— Data copy being executed	— Normal

Device No.	Signal name	Signal name ON (data value=1)	OFF (data value=0)
H102A(4138)	_	_	_
H102B(4139)	_	_	_
H102C(4140)	_	_	_
H102D(4141)	Continuous settings being executed	Continuous settings being executed	Normal
H102E(4142)	Continuous monitor being executed	Continuous monitor being executed	Normal
H102F(4143)	Request command completion	Request command completion	Normal
H103F (4144) to H103F (4159)	System use area		

• Configuration of holding register (for master station monitoring, slave station RAM writing)
The configuration of the holding register is as follows.

Request	Name	Monitor/	Extension	Minimum value	Maximum value	Unit
code		settings	option			
H000(0)	_	_	_	_	_	_
H001(1)	Total tension	Monitor	_	0 or less	2000 or more	N/×10 N
H002(2)	Left tension	Monitor	_	0 or less	2000 or more	N/×10 N
H003(3)	Right tension	Monitor	_	0 or less	2000 or more	N/×10 N
H004(4)	Left input voltage	Monitor	_	-1500 or less	1500 or more	mV
H005(5)	Right input voltage	Monitor	_	-1500 or less	1500 or more	mV
H006(6)	_	_	_	_	_	_
H007(7)	_	_	_	_	_	_
H008(8)	_	_	_	_	_	_
H009(9)	_	_	_	_	_	_
H00A(10)	_	_	_	_	_	_
H00B(11)	_	_	_	_	_	_
H00C(12)	_	_	_	_	_	_
H00D(13)	_	_	_	_	_	_
H00E(14)	_	_	_	_	_	_
H00F(15)	_	_	_	_	_	_
H010(16)	Tension upper limit detection	Setting	_	0	Tension full scale	N/×10 N
H011(17)	Tension lower limit detection	Setting	_	0	Tension full scale	N/×10 N
H012(18)	Detection outside target tension range	Setting	_	0	50	%
H013(19)	Tension display filter	Setting	_	5	80	sec
H014(20)	Tension detection filter	Setting	_	0	80	sec
H015(21)	Tension output filter	Setting	_	0	80	sec
H016(22)	_	_	_	_	_	_
H017(23)	_	_	_	_	_	_
H018(24)	_	_	_	_	_	_
H019(25)	_	_	_	_	_	_
H01A(26)	_	_	_	_	_	_
H01B(27)	_	_	_	_	_	_
H01C(28)	_	_	_	_	_	_
H01D(29)	_	_	_	_	_	_
H01E(30)	_	_	_	_	_	_
H01F(31)	_	_	_	_	_	_
H020(32)	Sensor input type selection	Setting	_	0 (LX type), 1 (strain	gauge)	_
H021(33)	Tension full scale	Setting	_	1	2000	N/×10 N
H022(34)	Tension display decimal point selection	Setting	_	0 (1), 1 (0.1), 2 (0.01	)	_
H023(35)	Tension display unit selection	Setting	_	0 (N), 1 (×10 N)		_
H024(36)	Span target tension	Setting	_	1	Tension full scale	N/×10 N
H025(37)	Left manual zero calibration	Setting	_	-999	999	N/×10 N
H026(38)	Right manual zero calibration	Setting	_	-999	999	N/×10 N
H027(39)	Left manual span calibration	Setting	_	50	300	%
H028(40)	Right manual span calibration	Setting	_	50	300	%
H029(41)	_	_	_	_	_	_

Request code	Name	Monitor/	Extension option	Minimum value	Maximum value	Unit
H02A(42)	_	_	_	_	_	_
H02B(43)	_	_	_	_	_	_
H02C(44)	_	_	_	_	_	_
H02D(45)	_	_	_	_	_	_
H02E(46)	_	_	_	_	_	_
H02F(47)	_	_	_	_	_	_
H030(48)	Reel diameter	Monitor	_	1	2000	mmφ
H031(49)	Target line velocity	Monitor	LE7-DCA	0	10000	m/min
H032(50)	Line acceleration	Monitor	LE7-DCA	0	50	m/min/sec
H033(51)	Measurement length/remaining length	Monitor	LE7-DCA	_	_	m
H034(52)	Reel rotational speed	Monitor	LE7-DCA	65000	1	r/min
H035(53)	New reel rotational speed	Monitor	LE7-DCA	3600	1	r/min
H036(54)	Constant slip ROTO speed command output	Monitor	LE7-DCA	1000	0.1	%
H037(55)	· · ·	Monitor	LE7-DCA	1000	0.1	%
	Predrive rotation speed command output					
H038(56)	Predrive target rotation speed	Monitor	LE7-DCA	3600	1	r/min
H039(57)	Reel diameter CALC adapter ROM version	Monitor	LE7-DCA	999	0.01	_
H03A(58)	<del>-</del>	_	_	_	_	_
H03B(59)	_	_	_	_	_	_
H03C(60)	_	_	_	_	_	_
H03D(61)	_	_	_	_	_	_
H03E(62)	_	-	_	_	_	_
H03F(63)	_	_	_	_	_	_
H040(64)	Initial diameter	Setting	LE7-DCA	1	2000	mmφ
H041(65)	Material thickness	Setting	LE7-DCA	0	10000	μm
H042(66)	Reel diameter detection 1	Setting	LE7-DCA	0	2000	mmφ
H043(67)	Reel diameter detection 2	Setting	LE7-DCA	0	2000	mmφ
H044(68)	Reel diameter detection 3	Setting	LE7-DCA	0	2000	mmφ
H045(69)	Measurement/remaining length detection 1	Setting	LE7-DCA	0	65000	m
H046(70)	Measurement/remaining length detection 2	Setting	LE7-DCA	0	65000	m
H047(71)	Measurement/remaining length detection 3	Setting	LE7-DCA	0	65000	m
H048(72)	Accelerating judgment acceleration	Setting	LE7-DCA	0	10	m/min/sec
H049(73)	Reel rotational speed gain	Setting	LE7-DCA	0	150	%
H04A(74)	Reel rotational speed bias	Setting	LE7-DCA	0	100	%
H04B(75)	Reel rotational speed startup gain	Setting	LE7-DCA	1	5	Time (s)
H04C(76)	Reel rotational speed startup timer	Setting	LE7-DCA	0	10	sec
H04D(77)	Predrive time	Setting	LE7-DCA	0	200	sec
H04E(78)	Predrive bias	Setting	LE7-DCA	-10	10	%
H04F(79)	_	_	_	_	_	_
H050(80)	Maximum diameter	Setting	_	Minimum diameter	2000	mmφ
H051(81)	Minimum diameter	Setting	_	1	Maximum diameter	mmφ
H052(82)	Teaching speed	Setting	LE7-DCA	1	10000	m/min
H053(83)	Velocity electronic gear ratio	Setting	LE7-DCA	9000	18000	%
H054(84)	Reel selection	Setting	LE7-DCA	0(unwinding), 1(wind	ing)	_
H055(85)	Number of reel pulse	Setting	LE7-DCA	0 (1 pulse), 1 (2 pulse pulses), 4 (16 pulses		_
H056(86)	Reel diameter calculation cycle	Setting	LE7-DCA	0 (1 pulse), 1 (2 pulse pulses), 4 (16 pulses	es), 2 (4 pulses), 3 (8	_
H057(87)	MEAS/RMN length calculation switch	Setting	LE7-DCA	0 (measurement leng length)		_
H058(88)	Material thickness unit	Setting	LE7-DCA	0 (×1), 1 (×0.1)		_
H059(89)	Maximum line acceleration	Setting	LE7-DCA	1	50	m/min/sec
	I.		1	1	1	1

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H05B(91)	Detection output selection	Setting	LE7-DCA	0 (Reel diameter), (mremaining length)	neasurement length/	_
H05C(92)	Detection output holding selection	Setting	LE7-DCA	0 (non-holding), 1 (ho	olding)	_
H05D(93)	Run/Stop judgment selection	Setting	LE7-DCA	0 (contact + internal) (internal)	, 1 (contact), 2	_
H05E(94)	Run judgment speed	Setting	LE7-DCA	Stop judgment speed	30	m/min
H05F(95)	Stop judgment speed	Setting	LE7-DCA	1	Run judgment speed	m/min
H060(96)	-	_	_	_	_	_
H061(97)	_	_	_	_	_	_
H062(98)	_	_	_	_	_	_
H063(99)	_	_	_	_	_	_
H064(100)	_	_	_	_	_	_
H065(101)	_	_	_	_	_	_
H066(102)	_	_	_	_	_	_
H067(103)	1-	_	_	_	_	_
H068(104)	_	_	_	_	_	_
H069(105)	_	_	_	_	_	_
H06A(106)	_	_	_	_	_	_
H06B(107)	<del> </del>	_	_	_	_	_
H06C(108)	<u> </u>	_	_	_	_	_
H06D(109)	_	_	_	_	_	_
H06E(110)	_	_	_	_	_	_
H06F(111)	_	_	_	_	_	_
H070(112)	Target tension	Monitor	_	0	2000	N/×10 N
H071(113)		Monitor	_	-1000 or less	1000 or more	%
	Control output  Torque output			-1000 or less	1000 or more	
H072(114)	· · ·	Monitor				%
H073(115)	-  -	<u> </u>		-  -	<del>-</del>	_
H074(116)						
H075(117)	Control output voltage for powder	Monitor	_	260 or more	0.1	V
H076(118)	Control output current for powder	Monitor	_	400 or more	0.01	Α
H077(119)	-		_	_	_	_
H078(120)		_	_	_	_	_
H079(121)	<u> -</u>		_	_	_	_
H07A(122)	_	_	_	_	_	_
H07B(123)	_	_	_	_	_	_
H07C(124)	_	_	_	_	_	_
H07D(125)	<u> -</u>	_	_	_	_	_
H07E(126)	_		_	_	_	_
H07F(127)	_		_	_	_	_
H080(128)	Tension setting	Setting	_	1	Tension full scale	N/×10 N
H081(129)	Manual setting	Setting	_	-1000	1000	%
H082(130)	Stall setting	Setting	_	0	1000	%
H083(131)	Start timer	Setting	_	0	300	sec
H084(132)	Stop timer	Setting	_	0	1000	sec
H085(133)	Stop gain	Setting	_	5	400	%
H086(134)	Stop bias	Setting	_	0	100	%
H087(135)	Acceleration/deceleration torque setting	Setting	LE7-DCA	0	1000	%
H088(136)	Gain 1	Setting	_	5	400	%
H089(137)	Gain 2	Setting	_	5	400	%
H08A(138)	Internal taper ratio	Setting	_	0	80	%
H08B(139)	External linear line taper ratio	Setting	_	0	100	%

Request	Name	Monitor/	Extension option	Minimum value	Maximum value	Unit
H08C(140)	New reel preset	Setting	_	0	1000	%
H08D(141)	New reel preset timer	Setting	_	0	300	sec
H08E(142)	Cutting torque	Setting	_	0	1000	%
H08F(143)	_	_	_	_	_	_
H090(144)	Broken line taper corner 1	Setting	_	1	2000	mmφ
H091(145)	Broken line taper ratio 1	Setting	_	0	100	%
H092(146)	Broken line taper corner 2	Setting	_	1	2000	mmφ
H093(147)	Broken line taper ratio 2	Setting	_	0	100	%
H094(148)	Broken line taper corner 3	Setting	_	1	2000	mmφ
H095(149)	Broken line taper ratio 3	Setting	_	0	100	%
H096(150)	Broken line taper corner 4	Setting	_	1	2000	mmφ
H097(151)	Broken line taper ratio 4	Setting	_	0	100	%
H098(152)	Broken line taper corner 5	Setting	_	1	2000	mmφ
H099(153)	Broken line taper ratio 5	Setting	_	0	100	%
H09A(154)	Broken line taper corner 6	Setting	_	1	2000	mmφ
H09B(155)	Broken line taper ratio 6	Setting	_	0	100	%
H09C(156)	Broken line taper corner 7	Setting	_	1	2000	mmφ
H09D(157)	Broken line taper ratio 7	Setting	_	0	100	%
H09E(158)	Broken line taper corner 8	Setting	_	1	2000	mmφ
H09F(159)	Broken line taper ratio 8	Setting	_	0	100	%
H0A0(160)	Proportional gain	Setting	_	0	100	%
H0A1(161)	Integral time	Setting	_	0	100	%
H0A2(162)	Dead band gain	Setting	_	0	100 - Proportional	%
110712(102)	Dodd barra garri	Colling			gain	70
H0A3(163)	Dead band width	Setting	_	0	100	%
H0A4(164)	Tension control filter	Setting	_	0	40	sec
H0A5(165)	Static mechanical loss A	Setting	_	-1000	1000	%
H0A6(166)	Static mechanical loss B	Setting	_	-1000	1000	%
H0A7(167)	Kinetic mechanical loss A	Setting	LE7-DCA	-1000	1000	%
H0A8(168)	Kinetic mechanical loss B	Setting	LE7-DCA	-1000	1000	%
H0A9(169)	Mass correction gain A	Setting	LE7-DCA	0	100	%
H0AA(170)	Mass correction gain B	Setting	LE7-DCA	0	100	%
H0AB(171)	Mass correction bias A	Setting	LE7-DCA	0	100	%
H0AC(172)	Mass correction bias B	Setting	LE7-DCA	0	100	%
H0AD(173)	_	_	_	_	_	_
H0AE(174)	_	_	_	_	_	_
H0AF(175)	_	_	_	_	_	_
H0B0(176)	Control mode selection	Setting	LE7-DCA	0 (feedback control),	1 (open loop control)	_
H0B1(177)	Integral feedback limit	Setting	_	0	101	%
H0B2(178)	Feedback selection during the stop timer	Setting	_	0 (invalid), 1 (valid)		_
H0B3(179)	Automatic control output polarity selection	Setting	_	0 (forward), 1 (revers	e)	_
H0B4(180)	Open-loop control ratio	Setting	LE7-DCA	0	100	%
H0B5(181)	Taper function selection	Setting	_	0 (no function), 1 (integrated line taper (external)), (external)), 4 (direct taper taper)	3 (broken line taper	-
H0B6(182)	Selection of two reel's switching FUNC	Setting	_	0 (invalid), 1 (valid)		_
H0B7(183)	Internal taper standard selection	Setting	_	0 (zero standard), 1 (	stall standard)	_
H0B8(184)	_	_	_	_	_	_
H0B9(185)	Mechanical loss function selection	Setting	LE7-DCA	0 (fixed mechanical lomechanical loss)	oss), 1 (high function	_
H0BA(186)	Stall automatic calculation gain	Setting	LE7-DCA	0	100	%
H0BB(187)	New reel preset AUTO calculation gain	Setting	LE7-DCA	0	100	%
. ,	· · ·		1	1	L	<u> </u>

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H0BC(188)	Control output upper limit	Setting	_	Control output lower limit	101	%
H0BD(189)	Control output lower limit	Setting	_	-101	Control output upper limit	%
H0BE(190)	_	_	_	_	_	_
H0BF(191)	_	_	_	_	_	_
H0C0(192)	Load model	Setting	_	0	200	_
H0C1(193)	Rated current	Setting	_	0	400	Α
H0C2(194)	Maximum torque correction	Setting	_	50	250	%
H0C3(195)	Nonlinear correction 0	Setting	_	0	1000	%
H0C4(196)	Nonlinear correction 10	Setting	_	0	1000	%
H0C5(197)	Nonlinear correction 20	Setting	_	0	1000	%
H0C6(198)	Nonlinear correction 30	Setting	_	0	1000	%
H0C7(199)	Nonlinear correction 40	Setting	_	0	1000	%
H0C8(200)	Nonlinear correction 50	Setting	_	0	1000	%
H0C9(201)	Nonlinear correction 60	Setting	_	0	1000	%
H0CA(202)	Nonlinear correction 70	Setting	_	0	1000	%
H0CB(203)	Nonlinear correction 80	Setting	_	0	1000	%
H0CC(204)	Nonlinear correction 90	Setting	_	0	1000	%
H0CD(205)	_	_	_	_	_	_
H0CE(206)	_		_	_	_	_
H0CF(207)	1_		_	_	_	_
H0D0(208)	_		_	_	_	_
H0D1(209)	Weak excitation	Setting	_	0	1000	%
H0D2(210)	Over current detection filter	Setting	_	0	20	sec
H0D3(211)	—		_	_	_	_
	_					
H0D4(212) H0D5(213)				_	_	
			-  -		_	
H0D6(214)	_			_	_	_
H0D7(215)	<del>-</del>			_	_	_
H0D8(216)	<del> </del>			_	_	_
H0D9(217)	<del> -</del>			_	_	_
H0DA(218)	_		_	_	_	_
H0DB(219)	<u> </u>	_	_	_	_	_
H0DC(220)	_	_	_	_	_	_
H0DD(221)	_	_	_	_	_	_
H0DE(222)	_	_	_	_	_	_
H0DF(223)	_	_	_	_	_	_
H0E0(224)	Contact input monitor	Monitor	_	0	0xFFFF	_
H0E1(225)	Contact output monitor	Monitor	_	0	0xFFFF	_
H0E2(226)	General-purpose analog input 1 monitor	Monitor	_	0	100	%
H0E3(227)	General-purpose analog input 2 monitor	Monitor	_	0	100	%
H0E4(228)	General-purpose analog input 3 monitor	Monitor	<b>—</b>	0	100	%
H0E5(229)	General-purpose analog output 1 monitor	Monitor	_	0	100	%
H0E6(230)	General-purpose analog output 2 monitor	Monitor	_	0	100	%
H0E7(231)	Analog output monitor for TENS control	Monitor	_	0	100	%
H0E8(232)	Analog output monitor for new reel preset	Monitor	_	0	100	%
H0E9(233)	Contact input monitor for reel DIA CALC	Monitor	LE7-DCA	0	0xFFFF	_
H0EA(234)	Contact output monitor for reel DIA CALC	Monitor	LE7-DCA	0	0xFFFF	-
H0EB(235)	Alarm display	Monitor	_	0	63	_
H0EC(236)	Network alarm device No.	Monitor	_	0	999	_
H0ED(237)	Main unit ROM version	Monitor	_	0	999	_
H0EE(238)	Network adapter ROM version	Monitor	LE7-CCL	0	999	_

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H0EF(239)	Communication signal monitor	Monitor	_	0	0xFFFF	_
H0F0(240)	Contact input 1 function selection	Setting	_	0 (no function), 1 (rur	• **	_
H0F1(241)	Contact input 2 function selection	Setting	_	output OFF/ON), 3 (s	- · ·	_
H0F2(242)	Contact input 3 function selection	Setting	_	OFF), 6 (gain 1 ON/C	(constant tension ON/ OFF), 7 (gain 2 ON/	_
H0F3(243)	Contact input 4 function selection	Setting	_	- · · · · · -	anual), 9 (reel change	_
H0F4(244)	Contact input 5 function selection	Setting	_	ON/OFF), 10 (cut tor		_
H0F5(245)	Contact input 6 function selection	Setting	_	(alarm reset ON/OFF	)	_
H0F6(246)	_	_	_	_	_	_
H0F7(247)	_	_	_	_	_	_
H0F8(248)	Contact output 1 function selection	Setting	_	0 (no function), 1 (ter	nsion lower limit	_
H0F9(249)	Contact output 2 function selection	Setting	_	detection), 2 (tension 3 (detection outside t (alarm occurrence de	• ,.	_
H0FA(250)	_	_	_	_	_	_
H0FB(251)	_	_	_	_		_
H0FC(252)	_	_	_	_	_	_
H0FD(253)	_	_	_	_	_	_
H0FE(254)	_	_	_	_	_	-
H0FF(255)	_	_	_	_	_	_
H100(256)	Analog input mode selection	Setting	_	0 (0 to 5 V mode), 1	(0 to 10 V mode)	_
H101(257)	Analog input 1 function selection	Setting	_	0 (no function), 1 (ter	nsion setting), 2 (stall	_
H102(258)	Analog input 2 function selection	Setting	_		ne taper ratio setting),	_
H103(259)	Analog input 3 function selection	Setting	_	<ul> <li>4 (new axis preset setting), 5 (manual setting), 6 (tension input), 7 (Reel diameter input)</li> </ul>		_
H104(260)	_	_	_	_	_	_
H105(261)	_	_	_	_	_	_
H106(262)	_	_	_	_	_	_
H107(263)	_	_	_	_	_	_
H108(264)	Analog output mode selection	Setting	_	0 (0 to 5 V mode), 1	(0 to 10 V mode)	_
H109(265)	Analog output 1 function selection	Setting	_	0 (no function), 1 (ten	sion monitor), 2 (Reel	_
H10A(266)	Analog output 2 function selection	Setting	_	diameter monitor), 3 monitor), 4 (A-axis Rospeed output), 5 (B-arotational speed outp	eel shaft rotational xis Reel shaft	_
H10B(267)	Analog output 1 gain	Setting	_	500	3000	%
H10C(268)	Analog output 2 gain	Setting	_	500	3000	%
H10D(269)	Analog output 1 bias	Setting	_	-500	500	%
H10E(270)	Analog output 2 bias	Setting	_	-500	500	%
H10F(271)	_	_	_	_	_	_
H110(272)	Two reel's switching FUNC output mode	Setting	_	0 (no internal switchin switching)	ng), 1 (with internal	_
H111(273)	Control output mode selection	Setting	_	to 10 V mode), 3 (-10	(-5 to 5 V mode), 2 (0 to 10 V mode), 4 (0 to V mode), 6 (0 to 2.7 V V mode), 8 (1 to 5 V	_
H112(274)	Control output gain	Setting	_	500	3000	%
H113(275)	New reel preset output gain	Setting	_	500	3000	%
H114(276)	Control output bias	Setting	_	-500	500	%
H115(277)	New reel preset output bias	Setting	_	-500	500	%
H116(278)	_	_	_		_	_
H117(279)	_	_	_	_	_	_
H118(280)	_	<u> </u>	_	_	_	_
H119(281)	_	_	_	_	_	_
H11A(282)	_	<u> </u>	_	_	_	_
	<u>I</u>	1	1	1	1	1

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H11B(283)	_	_	_	_	_	_
H11C(284)		-	_	_	_	_
H11D(285)	_	_	_	_	_	_
H11E(286)	_	_	_	_	_	_
H11F(287)	_	_	_	_	_	_
H120(288)	Set setting password	Setting	_	0	32000	_
H121(289)	Input setting password	Setting	_	0	32000	_
H122(290)	Set monitor password	Setting	_	0	32000	_
H123(291)	Input monitor password	Setting	_	0	32000	_
H124(292)	_	_	_	_	_	_
H125(293)	_	_	_	_	_	_
H126(294)	_	_	_	_	_	_
H127(295)	_	_	_	_	_	_
H128(296)	_	_	_	_	_	_
H129(297)	_	_	_	_	_	_
H12A(298)	_	_	_	_	_	_
H12B(299)	_	_	_	_	_	_
H12C(300)	_	_	_	_	_	_
H12D(301)	_	_	_	_	_	_
H12E(302)	_	_	_	_	_	_
H12F(303)	_	1_	_	_	_	_
H130(304)	Alarm history 1	Monitor	_	0	63	_
H131(305)	Alarm history 2	Monitor	_	0	63	_
H132(306)	Alarm history 3	Monitor	_	0	63	_
H133(307)	Alarm history 4	Monitor	_	0	63	_
H134(308)	Alarm history 5	Monitor	_	0	63	_
H135(309)	Alarm history 6	Monitor	_	0	63	_
H136(310)	Alarm history 7	Monitor	_	0	63	
	Alarm history 8	Monitor		0	63	
H137(311)	•					
H138(312)	Alarm history holding selection	Setting	_	0 (no holding), 1 (hol	301	_
H139(313)	Alarm display time	Setting	_		0xFFFF	sec
H13A(314)	Alarm operation selection 1	Setting	_	0		<u> </u>
H13B(315)	Alarm operation selection 2	Setting	_	0	0xFFFF	
H13C(316)	Alarm operation selection 3	Setting	_	0	0xFFFF	_
H13D(317)	Alarm operation selection 4	Setting	_	0	0xFFFF	_
H13E(318)	_	<u> </u>	_	_	_	_
H13F(319)	_	-	_	_	_	_
H140(320)	_	-	_	_	_	_
H141(321)	_	-	_	_	_	_
H142(322)	_	_	_	_	_	_
H143(323)	_	_	_	_	_	_
H144(324)	_	_	_	_	-	_
H145(325)	_	_	_	_	_	_
H146(326)	_	-	_	_	_	_
H147(327)	_	_	_	_	_	_
H148(328)	_	_	_	_	_	_
H149(329)	_	_	_	_	_	_
H14A(330)	_	_	_	_	_	_
H14B(331)	_	_	_	_	_	_
H14C(332)	_	_	_	_	_	_
H14D(333)	_	_	_	_	_	_
H14E(334)	_	_	_	_	_	_

Request	Name	Monitor/	Extension	Minimum value	Maximum value	Unit
code		settings	option			
H14F(335)	_	_	_	_	_	_
H150(336)	_	_	_	_	_	_
H151(337)	_	_	_	_	_	_
H152(338)	_	_	_	_	_	_
H153(339)	_	_	_	_	_	_
H154(340)	_	_	_	_	_	_
H155(341)	_	_	_	_	_	_
H156(342)	_	_	_	_	_	_
H157(343)	_	_	_	_	_	_
H158(344)	_	_	_	_	_	_
H159(345)	_	_	_	_	_	_
H15A(346)	_	_	_	_	_	_
H15B(347)	_	_	_	_	_	_
H15C(348)	_	_	_	_	_	_
H15D(349)	_	_	_	_	_	_
H15E(350)	_	_	_	_	_	_
H15F(351)	_	_	_	_	_	_
H160(352)	_	_	_	_	_	_
H161(353)	_	_	_	_	_	_
H162(354)	_	_	_	_	_	_
H163(355)	_	_	_	_	_	_
H164(356)	_	_	_	_	_	_
H165(357)	_	_	_	_	_	_
H166(358)	_	_	_	_	_	_
H167(359)	_	_	_	_	_	_
H168(360)	_	_	_	_	_	_
H169(361)	_	_	_	_	_	_
H16A(362)	_	_	_	_	_	_
H16B(363)	_	_	_	_	_	_
H16C(364)	_	_	_	_	_	_
H16D(365)	_	_	_	_	_	_
H16E(366)	_	_	_	_	_	_
H16F(367)	_	_	_	_	_	_
H170(368)	_	_	_	_	_	_
H171(369)	_	_	_	_	_	_
H172(370)	_	_	_	_	_	_
H173(371)	_	_	_	_	_	_
H174(372)	_	_	_	_	_	_
H175(373)	_	_	_	_	_	_
H176(374)	_	_	_	_	_	_
H177(375)	_	_	_	_	_	_
H178(376)	_	_	_	_	_	_
H179(377)	_	_	_	_	_	_
H17A(378)	_	_	_	_	_	_
H17B(379)	_	_	_	_	_	_
H17C(380)	_	_	_	_	_	_
H17D(381)	_	_	_	_	_	_
H17E(382)	_	_	_	_	_	_
H17F(383)	_	_	_	_	_	_
H180(384)	Open-loop control base torque	Setting	LE7-DCA	0	1000	%
H181(385)	Direct taper ratio	Setting	_	0	1000	%
H182(386)	Link tension monitor filter	Setting	_	0	80	sec
	<u> </u>	_	<u>I</u>	<u>I</u>	I.	

Request code	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H183(387)	Tension input	Setting	_	0	2000	N/×10 N
H184(388)	Reel diameter input	Setting	_	0	2000	mmφ
H185(389)	_	_	_	_	_	_
H186(390)	_	_	_	_	_	_
H187(391)	_	_	_	_	_	_
H188(392)	_	_	_	_	_	_
H189(393)	_	_	_	_	_	_
H18A(394)	_	_	_	_	_	_
H18B(395)	_	_	_	_	_	_
H18C(396)	_	_	_	_	_	_
H18D(397)	_	_	_	_	_	_
H18E(398)	_	_	_	_	_	_
H18F(399)	_	_	_	_	_	_

• Configuration of holding register (for slave station RAM+ROM writing) The configuration of the holding register is as follows.

Holding register	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H1000(4096)	_	_	_	_	_	_
H1001(4097)	Total tension	Monitor	_	0 or less	2000 or more	N/×10 N
H1002(4098)	Left tension	Monitor	_	0 or less	2000 or more	N/×10 N
H1003(4099)	Right tension	Monitor	_	0 or less	2000 or more	N/×10 N
H1004(4100)	Left input voltage	Monitor	_	-1500 or less	1500 or more	mV
H1005(4101)	Right input voltage	Monitor	_	-1500 or less	1500 or more	mV
H1006(4102)	_	_	_	_	_	_
H1007(4103)	_	_	_	_	_	_
H1008(4104)	_	_	_	_	_	_
H1009(4105)	_	_	_	_	_	_
H100A(4106)	_	_	_	_	_	_
H100B(4107)	_	_	_	_	_	_
H100C(4108)	_	_	_	_	_	_
H100D(4109)	_	_	_	_	_	_
H100E(4110)	_	_	_	_	_	_
H100F(4111)	_	_	_	_	_	_
H1010(4112)	Tension upper limit detection	Setting	_	0	Tension full scale	N/×10 N
H1011(4113)	Tension lower limit detection	Setting	_	0	Tension full scale	N/×10 N
H1012(4114)	Detection outside target tension range	Setting	_	0	50	%
H1013(4115)	Tension display filter	Setting	_	5	80	sec
H1014(4116)	Tension detection filter	Setting	_	0	80	sec
H1015(4117)	Tension output filter	Setting	_	0	80	sec
H1016(4118)			_	_	_	_
H1017(4119)	_		_	_	_	
H1018(4120)	_		_		_	
H1019(4121)	_			_		
H101A(4122)	_	_	_	_	_	_
H101B(4123)	_			_		
H101C(4124)				_	_	
H101D(4125)	_	_	_	_	-	_
H101E(4126)			_	_	_	_
H101F(4127)	Tension input filter	Setting	_	50	200	_
H1020(4128)	Sensor input type selection	Setting	_	0 (LX type), 1 (strain	T	-
H1021(4129)	Tension full scale	Setting	_	1	2000	N/×10 N
H1022(4130)	Tension display decimal point selection	Setting	-	0 (1), 1 (0.1), 2 (0.01)	)	_
H1023(4131)	Tension display unit selection	Setting	_	0 (N), 1 (×10 N)	T=	
H1024(4132)	Span target tension	Setting	-	1	Tension full scale	N/×10 N
H1025(4133)	Left manual zero calibration	Setting	_	-999	999	N/×10 N
H1026(4134)	Right manual zero calibration	Setting	_	-999	999	N/×10 N
H1027(4135)	Left manual span calibration	Setting	_	50	300	%
H1028(4136)	Right manual span calibration	Setting	-	50	300	%
H1029(4137)	_	_	-	_	_	-
H102A(4138)	Tension full scale × 10 data	Setting	_	10	20000	-
H102B(4139)	Span adjustment data range switching	Monitor	_	0	15	-
H102C(4140)	Left zero adjustment data	Monitor	_	-32768	32767	_
H102D(4141)	Right zero adjustment data	Monitor	-	-32768	32767	-
H102E(4142)	Left span adjustment data	Setting	_	-32768	32767	-
H102F(4143)	Right span adjustment data	Setting	_	-32768	32767	_
H1030(4144)	Reel diameter	Monitor	_	1	2000	mmφ
H1031(4145)	Target line velocity	Monitor	LE7-DCA	0	10000	m/min

Holding register	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H1032(4146)	Line acceleration	Monitor	LE7-DCA	0	50	m/min/sec
H1033(4147)	Measurement length/remaining length	Monitor	LE7-DCA	_	_	m
H1034(4148)	Reel rotational speed	Monitor	LE7-DCA	65000	1	r/min
H1035(4149)	New reel rotational speed	Monitor	LE7-DCA	3600	1	r/min
H1036(4150)	Constant slip ROTO speed command output	Monitor	LE7-DCA	1000	0.1	%
H1037(4151)	Predrive rotation speed command output	Monitor	LE7-DCA	1000	0.1	%
H1038(4152)	Predrive target rotation speed	Monitor	LE7-DCA	3600	1	r/min
H1039(4153)	Reel diameter CALC adapter ROM version	Monitor	LE7-DCA	999	0.01	_
H103A(4154)	<u> </u>	_	_	_	_	_
H103B(4155)	_	_	_	_	_	_
H103C(4156)	_	_	_	_	_	_
H103D(4157)	_	_	_	_	_	_
H103E(4158)	_	_	_	_	_	_
H103F(4159)	_	_	_	_	_	_
H1040(4160)	Initial diameter	Setting	LE7-DCA	1	2000	mmφ
H1041(4161)	Material thickness	Setting	LE7-DCA	0	10000	μm
H1042(4162)	Reel diameter detection 1	Setting	LE7-DCA	0	2000	mmφ
H1043(4163)	Reel diameter detection 2	Setting	LE7-DCA	0	2000	mmφ
H1044(4164)	Reel diameter detection 3	Setting	LE7-DCA	0	2000	mmφ
H1045(4165)	Measurement/remaining length detection 1	Setting	LE7-DCA	0	65000	m
	Measurement/remaining length detection 2	Setting	LE7-DCA	0	65000	m
H1046(4166)	, , , , , , , , , , , , , , , , , , ,	-		0		_
H1047(4167)	Measurement/remaining length detection 3	Setting	LE7-DCA		65000	m m/min/aaa
H1048(4168)	Accelerating judgment acceleration	Setting	LE7-DCA	0	10	m/min/sec
H1049(4169)	Reel rotational speed gain	Setting	LE7-DCA	0	150	%
H104A(4170)	Reel rotational speed bias	Setting	LE7-DCA	0	100	%
H104B(4171)	Reel rotational speed startup gain	Setting	LE7-DCA	1	5	Time (s)
H104C(4172)	Reel rotational speed startup timer	Setting	LE7-DCA	0	10	sec
H104D (4173)	Predrive time	Setting	LE7-DCA	0	200	sec
H104E(4174)	Predrive bias	Setting	LE7-DCA	-10	10	%
H104F(4175)	_	_	_	_	_	_
H1050(4176)	Maximum diameter	Setting	_	Minimum diameter	2000	mmφ
H1051(4177)	Minimum diameter	Setting	_	1	Maximum diameter	mmφ
H1052(4178)	Teaching speed	Setting	LE7-DCA	1	10000	m/min
H1053(4179)	Velocity electronic gear ratio	Setting	LE7-DCA	9000	18000	%
H1054(4180)	Reel selection	Setting	LE7-DCA	0 (unwinding), 1 (win	ding)	_
H1055(4181)	Number of reel pulse	Setting	LE7-DCA	0 (1 pulse), 1 (2 puls pulses), 4 (16 pulses	es), 2 (4 pulses), 3 (8 )	_
H1056(4182)	Reel diameter calculation cycle	Setting	LE7-DCA	0 (1 pulse), 1 (2 puls pulses), 4 (16 pulses	es), 2 (4 pulses), 3 (8 )	_
H1057(4183)	MEAS/RMN length calculation switch	Setting	LE7-DCA	0 (measurement leng length)	gth), 1 (remaining	_
H1058(4184)	Material thickness unit	Setting	LE7-DCA	0 (×1), 1 (×0.1)		_
H1059(4185)	Maximum line acceleration	Setting	LE7-DCA	1	50	m/min/sec
H105A(4186)	Maximum reel rotational speed	Setting	LE7-DCA	1	3600	r/min
H105B(4187)	Detection output selection	Setting	LE7-DCA	0 (reel diameter), 1 (remaining length)	measurement length/	_
H105C(4188)	Detection output holding selection	Setting	LE7-DCA	0 (non-holding), 1 (ho	olding)	_
H105D(4189)	Run/Stop judgment selection	Setting	LE7-DCA	0 (contact + internal) (internal)		_
H105E(4190)	Run judgment speed	Setting	LE7-DCA	Stop judgment speed	30	m/min
H105F(4191)	Stop judgment speed	Setting	LE7-DCA	1	Run judgment speed	m/min
H1060(4192)	<u> </u>		_		· Process	

Holding register	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
	_	_	_	_	_	_
H1061(4193)	_	_		-	_	
H1062(4194)			_	_	_	
H1063(4195)	_	_	_	<u> </u>	_	_
H1064(4196)	_	_	_	_	_	_
H1065(4197)	_	_	_	_	_	_
H1066(4198)	_	_	_	_	_	_
H1067(4199)	_	_	_	_	_	_
H1068 (4200	_	_	_	_	_	_
H1069(4201)	_	_	_	_	_	_
H106A(4202)	_	_	_	_	_	_
H106B(4203)	_	_	_	_	_	_
H106C(4204)	_	_	_	_	_	_
H106D(4205)	_	_	_	_	_	_
H106E(4206)	_	_	_	_	_	_
H106F(4207)	_	_	_	_	_	_
H1070(4208)	Target tension	Monitor	_	0	2000	N/×10 N
H1071(4209)	Control output	Monitor	_	-1000 or less	1000 or more	%
H1072(4210)	Torque output	Monitor	_	-1000 or less	1000 or more	%
H1073(4211)	100% reel conversion torque	Monitor	_	0	60000	N·m
H1074(4212)	Estimated powder life time	Monitor	_	0	30000	Hr
H1075(4213)	Control output voltage for powder	Monitor	_	260 or more	0.1	V
H1076(4214)	Control output current for powder	Monitor	_	400 or more	0.01	Α
H1077(4215)	_	_	_	_	_	_
H1078(4216)	_	_	_	_	_	_
H1079(4217)	_	_	_	_	_	_
H107A(4218)	_	_	_	_	_	_
H107B(4219)	_	_	_	_	_	_
H107C(4220)	_	_	_	_	_	_
H107D(4221)	_	_	_	_	_	_
H107E(4222)	_	_	_	_	_	_
H107F(4223)	Automatic control mode	Monitor	_	0	2	_
H1080(4224)	Tension setting	Setting	_	1	Tension full scale	N/×10 N
H1081(4225)	Manual setting	Setting	_	-1000	1000	%
H1082(4226)	Stall setting	Setting	_	0	1000	%
H1083(4227)	Start timer	Setting	_	0	300	sec
		_		0	-	
H1084(4228)	Stop timer	Setting	_		1000	sec
H1085(4229)	Stop gain	Setting	_	5	400	%
H1086(4230)	Stop bias	Setting	-	0	100	%
H1087(4231)	Acceleration/deceleration torque setting	Setting	LE7-DCA	0	1000	%
H1088(4232)	Gain 1	Setting	_	5	400	%
H1089(4233)	Gain 2	Setting	_	5	400	%
H108A(4234)	Internal taper ratio	Setting	_	0	80	%
H108B(4235)	External linear line taper ratio	Setting	_	0	100	%
H108C(4236)	New reel preset	Setting	_	0	1000	%
H108D(4237)	New reel preset timer	Setting	_	0	300	sec
H108E(4238)	Cutting torque	Setting	_	0	1000	%
H108F(4239)	_	_	_	_	_	_
H1090(4240)	Broken line taper corner 1	Setting	_	1	2000	mmφ
H1091(4241)	Broken line taper ratio 1	Setting	_	0	100	%
H1092(4242)	Broken line taper corner 2	Setting	_	1	2000	mmφ
H1093(4243)	Broken line taper ratio 2	Setting	_	0	100	%
H1094(4244)	Broken line taper corner 3	Setting	_	1	2000	mmφ

Holding register	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H1095(4245)	Broken line taper ratio 3	Setting	_	0	100	%
H1096(4246)	Broken line taper corner 4	Setting	_	1	2000	mmφ
H1097(4247)	Broken line taper ratio 4	Setting	_	0	100	%
H1098(4248)	Broken line taper corner 5	Setting	_	1	2000	mmφ
H1099(4249)	Broken line taper ratio 5	Setting	_	0	100	%
H109A(4250)	Broken line taper corner 6	Setting	_	1	2000	mmφ
H109B(4251)	Broken line taper ratio 6	Setting	_	0	100	%
H109C(4252)	Broken line taper corner 7	Setting	_	1	2000	mmφ
H109D(4253)	Broken line taper ratio 7	Setting	_	0	100	%
H109E (4254)	Broken line taper corner 8	Setting	_	1	2000	mmφ
H109F(4255)	Broken line taper ratio 8	Setting	_	0	100	%
H10A0(4256)	Proportional gain	Setting	_	0	100	%
H10A1(4257)	Integral time	Setting	_	0	100	%
H10A2(4258)	Dead band gain	Setting	_	0	100 - Proportional gain	%
H10A3(4259)	Dead band width	Setting	_	0	100	%
H10A4(4260)	Tension control filter	Setting	_	0	40	sec
H10A5(4261)	Static mechanical loss A	Setting	_	-1000	1000	%
H10A6(4262)	Static mechanical loss B	Setting	_	-1000	1000	%
H10A7(4263)	Kinetic mechanical loss A	Setting	LE7-DCA	-1000	1000	%
H10A8(4264)	Kinetic mechanical loss B	Setting	LE7-DCA	-1000	1000	%
H10A9(4265)	Mass correction gain A	Setting	LE7-DCA	0	100	%
H10AA(4266)	Mass correction gain B	Setting	LE7-DCA	0	100	%
H10AB(4267)	Mass correction bias A	Setting	LE7-DCA	0	100	%
H10AC(4268)	Mass correction bias B	Setting	LE7-DCA	0	100	%
H10AD(4269)	<u> </u>	_	_	_	_	_
H10AE(4270)	_	_	_	_	_	_
H10AF(4271)	_	_	_	_	_	_
H10B0(4272)	Control mode selection	Setting	LE7-DCA	0 (feedback control),	l 1 (open loop control)	_
H10B1(4273)	Integral feedback limit	Setting	_	0	101	%
H10B2(4274)	Feedback selection during the stop timer	Setting	_	0 (invalid), 1 (valid)	101	_
H10B2(4274)	Automatic control output polarity selection	Setting	_	0 (forward), 1 (reverse	۵)	_
H10B3(4276)	Open-loop control ratio	Setting	LE7-DCA	0	100	%
H10B5(4277)	Taper function selection	Setting		0 (no function), 1 (intelline taper (external)),	ernal taper), 2 (linear 3 (broken line taper	
				(external)), 4 (direct ta	aper)	
H10B6(4278)	Selection of two reel's switching FUNC	Setting	_	0 (invalid), 1 (valid)		_
H10B7(4279)	Internal taper standard selection	Setting	_	0 (zero standard), 1 (	stall standard)	_
H10B8(4280)	_	_	_	_	_	_
H10B9(4281)	Mechanical loss function selection	Setting	LE7-DCA	0 (fixed mechanical lo mechanical loss)	oss), 1 (high function	_
H10BA(4282)	Stall automatic calculation gain	Setting	LE7-DCA	0	100	%
H10BB(4283)	New reel preset AUTO calculation gain	Setting	LE7-DCA	0	100	%
H10BC(4284)	Control output upper limit	Setting	_	Control output lower limit	101	%
H10BD(4285)	Control output lower limit	Setting	_	-101	Control output upper limit	%
H10BE(4286)	_	_	_	_	_	_
H10BF(4287)	_	_	_	_	_	_
H10C0(4288)	Load model	Setting	_	0	200	_
H10C1(4289)	Rated current	Setting	_	0	400	Α
H10C2(4290)	Maximum torque correction	Setting	_	50	250	%
H10C3(4291)	Nonlinear correction 0	Setting	_	0	1000	%
H10C4(4292)	Nonlinear correction 10	Setting	_	0	1000	%

Holding	Name	Monitor/	Extension	Minimum value	Maximum value	Unit
register		settings	option			
H10C5(4293)	Nonlinear correction 20	Setting	_	0	1000	%
H10C6(4294)	Nonlinear correction 30	Setting	_	0	1000	%
H10C7(4295)	Nonlinear correction 40	Setting	_	0	1000	%
H10C8(4296)	Nonlinear correction 50	Setting	_	0	1000	%
H10C9(4297)	Nonlinear correction 60	Setting	_	0	1000	%
H10CA(4298)	Nonlinear correction 70	Setting	_	0	1000	%
H10CB(4299)	Nonlinear correction 80	Setting	_	0	1000	%
H10CC(4300)	Nonlinear correction 90	Setting	_	0	1000	%
H10CD(4301)	_	_	_	_	_	_
H10CE(4302)	_	_	_	_	_	_
H10CF(4303)	_	_	_	_	_	_
H10D0(4304)	Powder life prediction operation selection	Setting	_	0 (stop), 1 (execute)		_
H10D1(4305)	Weak excitation	Setting	_	0	1000	%
H10D2(4306)	Over current detection filter	Setting	_	0	20	sec
H10D3(4307)	Coil limit temperature	Setting	_	80	180	°C
H10D3(4307)	—		_	_	_	
H10D4(4300)	_	_	_			<del>                                     </del>
H10D6(4310)	_	_				<del> </del>
H10D0(4310)	_	_		_	_	<del> </del>
	_	_	_	_		<del> </del>
H10D8(4312)	_			_	_	<del> </del>
H10D9(4313)	_		_	_	_	<del> -</del>
H10DA(4314)	_	_	_	_	_	
H10DB(4315)	_	_	_	_	_	
H10DC(4316)		_	_	_	_	
H10DD(4317)		_	_	_	_	
H10DE(4318)	Selection of tension input	Setting	_	0	2	
H10DF(4319)	Selection of reel diameter input	Setting	_	0	2	
H10E0(4320)	Contact input monitor	Monitor	_	0	0xFFFF	-
H10E1(4321)	Contact output monitor	Monitor	_	0	0xFFFF	
H10E2(4322)	General-purpose analog input 1 monitor	Monitor	_	0	100	%
H10E3(4323)	General-purpose analog input 2 monitor	Monitor	_	0	100	%
H10E4(4324)	General-purpose analog input 3 monitor	Monitor	_	0	100	%
H10E5(4325)	General-purpose analog output 1 monitor	Monitor	_	0	100	%
H10E6(4326)	General-purpose analog output 2 monitor	Monitor	_	0	100	%
H10E7(4327)	Analog output monitor for TENS control	Monitor	_	0	100	%
H10E8(4328)	Analog output monitor for new reel preset	Monitor	_	0	100	%
H10E9(4329)	Contact input monitor for reel DIA CALC	Monitor	LE7-DCA	0	0xFFFF	_
H10EA(4330)	Contact output monitor for reel DIA CALC	Monitor	LE7-DCA	0	0xFFFF	-
H10EB(4331)	Alarm display	Monitor	_	0	63	_
H10EC(4332)	Network alarm device No.	Monitor	_	0	999	-
H10ED(4333)	Main unit ROM version	Monitor	_	0	999	-
H10EE(4334)	Network adapter ROM version	Monitor	LE7-CCL	0	999	_
H10EF(4335)	Communication signal monitor	Monitor	_	0	0xFFFF	-
H10F0(4336)	Contact input 1 function selection	Setting	_	0 (no function), 1 (run	• **	_
H10F1(4337)	Contact input 2 function selection	Setting	_	output OFF/ON), 3 (s (inching ON/OFF), 5	tall memory), 4 (constant tension ON/	
H10F2(4338)	Contact input 3 function selection	Setting	_	OFF), 6 (gain 1 ON/C	•	_
H10F3(4339)	Contact input 4 function selection	Setting	_		anual), 9 (reel change	_
H10F4(4340)	Contact input 5 function selection	Setting	_	ON/OFF), 10 (cut tord (alarm reset ONOFF/		_
H10F5(4341)	Contact input 6 function selection	Setting	_	(alaim 1030t ONOT 17		_
H10F6(4342)	_	_	_	_	_	_
	_					

H10F8(4344)		Monitor/ Extension option Minimum value				
, ,	Contact output 1 function selection	Setting	_	0 (no function), 1 (ten		_
H10F9(4345)	Contact output 2 function selection	Setting	_	detection), 2 (tension 3 (detection outside t (alarm occurrence de	ension range), 4	_
H10FA(4346)	_	_	_	_	_	_
H10FB(4347)	_	_	_	_	_	_
H10FC(4348)	_	_	_	_	_	_
H10FD(4349)	_	_	_	_	_	_
H10FE(4350)	_	_	_	_	_	_
H10FF(4351)	_	_	_	_	_	_
H1100(4352)	Analog input mode selection	Setting	_	0 (0 to 5 V mode), 1 (	0 to 10 V mode)	_
H1101(4353)	Analog input 1 function selection	Setting	_	0 (no function), 1 (ten	sion setting), 2 (stall	_
H1102(4354)	Analog input 2 function selection	Setting	_	setting), 3 (straight lir		_
H1103(4355)	Analog input 3 function selection	Setting	_	<ul> <li>4 (new axis preset se setting), 6 (tension in input)</li> </ul>		_
H1104(4356)	_	_	_	_	_	_
H1105(4357)	_	_	_	_	_	_
H1106(4358)	_	_	_	_	_	_
H1107(4359)	_	_	_	_	_	_
H1108(4360)	Analog output mode selection	Setting	_	0 (0 to 5 V mode), 1 (	0 to 10 V mode)	_
H1109(4361)	Analog output 1 function selection	Setting	_	0 (no function), 1 (ter	· · · · · · · · · · · · · · · · · · ·	_
H110A(4362)	Analog output 2 function selection	Setting	_	diameter monitor), 3 monitor), 4 (A-axis re speed output), 5 (B-a rotational speed outp		
H110B(4363)	Analog output 1 gain	Setting	_	500	3000	%
H110C(4364)	Analog output 2 gain	Setting	_	500	3000	%
H110D(4365)	Analog output 1 bias	Setting	_	-500	500	%
H110E(4366)	Analog output 2 bias	Setting	_	-500	500	%
H110F(4367)	_		_	_	_	_
H1110(4368)	Two reel's switching FUNC output mode	Setting	_	0 (no internal switchin switching)	ng), 1 (with internal	_
H1111(4369)	Control output mode selection	Setting	_		to 10 V mode), 4 (0 to V mode), 6 (0 to 2.7 V	_
H1112(4370)	Control output gain	Setting	_	500	3000	%
H1113(4371)	New reel preset output gain	Setting	_	500	3000	%
H1114(4372)	Control output bias	Setting	_	-500	500	%
H1115(4373)	New reel preset output bias	Setting	_	-500	500	%
H1116(4374)	_	_	_	_	_	_
H1117(4375)	_	_	_	_	_	_
H1118(4376)	_	_	_	_	_	_
H1119(4377)	_	_	_	_	_	_
H111A(4378)	_	_	_	_	_	_
H111B(4379)	_	_	_	_	_	_
H111C(4380)	_	_	_	_	_	_
H111D(4381)	_	_	_	_	_	_
H111E(4382)	_	_	_	_	_	_
	_	_	_	_	_	_
H111F(4383)	Set setting password	Setting	I —	1 ()		_
H111F(4383) H1120(4384)	Set setting password	Setting	_	0	32000	_
	Set setting password  Input setting password  Set monitor password	Setting Setting Setting	_	0 0	32000 32000 32000	_

Register	- - - -
H1126(4390)   Operation mode selection   Setting   —   1 (LE7-40GU), 2 (LE-40MT), 3 (LE-30CT)     H1127(4391)   Selection of function to use 1   Setting   —   O   OxFFFF     H1128(4392)   Selection of function to use 2   Setting   —   O (backup not provided), 1 (backup provided)     H1129(4393)   Memory cassette backup selection   Setting   —   O (No function) 1 (Copy to Menu 1), 2 (Copy to Menu 2) 3 (Copy to Menu 3) 4 (Copy to Menu 4), 5 (Copy to Menu 3) 4 (Copy to Menu 6), 7 (C	- - - -
H1127(4391)   Selection of function to use 1   Setting   —   0   OxFFFF     H1128(4392)   Selection of function to use 2   Setting   —   0   OxFFFF     H1129(4393)   Memory cassette backup selection   Setting   —   O (backup not provided), 1 (backup provided)   H112A(4394)   Data copy selection   Setting   —   O (No function) 1 (Copy to Menu 1), 2 (Copy to Menu 2) 3 (Copy to Menu 3) 4 (Copy to Menu 4), 5 (Copy to Menu 5), 6 (Copy to Menu 6), 7 (Copy to Menu 7), 8 (Copy to Menu 8), 9 (Read from memory cassette), 11 (Check with memory cassette)     H112B(4395)   Data initialization selection   Setting   —   O (no function), 1 (initialize all parameters     H112C(4396)   —   —   —   —     H112D(4397)   —   —   —   —     H112E(4398)   —   —   —   —     H112F(4399)   —   —   —   —     H112F(4399)   —   —   —   —     H113O(4400)   Alarm history 1   Monitor   —   0   63     H1131(4401)   Alarm history 2   Monitor   —   0   63	- - - -
H1128(4392)   Selection of function to use 2   Setting   —   0   0xFFFF     H1129(4393)   Memory cassette backup selection   Setting   —   0 (backup not provided), 1 (backup provided)   H112A(4394)   Data copy selection   Setting   —   0 (No function) 1 (Copy to Menu 1), 2 (Copy to Menu 2) 3 (Copy to Menu 3) 4 (Copy to Menu 4), 5 (Copy to Menu 5), 6 (Copy to Menu 6), 7 (Copy to Menu 7), 8 (Copy to Menu 8), 9 (Read from memory cassette), 11 (Check with memory cassette)   H112B(4395)   Data initialization selection   Setting   —   0 (no function), 1 (initialize all parameters   H112C(4396)   —   —   —   —   —   —   H112D(4397)   —   —   —   —   —   H112E(4398)   —   —   —   —   —   —   H112F(4399)   —   —   —   —   —   —   H113D(4400)   Alarm history 1   Monitor   —   0   63   H1131(4401)   Alarm history 2   Monitor   —   0   63	_
H1129(4393)   Memory cassette backup selection   Setting   —   0 (backup not provided), 1 (backup provided)	_
H112A(4394)   Data copy selection   Setting   —   O (No function) 1 (Copy to Menu 1), 2 (Copy to Menu 2) 3 (Copy to Menu 3) 4 (Copy to Menu 4), 5 (Copy to Menu 5), 6 (Copy to Menu 6), 7 (Copy to Menu 7), 8 (Copy to Menu 8), 9 (Read from memory cassette), 10 (write to memory cassette), 11 (Check with memory cassette)   H112B(4395)   Data initialization selection   Setting   —   O (no function), 1 (initialize all parameters   H112C(4396)   —   —   —   —   —   —   H112D(4397)   —   —   —   —   —   H112E(4398)   —   —   —   —   —   —   H112F(4399)   —   —   —   —   —   H1130(4400)   Alarm history 1   Monitor   —   O   63   H1131(4401)   Alarm history 2   Monitor   —   O   63	
Copy to Menu 2) 3 (Copy to Menu 3) 4 (Copy to Menu 4), 5 (Copy to Menu 5), 6 (Copy to Menu 6), 7 (Copy to menu 7), 8 (Copy to Menu 8), 9 (Read from memory cassette), 10 (write to memory cassette), 11 (Check with memory cassette)    H112B(4395)   Data initialization selection   Setting   —	
H112C(4396)       —       —       —       —         H112D(4397)       —       —       —       —         H112E(4398)       —       —       —       —         H112F(4399)       —       —       —       —         H1130(4400)       Alarm history 1       Monitor       —       0       63         H1131(4401)       Alarm history 2       Monitor       —       0       63	) — — —
H112D(4397)       —       —       —       —         H112E(4398)       —       —       —       —         H112F(4399)       —       —       —       —         H1130(4400)       Alarm history 1       Monitor       —       0       63         H1131(4401)       Alarm history 2       Monitor       —       0       63	
H112E(4398) — — — — — — — — — — — — — — — — — — —	_
H112F(4399) — — — — — — — — — — — — — — — — — —	1
H1130(4400)       Alarm history 1       Monitor       —       0       63         H1131(4401)       Alarm history 2       Monitor       —       0       63	_
H1131(4401) Alarm history 2 Monitor — 0 63	_
	_
H1132(4402) Alarm history 3 Monitor — 0 63	_
<u></u> , / main motor, 0	_
H1133(4403) Alarm history 4 Monitor — 0 63	_
H1134(4404) Alarm history 5 Monitor — 0 63	_
H1135(4405) Alarm history 6 Monitor — 0 63	_
H1136(4406) Alarm history 7 Monitor — 0 63	_
H1137(4407) Alarm history 8 Monitor — 0 63	_
H1138(4408) Alarm history holding selection Setting — 0 (no holding), 1 (holding)	_
H1139(4409) Alarm display time Setting — 0 301	sec
H113A(4410) Alarm operation selection 1 Setting — 0 0xFFFF	_
H113B(4411) Alarm operation selection 2 Setting — 0 0xFFFF	_
H113C(4412) Alarm operation selection 3 Setting — 0 0xFFFF	
H113D(4413) Alarm operation selection 4 Setting — 0 0xFFFF	
H113E(4414) — — — — —	
H113F(4415) — — — — —	_
H1140(4416) Network mode selection Setting — 0 (No function), 1 (N:N Network), 2 (MODBUS/RTU), 3 (MODBUS (ASCII)), 4 (CC-Link), 5 (CC-Link IEF)	-
H1141(4417)         Station No. in N:N Network         Setting         —         1         7	_
H1142(4418)         MODBUS station No.         Setting         —         1         247	_
H1143(4419) MODBUS format selection Setting — 0 0xFFFF	_
H1144(4420)         CC-Link station No.         Setting         LE7-CCL         1         64	_
H1145(4421) Number of occupied stations in CC-Link Setting LE7-CCL 0 (2 stations occupied), 1 (4 stations occupied)	_
H1146(4422) Communication speed in CC-Link Setting LE7-CCL 0 (156k), 1 (625k), 2 (2.5M), 3 (5M), 4 (10M)	_
H1147(4423) CC-Link version Setting — 0 (Ver.2.00), 1 (Ver.1.10)	_
H1148(4424) Extended cyclic in CC-Link Setting LE7-CCL 0 (1x), 1 (2x), 2 (4x)	_
H1149(4425) CC-Link IE network No. Setting LE7-CCL 1 239	_
H114A(4426)	_
H114B(4427) — — — — — —	_
H114C(4428) — — — — —	_
H114D(4429) — — — — — —	<del> </del> -
H114E(4430) — — — — —	_
	1

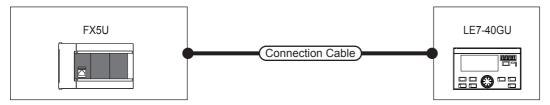
Holding register	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H1150(4432)	Continuous monitoring FUNC selection 1	Setting	_	0	999	_
H1151(4433)	Continuous monitoring FUNC selection 2	Setting	_	0	999	_
H1152(4434)	Continuous monitoring FUNC selection 3	Setting	_	0	999	_
H1153(4435)	Continuous monitoring FUNC selection 4	Setting	_	0	999	_
H1154(4436)	Continuous monitoring FUNC selection 5	Setting	_	0	999	_
H1155(4437)	Continuous monitoring FUNC selection 6	Setting	_	0	999	_
H1156(4438)	Continuous monitoring FUNC selection 7	Setting	_	0	999	_
H1157(4439)	Continuous monitoring FUNC selection 8	Setting	_	0	999	_
H1158(4440)	Continuous monitoring FUNC selection 9	Setting		0	999	_
H1159(4441)	Continuous monitoring FUNC selection 10	Setting		0	999	_
H115A(4442)	Continuous monitoring FUNC selection 11	Setting		0	999	_
H115B(4443)	Continuous monitoring FUNC selection 12	Setting		0	999	
H115C(4444)	Continuous monitoring FUNC selection 13	Setting		0	999	
	, , ,	-		0		
H115D(4445)	Continuous monitoring FUNC selection 14	Setting			999	
H115E(4446)	Continuous monitoring FUNC selection 15	Setting		0	999	_
H115F(4447)	Continuous monitoring FUNC selection 16	Setting		0	999	-
H1160(4448)	Continuous setting function selection 1	Setting		0	999	_
H1161(4449)	Continuous setting function selection 2	Setting		0	999	-
H1162(4450)	Continuous setting function selection 3	Setting		0	999	-
H1163(4451)	Continuous setting function selection 4	Setting		0	999	_
H1164(4452)	Continuous setting function selection 5	Setting		0	999	_
H1165(4453)	Continuous setting function selection 6	Setting		0	999	-
H1166(4454)	Continuous setting function selection 7	Setting		0	999	_
H1167(4455)	Continuous setting function selection 8	Setting		0	999	_
H1168(4456)	Continuous setting function selection 9	Setting		0	999	_
H1169(4457)	Continuous setting function selection 10	Setting		0	999	_
H116A(4458)	Continuous setting function selection 11	Setting		0	999	-
H116B(4459)	Continuous setting function selection 12	Setting		0	999	_
H116C(4460)	Continuous setting function selection 13	Setting		0	999	_
H116D(4461)	Continuous setting function selection 14	Setting		0	999	_
H116E(4462)	Continuous setting function selection 15	Setting		0	999	_
H116F(4463)	Continuous setting function selection 16	Setting		0	999	_
H1170(4464)	Extended screen 1	Setting		0	999	_
H1171(4465)	Extended screen 2	Setting		0	999	_
H1172 (4466)	Extended screen 3	Setting		0	999	_
H1173(4467)	Extended screen 4	Setting		0	999	_
H1174(4468)	Extended screen 5	Setting		0	999	_
H1175(4469)	Extended screen 6	Setting		0	999	_
H1176(4470)	Extended screen 7	Setting		0	999	_
H1177(4471)	Extended screen 8	Setting		0	999	<del> </del>
H1178(4472)	Power standby display	Setting		0 (displayed), 1 (not o	1	_
H1179(4473)	Ethernet communication	Setting		0 (No function), 1 (Co		_
		Setting		(SLMP)		
H117A(4474)	SLMP station No.	Setting		1	7	-
H117B(4475)	_	_	_	_	_	_
H117C(4476)	_	_	_	_	_	_
H117D(4477)	_	-	_	_	_	-
H117E(4478)	_	_	_	_	_	-
H117F(4479)	_	_	_	_	_	_
H1180(4480)	Base torque in open-loop control	Setting	LE7-DCA	0	1000	%
H1181(4481)	Direct taper rate	Setting	_	0	1000	%
H1182(4482)	Link tension monitor filter	Setting	_	0	80	sec

Holding register	Name	Monitor/ settings	Extension option	Minimum value	Maximum value	Unit
H1183(4483)	Tension input	Setting	_	0	2000	N/×10 N
H1184(4484)	Reel diameter input	Setting	_	0	2000	mmφ
H1185(4485)	_	_	_	_	_	_
H1186(4486)	_	_	_	_	_	_
H1187(4487)	_	_	_	_	_	_
H1188(4488)	_	_	_	_	_	_
H1189(4489)	_	_	_	_	_	_
H118A(4490)	_	_	_	_	_	_
H118B(4491)	_	_	_	_	_	_
H118C(4492)	_	_	_	_	_	_
H118D(4493)	_	_	_	_	_	_
H118E(4494)	_	_	_	_	_	_
H118F(4495)	_	_	_	_	_	_

# 7.4 Reference Program

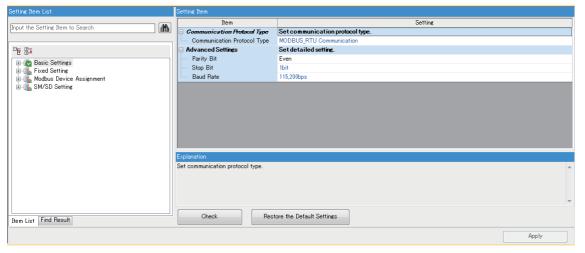
A basic example program (GX Works3) for MODBUS/RTU, ASCII(SLAVE) communication is described.

### System configuration



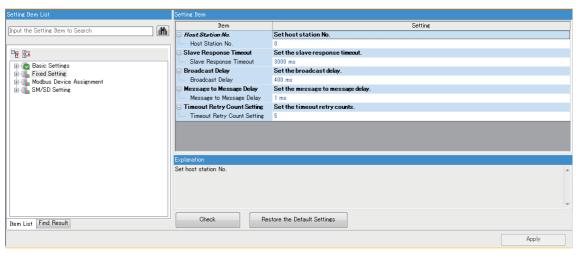
### **Settings**

### **■**Basic settings



Item	Setting
Communication protocol type	MODBUS_RTU Communication

### **■**Fixed setting

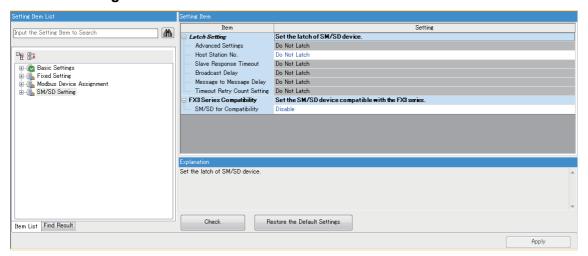


Item	Setting
Host station No.	0
Slave response timeout	3000 ms
Broadcast delay	400 ms
Message to message delay	1 ms
Timeout retry count setting	5

### **■**Modbus device assignment

Setting is unnecessary.

### **■SM/SD** setting



### Latch setting

Item	Setting
Host station No.	Do not latch
Total number of local station	Do not latch

### FX3 Series compatibility

Item	Setting
SM/SD for compatibility	Disable

### Program example

Write		1	2	3	4	5	6	7	8	9	10	11	12
		SM402 										K1	D1 MODBUS
1	(0) <sub>ON</sub>	l at rt									MOV		station No.
2												SET	M1 MODBUS protocol 1 execution
	S	M8800 H H											Y1
3	(8) <sub>MC</sub>	DBUS mmunica											MODBUS communicati
		° M8500 ⊢											Y2
4		rial mmunica n error											MODBUS communicati on error
5 F	Read coils	M1											
6		$+ \vdash$					ADPRW	D1 MODBUS station No.	H1 Function c (Read coil	H1000 ode H01 s)	K48	X100 Run/Stop	M10 MODBUS protocol 1 being executed
			M11										
7			Normal completion of MODBUS protocol 1									RST	M1 MODBUS protocol 1 execution
			protocori									_	M2
8												SET	MODBUS protocol 2 execution
9 [	Coil multiple w												
10		M2 -					ADPRW	D1 MODBUS station No.	H0F Function c (Write mul	H0 ode H0F tiple coils)	K48	Y100 Run/Stop	M13 MODBUS protocol 2 being executed
			M14										
11			Normal completion of MODBUS									RST	M2 MODBUS protocol 2 execution
			protocol 2										
12												SET	M3 MODBUS protocol 3 execution

Writ	e •	1	2	3	4	5	6	7	8	9	10	11	12
13	Continuous	monitor pro	ocessing										
14	(98)	$\vdash$										SET	M100 Monitor item 1 address setting
15	(138)	X0 	M100  Monitor Item 1 address setting								MOV	D100 Monitor item 1 address	D10 MODBUS protocol 3 first device
16			M101  Monitor item 2 address setting								MOV	D101 Monitor item 2 address	D10 MODBUS protocol 3 first device
17			M102  Monitor item 3 address setting								MOV	D102 Monitor item 3 address	D10 MODBUS protocol 3 first device
18			M103  Monitor item 4 address setting								MOV	D103 Monitor item 4 address	D10 MODBUS protocol 3 first device
19			MODBUS protocol 3 execution				ADPRW	D1 MODBUS station No.	code H03	D10 MODBUS protocol 3 first device	K1	D110Z0 Monitor item 1 setting value	M16 MODBUS protocol 3 being executed
20				M17  Normal completion of MODBUS protocol 3								RST	M100Z0 Monitor item 1 address setting
21												INC	ZO
22												SET	M100Z0 Monitor item 1 address setting

Write	*	1	2	3	4	5	6	7	8	9	10	11	12
23	(195)	=	No. of setti (4 items in	Z0 ng items sample)							MOV	КО	ZO
24												SET	M100 Monitor item 1 address setting
25	(207)	XO Monitoring start	M3  MODBUS protocol 3 execution	M17  Normal completion of MODBUS protocol 3								RST	M3 MODBUS protocol 3 execution
26		X0 Monitoring start										SET	M4 MODBUS protocol 4 execution
27 C	ontinuous	settings pro	ocessing										
28	(219)	SM402  ON at start									MOV	K128	D200 Setting item first device
29											MOV	КЗ	D201 No. of setting item write devices
30	(266)	X1 X1 Setting Start	M4  MODBUS protocol 4 execution				ADPRW	D1 MODBUS station No.		device	D201 No. of setting item write devices	D210 MODBUS protocol 4 communica ting	M19 MODBUS protocol 4 beins executed
31	(283)	X1 X1 Setting Start	M4  MODBUS protocol 4 execution	M20 Normal completion of MODBUS protocol 4								RST	M4 MODBUS protocol 4 execution
32		X1 ————————————————————————————————————		proceed 4								SET	M1 MODBUS protocol 1 execution

Write	e • 1 2 Feedback control sequence process	3 4	5	6	7	8	9	10	11	12
34	(295) Stall start								SET	Y103 Auto/Manual
35	X3  Start the controller.								SET	Y100 Run/Stop
36	Start the controller.								RST	Y100 Run/Stop
37	(349) Stall start								RST	Y100 Run/Stop
38									RST	Y103 Auto/Manual
37	(349) Stall start								RST	Y100 Run/Stop
38									RST	Y103 Auto/Manual
39	Status monitoring processing X100									Y10
40	(355) <sub>Run/Stop</sub>									Running lamp
41	X110 (393) Manual									Y11 O Manual
42	Control									Y12
72	(397) Automatic control  X112									Automatic control lamp Y13
43	(401) Auto lamp flicker in operation/ stopped									Auto lamp flicker in operation lamp
44	(405)									[END ]

### Using method of ladder

- Monitored items: By storing the device number of items to be monitored to D100 to D103, and setting X0=ON, the monitored values are stored in D110 to D113.
- Setting items: By inputting the first device of setting items to D200, inputting the number of written devices to D201, set X1=ON, and the setting values stored in D210 or later are stored.
- Feedback control: By turning ON/OFF X2 and X3, the control status is changed.?

List of used devices (The allocation is an example.)

Device name	Classification*1	Allocation function	Use
D100 to D104	Setting	Monitored item 1 to 4	Device set for individual access to each station No.
D200	Setting	Request command + request code/data setting 1 to 2	Device set to use the request command
X100 to 157	Monitoring	Input signal	Store ON/OFF status of input signal.
Y100 to 157	Setting	Output signal	Store ON/OFF status of output signal.
D1	Setting	MODBUS station No.	Device to specify the station No. (station No.=1 at all times in a sample)
D100 to D103	Setting	Address of monitored item 1 to 4	Set the device No. to be monitored.
D110 to D113	Setting	Set value of monitored value 1 to 4	Set value which is monitored in monitored item 1 to 4 is stored.
D200	Setting	Setting items first device	Set the first device of items to be set. (D128: tension setting in a sample)
D201	Setting	The number of setting items written devices	Set the number of items to be set. (the three items, D128 to D130 in a sample)
to D210	Setting	Setting items set value	Store the set value to be set. (The three devices, D210 to D212 are used in a sample.)
D120 to D123	Monitoring	Continuous monitor 1 to 4	Continuous monitor execution result is stored.
D130 to D131	Setting	Continuous setting 1 to 2	Setting value of continuous setting is stored.
X0	Setting	Start request command access execution	Execute request command.
X1	Setting	Start continuous monitor execution	Start to execute continuous monitor.
X2	Setting	Start continuous setting execution	Start to execute continuous setting.
X3	Setting	Start stall execution	Start to execute stall.
Y1	Monitoring	In MODBUS communication	Turn ON during the execution of MODBUS communication
Y2	Monitoring	MODBUS communication error	Turn ON during the MODBUS communication error.
Y10	Monitoring	Run	Run: ON/Stop: OFF
Y11	Monitoring	Manual control	Manual control ON
Y12	Monitoring	Automatic control	Automatic control ON
Y13	Monitoring	Auto lamp flicker in operation	Auto lamp flicker in operation ON
M1 to 4	System	ADPRW execution flag	Execute adapter instructions successively.
M10 to 22	System	ADPRW execution status flag	Store the execution result of adapter instructions.
M100 to M103	System	Address setting of monitored item 1 to 4	Set monitored item 1 to 4 successively.

<sup>\*1</sup> Classification

Setting: items to be set/input when using functions Monitoring: items to monitor output when using functions

# **REVISIONS**

Revision date	Revision	Description
July 2018	A	First edition

This manual confers no industrial property rights or any rights of any other kind, nor does it confer any patent licenses. Mitsubishi Electric Corporation cannot be held responsible for any problems involving industrial property rights which may occur as a result of using the contents noted in this manual.

© 2018 MITSUBISHI ELECTRIC CORPORATION

## **TRADEMARKS**

CRIMPFOX is a tradmark of Phoenix Contact GmbH & Co. KG.

Ethernet is a trademark of Xerox Corporation.

MODBUS® is a registered trademark of Schneider Electric SA.

Microsoft<sup>®</sup> and Windows<sup>®</sup> are either registered trademarks or trademarks of Microsoft Corporation in the United States and/or other countries.

The company name and the product name to be described in this manual are the registered trademarks or trademarks of each company.

Manual number: SH(NA)-081834ENG-A	
When exported from Japan, this manual does not require application to the Ministry of Economy, Trade and Industry for service transaction permission.	
MITSUBISHI ELECTRIC  HEAD OFFICE: TOKYO BUILDING, 2-7-3 MARUNOUCHI,	